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# Marshall J. Leitman, Epifanio G. Virga <br> On uniqueness for bounded channel flows of viscoelastic fluids 

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Meccanica dei fluidi. - On uniqueness for bounded channel flows of viscoelastic fluids. Nota di Marshall J. Leitman e Epifanio G. Virga, presentata (*) dal Corrispondente T. Manacorda

Abstract. - It was conjectured in [1] that there is at most one bounded channel flow for a viscoelastic fluid whose stress relaxation function $G$ is positive, integrable, and strictly convex. In this paper we prove the uniqueness of bounded channel flows, assuming $G$ to be non-negative, integrable, and convex, but different from a very specific piecewise linear function. Furthermore, whenever these hypotheses apply, the unbounded channel flows, if any, must grow in time faster than any polynomial.

KEY words: Uniqueness; Channel flows; Viscoelasticy fluids.

Rlassunto. - Sull'unicità di soluzione per l'equazione del moto in un canale di un fluido viscoelastico. In [1] è stata avanzata la congettura che l'equazione che descrive il moto in un canale di un fluido viscoelastico la cui funzione di rilassamento degli sforzi $G$ sia positiva, integrabile e strettamente convessa può avere al più una soluzione limitata. In questo lavoro l'unicità di soluzione è dimostrata assumendo che $G$ sia non negativa, integrabile e convessa, ma diversa da una specialissima funzione lineare a tratti. Inoltre, quando ricorrono queste ipotesi, le eventuali soluzioni illimitate dell'equazione di moto devono divergere nel tempo più rapidamente di qualsiasi polinomio.

In [1] we considered the smooth bounded channel flows of a viscoelastic fluid. We sought solutions to the homogeneous equation of motion

$$
\begin{equation*}
\rho u_{t}(x, t)-\int_{0}^{\infty} G(s) u_{x x}(x, t-s) \mathrm{d} s=0 \tag{1}
\end{equation*}
$$

subject to the boundary conditions

$$
\begin{equation*}
u(0, t)=u(\mathrm{~L}, t)=0 \quad \forall t \in R, \tag{2}
\end{equation*}
$$

in the class of functions $\left({ }^{1}\right)$

$$
U:=\left\{u \in C^{2}(\Sigma)\left|0 \leqq \sup _{\Sigma}\right| u \mid<\infty\right\}
$$

where $\Sigma$ is the strip

$$
\Sigma:=\{(x, t): x \in[0, \mathrm{~L}], t \in R\} .
$$

We denote by $u$ the component of the velocity field along the axis of the channel. L is the width of the channel, $\rho$ is a positive constant representing the mass density of the fluid per unit volume, and $G:(0, \infty) \rightarrow R$ is the stress relaxation function.

In [1] we conjectured that whenever the function $G$ is positive, decreasing, integrable, and strictly convex, equations (1) and (2) bave no solution in $U$ except $u \equiv 0$. Now we are able to prove more than that.
(*) Nella seduta del 22 giugno 1988.
$\left.{ }^{( }{ }^{1}\right)$ The smoothness condition on $x \mapsto u(x, t)$ can be relaxed without difficulty; it is not central to our argument.

Theorem. If $G$ is (i) non-negative, (ii) integrable, and (iii) convex, then $u \equiv 0$ is the only solution of (1) and (2) in $U$ unless $G$ is linear on each interval $\left(k T_{N},(k+1) T_{N}\right), k=$ $=0,1,2, \ldots$, where

$$
\begin{equation*}
T_{N}:=\frac{2 \mathrm{~L}}{N} \sqrt{\frac{\rho}{G(0)}} \tag{3}
\end{equation*}
$$

and $N$ is a positive integer.
As a consequence, we shall show that when $G$ is the piecewise linear function described in the Theorem, (1) and (2) admit standing wave solutions of the form:

$$
u(x, t)=\frac{1}{2 i}\left[f\left(x+\sqrt{\frac{G(0)}{\rho}} t\right)-f\left(-x+\sqrt{\frac{G(0)}{\rho}} t\right)\right]
$$

where $f$ is any suitably smooth complex-valued $\left(\frac{2 \mathrm{~L}}{N}\right)$-periodic function.
Remark 1. The hypotheses (i)-(iii) imply that $G$ is absolutely continuous on each closed sub-interval of $(0, \infty)$, and its derivative $\dot{G}$ is non-positive (almost everywhere). Of course $\lim _{t \rightarrow \infty} G(t)=0$. Although redundant, the hypothesis that $G$ be non-increasing is physically meaningful, and so it is frequently added to the list (i)-(iii).

Remark 2. The Theorem asserts that, under hypotheses (i)-(iii), the solution to the non-homogeneous equation of motion for a viscoelastic fluid is unique within the class of smooth bounded flows, unless $G$ is very special. Uniqueness theorems in viscoelasticity have also been proved within classes of functions vanishing asymptotically in the past (see e.g.[2] and [3]).

Remark 3. If $G(t)$ or $\dot{G}(t)$, or both, become unbounded as $t$ approaches zero, then $G$ certainly cannot have the special piecewise linear form and, hence, the uniqueness referred to in Remark 2 obtains. Joseph, Renardy and Saut [4] have considered viscoelastic fluid responses of this type.

Remark 4. As mentioned in [1] (Remark 4), if $G$ has finite support some of the results presented here can also be obtained by methods of Hale [5].

The proof of the Theorem relies on the following Lemma.
Lemma. For every function $g:(0, \infty) \rightarrow R$ that satisfies bypotheses (i)-(iii) of the Theorem, let $\hat{g}: R \rightarrow C$ be defined by

$$
\begin{equation*}
\hat{g}(\lambda):=\int_{0}^{\infty} e^{-2 \pi i \lambda t} g(t) \mathrm{d} t \tag{4}
\end{equation*}
$$

Then the function

$$
\begin{equation*}
\varphi(\lambda):=2 \pi \mathrm{i} \lambda+\hat{g}(\lambda), \quad \lambda \in R, \tag{5}
\end{equation*}
$$

bas zeros if and only if $g$ is piecewise linear with nodes equally spaced at intervals of $t_{0}:=$ $=2 \pi / \sqrt{g(0)}$. In this case $\varphi(\lambda)$ bas precisely two simple zeros: $\lambda= \pm 1 / t_{0}$.

Proof. First observe that the complex equation $\varphi(\lambda)=0$ is equivalent to the two real equations:

$$
\begin{align*}
& \int_{0}^{\infty} \cos (2 \pi \lambda t) g(t) \mathrm{d} t=0,  \tag{6}\\
& \int_{0}^{\infty} \sin (2 \pi \lambda t) g(t) \mathrm{d} t=2 \pi \lambda .
\end{align*}
$$

By (i) $\lambda=0$ is not a solution of (6). Moreover, if $\lambda_{0} \neq 0$ is a solution of (6) and (7), so is $-\lambda_{0}$. Let $\lambda>0$. Since (iii) ensures that $g$ is absolutely continuous on each closed subinterval of $(0, \infty)$ (see Remark 1 ), we can integrate by parts in the left-hand side of (6), and get

$$
\begin{equation*}
\int_{0}^{\infty} \sin (2 \pi \lambda t)[-\dot{g}(t)] \mathrm{d} t=0 \tag{8}
\end{equation*}
$$

To see this, we must verify the formula (see Remark 3)

$$
\begin{equation*}
\int_{0}^{\infty} \cos (2 \pi \lambda t) g(t) \mathrm{d} t=\int_{0}^{\infty} \frac{\sin (2 \pi \lambda t)}{2 \pi \lambda}[-\dot{g}(t)] \mathrm{d} t . \tag{9}
\end{equation*}
$$

First observe that, for $0<\alpha<1 / 2 \lambda<\beta<\infty$,

$$
\begin{aligned}
\int_{\alpha}^{\beta} \cos (2 \pi \lambda t) g(t) \mathrm{d} t=-\int_{\alpha}^{1 / 2 \lambda} \frac{\sin (2 \pi \lambda t)}{2 \pi \lambda} \dot{g}(t) \mathrm{d} t-\int_{1 / 2 \lambda}^{\beta} & \frac{\sin (2 \pi \lambda t)}{2 \pi \lambda} \dot{g}(t) \mathrm{d} t- \\
& -\frac{\sin (2 \pi \lambda \alpha)}{2 \pi \lambda \alpha} \alpha g(\alpha)+\frac{\sin (2 \pi \lambda \beta)}{2 \pi \lambda} g(\beta)
\end{aligned}
$$

By virtue of (i)-(iii) and Remark 1, we can let $\beta \rightarrow \infty$ in the latter formula, noting that the last term vanishes in the limit. The integral on the left-hand side exists as $\alpha \rightarrow 0$. Hence,

$$
\lim _{\alpha \rightarrow 0}\left[\int_{\alpha}^{1 / 2 \lambda} \frac{\sin (2 \pi \lambda t)}{2 \pi \lambda}[-\dot{g}(t)] \mathrm{d} t-\frac{\sin (2 \pi \lambda \alpha)}{2 \pi \lambda \alpha} \alpha g(\alpha)\right]
$$

exists too. Now the limit of the integral is either non-negative or infinite, since the integrand is non-negative. If it is infinite, so is $\lim _{\alpha \rightarrow 0} \alpha g(\alpha)$, which violates (ii). Thus both terms remain finite as $\alpha \rightarrow 0$. In fact $\lim _{\alpha \rightarrow 0} \alpha g(\alpha)=0$, or else (ii) is again violated. Formula (9) is thus verified ${ }^{2}$ ).

Since $g$ satisfies (ii) and (iii), the function $t \mapsto-\dot{g}(t)$ is non-negative and non-increasing (almost everywhere). Thus $\lambda>0$ solves (8) only if $\dot{g}$ is constant (almost every-
$\left.{ }^{(2}\right)$ Formula (9) remains valid if $g$ is merely assumed to be non-negative, non-increasing, and integrable. In this case $-\dot{g}(t) \mathrm{d} t$ must be replaced by $\mathrm{d} \mu(t)$, where $\mu$ denotes the (non-negative) Borel measure induced by the function $-g$. The proof is the same.
where) on each interval

$$
\left(\frac{k}{\lambda}, \frac{k+1}{\lambda}\right), \quad k=0,1,2, \ldots
$$

Since $g$ is absolutely continuous, it must have the form

$$
g\left(\frac{k+s}{\lambda}\right)=\left(\gamma_{k+1}-\gamma_{k}\right) s+\gamma_{k}, \quad 0 \leqq s \leqq 1, \quad k=0,1,2, \ldots,
$$

where $\left\{\gamma_{k}\right\}_{k=0}^{\infty}$ is some non-negative, non-increasing, summable sequence. Substituting this $g$ into (7) yields $(2 \pi \lambda)^{2}=g(0)$. Thus the zeros of (5) are

$$
\lambda= \pm \frac{\sqrt{g(0)}}{2 \pi}
$$

Finally, these roots are simple if and only if

$$
\lim _{\varepsilon \rightarrow 0} \frac{1}{\varepsilon} \varphi\left(\frac{\sqrt{g(0)}}{2 \pi}+\varepsilon\right) \neq 0
$$

A straightforward but tedious calculation shows that this limit is equal to $6 \pi \mathrm{i}$.
Proof of the Theorem. We extend $u$ oddly in $x$ to the interval [ $-\mathrm{L}, \mathrm{L}$ ] and compute its Fourier series in $x$ :

$$
u(x, t)=\sum_{n=1}^{\infty} v_{n}(t) \sin \left(\frac{n \pi x}{\mathrm{~L}}\right),
$$

where

$$
v_{n}(t):=\frac{2}{\mathrm{~L}} \int_{0}^{\mathrm{L}} u(x, t) \sin \left(\frac{n \pi x}{\mathrm{~L}}\right) \mathrm{d} x, \quad n=1,2, \ldots .
$$

If $u \in U$ solves (1) and (2), then each function $v_{n}$ is bounded, of class $C^{1}(R)$, and solves the equation

$$
\begin{equation*}
\dot{v}_{n}(t)+\int_{0}^{\infty} g_{n}(s) v_{n}(t-s) \mathrm{d} s=0 \tag{10}
\end{equation*}
$$

where

$$
g_{n}(s):=\frac{1}{\mathrm{~L}}\left(\frac{n \pi}{\rho}\right)^{2} G(s) .
$$

For a given $n$, we now seek solutions of (10) within the class of tempered distributions on $R\left({ }^{3}\right)$. If $b: R \rightarrow C$ is any integrable function we denote by $\hat{b}: R \rightarrow C$ its Fourier transform

$$
\hat{h}(\lambda):=\int_{-\infty}^{+\infty} \mathrm{e}^{-2 \pi i \lambda t} h(t) \mathrm{d} t .
$$

If we extend $G$ to $(-\infty, 0)$ by setting $G(t)=0$ for every $t<0$, then $\hat{g}_{n}$ is defined as in
${ }^{(3)}$ ) Bounded solutions of (10), if any, must be in $C^{\infty}(\boldsymbol{R})$. Indeed, if $v_{n}$ is an everywhere differentiable function which solves (10) pointwise, a theorem of Leitman and Mizel (see [6], Sect. 4) shows that $\dot{v}_{n}$ is locally absolutely continuous. An induction argument completes the proof.
(4). Let $\hat{v}_{n}$ denote the Fourier transform of $v_{n}$ regarded as a tempered distribution. Then (10) is equivalent to

$$
\begin{equation*}
\varphi_{n} \hat{v}_{n}=0 \tag{11}
\end{equation*}
$$

where $\varphi_{n}$ is a function defined as in (5). The solutions of (11), if any, must have support on the set $\left\{\lambda \in R: \varphi_{n}(\lambda)=0\right\}$. Since $g_{n}$ satisfies hypotheses (i)-(iii), the Lemma applies, and so $\hat{v}_{n}=0$ is the only solution of (11), and $v_{n}=0$ the only solution of (10), unless $g_{n}$ is piecewise linear with nodes equally spaced at intervals of

$$
T_{n}=\frac{2 \mathrm{~L}}{n} \sqrt{\frac{\rho}{G(0)}}
$$

If this is the case, then the solutions of (10) within the class of tempered distributions are spanned by the bounded periodic functions $\left({ }^{4}\right)$

$$
\begin{equation*}
t \mapsto e^{ \pm 2 \pi i t / T_{n}} . \tag{12}
\end{equation*}
$$

If $G$ is linear on each interval $\left(k T_{N},(k+1) T_{N}\right), k=0,1,2, \ldots$, for some positive integer $N$, then every $g_{m N}, m=1,2, \ldots$, is also linear on each interval

$$
\left(k \frac{T_{N}}{m},(k+1) \frac{T_{N}}{m}\right)
$$

and so can be regarded as a piecewise linear function with nodes equally spaced at intervals of $T_{m \mathrm{~N}}$. Thus $v_{m \mathrm{~N}}, m=1,2, \ldots$, are the only non-zero Fourier coefficients of $u$; they are periodic functions of the form (12) with $T_{n}$ replaced by $T_{m \mathrm{~N}}$.

If $G$ is not the piecewise linear function above, and satisfies (i)-(iii), then $u \equiv 0$ is the only solution of (1) and (2) in $U$, since every $v_{n}$ vanishes.

Remark 5. The argument employed to prove the Theorem also shows that whenever $G$ satisfies (i)-(iii) any unbounded solution to (1) and (2) must grow faster than any polynomial as $|t| \rightarrow \infty$.

There are some consequences of the Theorem worth mentioning. Suppose that $G$ satisfies (i)-(iii) and is strictly convex in a neighbourhood of some point. Then it cannot be piecewise linear, and the Theorem guarantees that the solutions of (1) and (2), if any, must be unbounded.

Now $f_{i x}$ a positive integer $N$ and write $G_{N}$ for that piecewise linear interpolation of $G$ with nodes equally spaced at intervals of $T_{N}$ (the same as in (3)). Then the functions

$$
u_{N}^{ \pm}(x, t)=e^{ \pm 2 \pi i t / T_{N}} \sin \left(\frac{N \pi x}{\mathrm{~L}}\right),
$$

solve (1) and (2) with $G$ replaced by $G_{N}$. On the other hand, this $G_{N}$ can also be regarded as a piecewise linear function with nodes equally spaced at $T_{N} / m$, for any posi-
tive integer $m$. Since $T_{N} / m=T_{m N}$, it follows that the functions
$u_{m \mathrm{~N}}^{ \pm}(x, t)=e^{ \pm 2 \pi i m t / T_{N}} \sin \left(\frac{m N \pi x}{\mathrm{~L}}\right)=$
$=\frac{1}{2 i}\left[\exp \left(\frac{i m N \pi}{L}\left(x \pm \sqrt{\frac{G(0)}{\rho}} t\right)\right)-\exp \left(\frac{i m N \pi}{L}\left(-x \pm \sqrt{\frac{G(0)}{\rho}} t\right)\right)\right]$,
also solve (1) and (2) with $G$ replaced by $G_{N}$. Furthermore, if $f: R \rightarrow C$ is any function with a sufficiently smooth Fourier series of the form:

$$
f(x)=\sum_{m=-\infty}^{\infty} c_{m} e^{i m N \pi x / L}
$$

then

$$
u_{f}(x, t)=\frac{1}{2 i}\left[f\left(x+\sqrt{\frac{G(0)}{\rho}} t\right)-f\left(-x+\sqrt{\frac{G(0)}{\rho}} t\right)\right]
$$

is again a bounded solution of (1) and (2) when $G$ is replaced by $G_{N}$.
Recall that $N$ was any fixed positive integer. By choosing $N$ large enough, and hence $T_{N}$ small enough, we can approximate $G$ by $G_{N}$ uniformly to any desired degree of accuracy. This means that if equations (1) and (2) do not admit globally bounded solutions for a given $G$, there are uniformly close approximations to $G$ for which they do. We had already encountered in [1] a $G$ for which this phenomenon occurs.

Remark 6. The hypothesis that $G$ be convex plays a crucial role in the proof of the Theorem. It is easy to show by example that if $G$ is non-negative and integrable, but fails to be convex, then the Theorem is not true. Let

$$
\begin{equation*}
G(t)=\gamma t e^{-\alpha t} \text { for } \mathrm{t} \geqq 0 \text {, } \tag{13}
\end{equation*}
$$

with $\gamma$ and $\alpha$ positive constants. Then (1) and (2) have solutions of the form

$$
u(x, t)=u_{0} \sin \left(\frac{p \pi x}{\mathrm{~L}}\right)
$$

if

$$
p=\sqrt{\frac{2 \mathrm{~L}^{2} \alpha^{3} \rho}{\gamma \pi^{2}}}
$$

is an integer.
The $G$ in (13), while surely non-convex, also fails to be non-increasing. To see that it is just convexity which is at issue here, we can easily find a $G$ which is non-negative, non-increasing, integrable but non convex, for which the situation is similar.

For example, let $G$ have constant value on the interval $[0, \beta]$ and be zero on $(\beta, \infty)$. Then bounded solutions of (1) and (2) can be constructed as before, if and only if,

$$
\frac{\beta}{\pi} \sqrt{2 \alpha}
$$

is an odd integer.

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