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**Integral representation and relaxation for functionals  
defined on measures**

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**Analisi matematica.** — *Integral representation and relaxation for functionals defined on measures.* Nota (\*) di ENNIO DE GIORGI, LUIGI AMBROSIO e GIUSEPPE BUTTAZZO, presentata dal Corrisp. E. DE GIORGI.

ABSTRACT. — Given a separable metric locally compact space  $\Omega$ , and a positive finite non-atomic measure  $\lambda$  on  $\Omega$ , we study the integral representation on the space of measures with bounded variation  $\Omega$  of the lower semicontinuous envelope of the functional

$$F(u) = \int_{\Omega} f(x, u) d\lambda \quad u \in L^1(\Omega, \lambda, \mathbf{R}^n)$$

with respect to the weak convergence of measures.

KEY WORDS: Relaxation; Integral representation; Measures.

RIASSUNTO. — *Rappresentazione integrale e rilassamento per funzionali definiti sulle misure.* Dato uno spazio metrico localmente compatto a base numerabile  $\Omega$  ed una misura  $\lambda$  su tale spazio, positiva, finita e non atomica, si studia la rappresentazione integrale del funzionale ottenuto rilassando

$$F(u) = \int_{\Omega} f(x, u) d\lambda \quad u \in L^1(\Omega, \lambda; \mathbf{R}^n)$$

nello spazio  $\mathbf{M}_n(\Omega)$  delle misure a variazione limitata su  $\Omega$ , rispetto alla topologia della convergenza debole di misure.

## 1. INTRODUCTION

In many problems of Calculus of Variations, given a functional  $F$  defined on a topological space  $(X, \tau)$ , it is useful to introduce the so-called (sequentially)  $\tau$ -relaxed functional  $\bar{F}$  defined by

$$\bar{F}(x) = \sup \{G(x) : G \text{ is sequentially } \tau\text{-l.s.c.}, G \leq F\}.$$

where  $G : X \rightarrow \bar{\mathbf{R}}$  is said sequentially  $\tau$ -l.s.c. if and only if

$$G(x_{\infty}) \leq \liminf_{h \rightarrow +\infty} G(x_h)$$

for every sequence  $(x_h) \subset X$  converging to  $x_{\infty} \in X$  in the topology  $\tau$ .

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When  $F$  is an integral functional, it is interesting to find an integral representation for the relaxed functional  $\bar{F}$ . General results of this type have been obtained in the literature either when  $\Omega$  is a bounded open subset of  $\mathbf{R}^k$ ,  $X$  is a Sobolev space  $W^{1,p}(\Omega; \mathbf{R}^n)$ ,  $\tau$  is the weak  $W^{1,p}(\Omega; \mathbf{R}^n)$  topology (or the strong  $L^p(\Omega; \mathbf{R}^n)$  topology) and

$$F(u) = \int_{\Omega} f(x, u, D u) dx$$

(see for instance [1], [4], [9]), or when  $X$  is a space  $L^p(\Omega, \lambda; \mathbf{R}^n)$ ,  $\tau$  is the weak  $L^p(\Omega, \lambda; \mathbf{R}^n)$  topology (or the strong  $L^p(\Omega, \lambda; \mathbf{R}^n)$  topology) and

$$F(u) = \int_{\Omega} f(x, u) d\lambda(x)$$

where  $\lambda$  is a given measure on a separable locally compact metric space  $\Omega$  (see for instance [3], [5], [7]).

In this paper we study the  $\tau$ -relaxation of functionals of the type (see Theorem 2.4)

$$F(\mu) = \begin{cases} \int_{\Omega}^* f(x, u) d\lambda(x) & \text{if } \mu = u \cdot \lambda \text{ with } u \in L^1(\Omega, \lambda; \mathbf{R}^n) \\ +\infty & \text{otherwise} \end{cases}$$

where  $\mu$  belongs to the space  $\mathbf{M}_n$  of the vector valued measures on  $\Omega$  with bounded variation,  $\tau$  is the weak topology of measures,  $f: \Omega \times \mathbf{R}^n \rightarrow [0, +\infty]$  is a function (not necessarily measurable), and  $\int^*$  denotes the upper integral. Similar results, under measurability hypotheses on  $f$ , have been obtained with different proofs in [2], [11], [14]. The proof of Theorem 2.4, which guarantees an integral representation for the relaxed functional, is based on an approach rather different from the one followed in [2], [11], [14], and relies on an abstract integral representation theorem for functionals  $F(\mu, B)$ , depending on measures  $\mu \in \mathbf{M}_n$  and Borel sets  $B \in \mathbf{B}(\Omega)$  (see Theorem 2.3).

The integral representation theorem given in this paper is the natural generalization of the theorem given in [3] concerning functionals  $F(u, B)$ , depending on  $u \in L^1(\Omega, \lambda; \mathbf{R}^n)$  and  $B \in \mathbf{B}(\Omega)$ . Finally, in the last section of the paper we show some examples for which it is possible to compute explicitly the relaxed functional.

## 2. STATEMENT OF THE RESULTS.

In this section  $(\Omega, \mathbf{B}, \lambda)$  will denote a measure space, where  $\Omega$  is a separable metric locally compact space,  $\mathbf{B}$  is the  $\sigma$ -algebra of the Borel subsets of  $\Omega$ , and  $\lambda: \mathbf{B} \rightarrow [0, +\infty[$  is a positive, non-atomic, finite measure.

For every vector measure  $\mu : \mathbf{B} \rightarrow \mathbf{R}^n$  and every  $B \in \mathbf{B}$  the variation of  $\mu$  on  $B$  is defined by

$$|\mu|(B) = \sup \left\{ \sum_{h=1}^{\infty} |\mu(B_h)| : B_h \in \mathbf{B}, \bigcup_{h=1}^{\infty} B_h \subset B, B_h \text{ pairwise disjoint} \right\},$$

We consider the following spaces:

$\mathbf{M}_n$  the space of all vector measures  $\mu : \mathbf{B} \rightarrow \mathbf{R}^n$  with finite variation on  $\Omega$ ;

$L_n^p$  the space of all  $\lambda$ -measurable functions  $u : \Omega \rightarrow \mathbf{R}^n$  with  $\int_{\Omega} |u|^p d\lambda < +\infty$ ;

$C_n^0$  the space of all continuous functions  $u : \Omega \rightarrow \mathbf{R}^n$  "vanishing on the boundary", that is for every  $\varepsilon > 0$  there exists a compact subset  $K_\varepsilon$  of  $\Omega$  such that  $|u(x)| < \varepsilon$  for all  $x \in \Omega - K_\varepsilon$ .

The space  $\mathbf{M}_n$  can be identified with the dual space of  $C_n^0$  by the duality (see [13], page 40)

$$\langle \mu, u \rangle_{\Omega} = \sum_{i=1}^n \int_{\Omega} u^i d\mu_i \quad (u \in C_n^0, \mu \in \mathbf{M}_n),$$

so that a sequence  $(\mu_h)$  in  $\mathbf{M}_n$  is weak\*-convergent to  $\mu \in \mathbf{M}_n$  if and only if

$$\langle \mu_h, u \rangle_{\Omega} \rightarrow \langle \mu, u \rangle_{\Omega} \quad \text{for every } u \in C_n^0.$$

In the following, given  $u \in L_n^1$ , we denote by  $u \cdot \lambda$  the measure of  $\mathbf{M}_n$  defined by

$$(u \cdot \lambda)(B) = \int_B u d\lambda \quad \text{for every } B \in \mathbf{B}.$$

**DEFINITION 2.1.** *We say that  $\mu \in \mathbf{M}_n$  is absolutely continuous with respect to  $\lambda$  (and we write  $\mu \ll \lambda$ ) if*

$$|\mu|(B) = 0 \quad \text{whenever } B \in \mathbf{B} \text{ and } \lambda(B) = 0.$$

*We say that  $\mu \in \mathbf{M}_n$  is singular with respect to  $\lambda$  (and we write  $\mu \perp \lambda$ ) if*

$$|\mu|(\Omega - B) = 0 \quad \text{for a suitable } B \in \mathbf{B} \text{ with } \lambda(B) = 0.$$

It is well-known that every absolutely continuous measure  $\mu \in \mathbf{M}_n$  is representable in the form  $\mu = a \cdot \lambda$  for a suitable  $a \in L_n^1$ ; moreover, the following Le-

besgue-Nykodim decomposition result for measures of  $\mathbf{M}_n$  holds (see [13] page 122).

**PROPOSITION 2.2.** *For every  $\mu \in \mathbf{M}_n$  there exist a unique function  $a \in L_n^1$  and a unique measure  $\mu^s \in \mathbf{M}_n$  such that*

- i)  $\mu = a \cdot \lambda + \mu^s$ ;
- ii)  $\mu^s$  is singular with respect to  $\lambda$ .

The function  $a$  is often indicated by  $\frac{d\mu}{d\lambda}$ .

For proper convex functions  $f: \mathbf{R}^n \rightarrow ]-\infty, +\infty]$  we define as usual the recession function of  $f$  (see [12]) by

$$f^\infty(s) = \lim_{t \rightarrow +\infty} \frac{f(w + ts)}{t} \quad \text{for every } s \in \mathbf{R}^n,$$

where  $w$  is any point in  $\mathbf{R}^n$  such that  $f(w) < +\infty$ ; in fact, the definition above is actually independent of the choice of  $w$ .

We are now in a position to state our integral representation result.

**THEOREM 2.3.** *Let  $\Phi: \mathbf{M}_n \times \mathbf{B} \rightarrow ]-\infty, +\infty]$  be a functional satisfying the following properties:*

- i)  $\Phi$  is  $\mathbf{B}$ -local (that is  $\Phi(\mu, B) = \Phi(\nu, B)$  whenever  $\mu, \nu \in \mathbf{M}_n$ ,  $B \in \mathbf{B}$ , and  $|\mu - \nu|(B) = 0$ );
- ii) for every  $\mu \in \mathbf{M}_n$  the set function  $\Phi(\mu, \cdot)$  is finitely additive;
- iii) the functional  $\Phi(\cdot, \Omega)$  is convex and sequentially lower semicontinuous with respect to the weak\*-convergence on  $\mathbf{M}_n$ ;
- iv) there exists  $u_0 \in L_n^1$  such that  $\Phi(u_0, B) < +\infty$  for every  $B \in \mathbf{B}$ ;
- v) for every  $\mu \in \mathbf{M}_n$  singular with respect to  $\lambda$  the function  $t \rightarrow \Phi(u_0 + t\mu, \Omega) - \Phi(u_0, \Omega)$  is positively 1-homogeneous.

Then, there exists a Borel function  $\phi: \Omega \times \mathbf{R}^n \rightarrow ]-\infty, +\infty]$  such that

- a) for every  $x \in \Omega$  the function  $\phi(x, \cdot)$  is convex and lower semicontinuous on  $\mathbf{R}^n$ ;
- b) there exist  $a \in L_1^1$  and  $b \geq 0$  such that  $\phi(x, s) \geq -b|s| + a(x)$  for  $\lambda$ -a.e.  $x \in \Omega$  and for all  $s \in \mathbf{R}^n$ ;
- c) the following integral representation formula holds for every  $\mu \in \mathbf{M}_n$ :

$$\Phi(\mu, B) - \Phi(u_0, B) = \int_B \phi\left(x, \frac{d\mu}{d\lambda}\right) d\lambda + \int_B \phi^\infty\left(x, \frac{d\mu^s}{d|\mu^s|}\right) d|\mu^s|$$

where  $\mu = \frac{d\mu}{d\lambda} \cdot \lambda + \mu^s$  is the Lebesgue-Nykodim decomposition of  $\mu$ , and for every  $x \in \Omega$   $\phi^\infty(x, \cdot)$  is the recession function of  $\phi(x, \cdot)$ .

d) the function  $\Phi^\infty(x, s)$  is lower semicontinuous in  $(x, s)$ .

By using the integral representation theorem above, we can solve the relaxation problem which can be stated as follows. Let  $f: \Omega \times \mathbf{R}^n \rightarrow [0, +\infty]$  be a given function (note that no measurability hypotheses are required); for every  $\mu \in \mathbf{M}_n$  define

$$(2.1) \quad F(\mu) = \begin{cases} \int_{\Omega}^* f(x, u(x)) d\lambda(x) & \text{if } \mu = u \cdot \lambda \text{ with } u \in L_n^1 \\ +\infty & \text{otherwise,} \end{cases}$$

where  $\int^*$  denotes the upper integral. We are interested in the characterization of the greatest functional  $\Phi$  on  $\mathbf{M}_n$  which is sequentially  $w^*$ -l.s.c. and less than or equal to  $F$ ; in particular, we want to write  $\Phi$  in the form

$$(2.2) \quad \Phi(\mu) = \int_{\Omega} \phi\left(x, \frac{d\mu}{d\lambda}\right) d\lambda(x) + \int_{\Omega} \phi^\infty\left(x, \frac{d\mu^s}{d|\mu|}\right) d|\mu|$$

for a suitable integrand  $\phi$ . The following result holds.

**THEOREM 2.4.** *Assume that the functional  $F$  defined in (2.1) is finite in at least one  $u_0 \in L_n^1$ . Then there exists a Borel function  $\phi(x, s)$ , convex and lower semicontinuous in  $s$ , such that (2.2) holds for every  $\mu \in \mathbf{M}_n$ . Moreover,  $\phi^\infty(x, s)$  is lower semicontinuous in  $(x, s)$ .*

### 3. SOME EXAMPLES

In [10] Olech found a characterization of all integrands  $\phi$  such that the functional

$$\Phi(u) = \int_{\Omega} \phi(x, u) d\lambda$$

is sequentially  $w^*$ - $\mathbf{M}_n$  lower semicontinuous on the space  $L_n^1$ . His result is that  $\Phi$  is sequentially  $w^*$ - $\mathbf{M}_n$  lower semicontinuous if and only if there exist a sequence of functions  $a_h \in L_n^1$  and a sequence of functions  $b_h \in C_n^0$  such that

$$\phi(x, u) = \sup \{a_h(x) + \langle b_h(x), u \rangle : h \in \mathbf{N}\} \quad \forall u \in \mathbf{R}^n$$

for  $\lambda$ -a.e.  $x \in \Omega$ . By using this result, it is possible to find an explicit characterization of the integrand given by Theorem 2.4 in some interesting cases (see also for instance [6], [8]).

EXAMPLE 1. Let  $f: \Omega \times \mathbf{R}^n \rightarrow \mathbf{R}$  be the function

$$f(x, s) = a(x) |s|$$

where  $a: \Omega \rightarrow [0, +\infty]$  is a measurable function. Then the relaxed functional  $\Phi$  of Theorem 2.4 can be represented in the form (2.2) with  $\phi$  given by

$$\phi(x, s) = \tilde{a}(x) |s|$$

where  $\tilde{a}$  is the greatest lower semicontinuous function on  $\Omega$  less than or equal to  $a$  almost everywhere on  $\Omega$ . If  $a \in L^1_{\text{loc}}(\Omega)$ , it is easy to see that the following formula holds

$$(3.1) \quad \tilde{a}(x) = \liminf_{y \rightarrow x} \limsup_{\rho \rightarrow 0} \int_{B_\rho(y)} a(t) dt \quad \text{for every } x \in \Omega.$$

EXAMPLE 2. Let  $a \in L^1_1$  and let  $f: \Omega \times \mathbf{R}^n \rightarrow \mathbf{R}$  be the function

$$f(x, s) = a(x) \sqrt{1 + |s|^2}.$$

If we denote by  $\tilde{a}$  the function defined in (3.1), then the relaxed functional  $\Phi$  given by Theorem 2.4 can be represented in the form (2.2) with  $\phi$  given by

$$\phi(x, s) = \begin{cases} \tilde{a}(x) \sqrt{1 + |s|^2} & \text{if } a(x) \leq \tilde{a}(x) \\ a(x) \sqrt{1 + |s|^2} & \text{if } a(x) > \tilde{a}(x) \text{ and } |s| \leq \\ & \leq \frac{\tilde{a}(x)}{\sqrt{a^2(x) - \tilde{a}^2(x)}} \\ \tilde{a}(x) |s| + \sqrt{a^2(x) - \tilde{a}^2(x)} & \text{otherwise.} \end{cases}$$

EXAMPLE 3. Let  $a: \Omega \rightarrow [0, +\infty]$  be a measurable function and let  $f: \Omega \times \mathbf{R} \rightarrow \mathbf{R}$  be the function

$$f(x, s) = a(x) |s|^p \quad (\text{with } p > 1).$$

Then, the relaxed functional  $\Phi$  given by Theorem 2.4 can be represented in the form (2.2) with  $\phi$  given by

$$\phi(x, s) = a^*(x) |s|^p$$



where  $a^*$  is the function

$$a^*(x) = \begin{cases} 0 & \text{if } x \in \Omega - U \\ +\infty & \text{if } x \in U \text{ and } a(x) = 0 \\ a(x) & \text{otherwise.} \end{cases}$$

and  $U$  is the greatest open subset of  $\Omega$  such that  $a^{1/(1-p)} \in L^1_{loc}(U)$ .

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