# ATTI ACCADEMIA NAZIONALE DEI LINCEI

CLASSE SCIENZE FISICHE MATEMATICHE NATURALI

# RENDICONTI

Ján Andres

Boundedness results of solutions to the equation x''' + ax'' + g(x)x' + h(x) = p(t) without the hypothesis  $h(x) \operatorname{sgn} x \ge 0$  for |x| > R.

Atti della Accademia Nazionale dei Lincei. Classe di Scienze Fisiche, Matematiche e Naturali. Rendiconti, Serie 8, Vol. **80** (1986), n.7-12, p. 533–539.

Accademia Nazionale dei Lincei

<http://www.bdim.eu/item?id=RLINA\_1986\_8\_80\_7-12\_533\_0>

L'utilizzo e la stampa di questo documento digitale è consentito liberamente per motivi di ricerca e studio. Non è consentito l'utilizzo dello stesso per motivi commerciali. Tutte le copie di questo documento devono riportare questo avvertimento.

Articolo digitalizzato nel quadro del programma bdim (Biblioteca Digitale Italiana di Matematica) SIMAI & UMI http://www.bdim.eu/

Atti della Accademia Nazionale dei Lincei. Classe di Scienze Fisiche, Matematiche e Naturali. Rendiconti, Accademia Nazionale dei Lincei, 1986.

Equazioni differenziali. — Boundedness results of solutions to the equation x''' + ax'' + g(x)x' + h(x) = p(t) without the hypothesis  $h(x) \operatorname{sgn} x \ge 0$  for |x| > R. Nota di JAN ANDRES, presentata <sup>(\*)</sup> dal Corrisp. R. CONTI.

RIASSUNTO. — Per l'equazione differenziale ordinaria non lineare del 3° ordine indicata nel titolo, studiata da numerosi autori sotto l'ipotesi  $h(x) \operatorname{sgn} x \ge 0$  per |x| >> R, si dimostra l'esistenza di almeno una soluzione limitata sopprimendo l'ipotesi suddetta.

#### 1. HISTORICAL REMARKS

About some fifteen years ago there was still under consideration a very actual question at that time of boundedness of solutions to the following Liénardtype third order equations

(1) 
$$x''' + ax'' + g(x) x' + h(x) = p(t),$$

where a is a positive real, g(x),  $h(x) \in C^{1}(\mathbb{R}^{1})$  and  $p(t) \in C^{1}(\mathbb{R}^{+})$ . Assuming either (see e.g. [1-5])

(2) 
$$b \leq g(x) \leq G$$
 (b, G-suitable positive reals)

or [1, 6, 7] G(x)/x  $\ge b$  for all  $x \in \mathbb{R}^3$ , where G(x) =  $\int_{-\infty}^{x} g(s) ds$ ,

$$\limsup_{|x|\to\infty} |h(x)| < \infty$$

together with

(4) 
$$\liminf_{|x|\to\infty} h(x) \operatorname{sgn} x > 0$$

or

(5) 
$$\limsup_{|x| \to \infty} h'(x) < ab$$

(\*) Nella seduta del 29 novembre 1986.

together with

(6)

 $\lim_{|x|\to\infty} h(x) \operatorname{sgn} x = \infty$ 

respectively, and

(7) 
$$\limsup_{t \to \infty} |p(t)| < \infty,$$
  
(8) 
$$|\int_{\infty}^{\infty} p(t) dt| < \infty,$$

many dissipativity results then had been carried out.

Furthermore, J.O.C. Ezeilo (jointly with H.O. Tejumola) pointed out [2] that (6) is superfluous with respect to (4) and (5) and the same author also noticed [3] that the conditions (7) and (8) are under (6) interchangeable.

K.E. Swick has succeeded [4] moreover in replacing (5) by a more liberal restriction, namely

$$\liminf_{|x|\to\infty} a \left( a \operatorname{G} (x)/x - 2h(x)/x \right) - \left( a^2/2 - \operatorname{G} (x)/x - \alpha h(x)/x \right)^2$$

with a suitable constant  $\alpha > 2(a^2 + b)/a(a^2 + 2b)$ . The same author still has studied [5] the more general case (cf. (4), (6))

(9)  $h(x) \operatorname{sgn} x \ge 0$  for  $|x| > \mathbb{R}$  (R-suitable positive real)

in spite of replacing (7), (8) by

(10) 
$$\int_{0}^{\infty} |p(t)| dt < \infty$$

in order to obtain the following result:

(11) 
$$\lim_{t\to\infty} x(t) = \overline{x}, \quad \lim_{t\to\infty} x'(t) = \lim_{t\to\infty} x''(t) = 0,$$

satisfied for all solutions of (1) with  $\overline{x}$  being the appropriate zero points of h(x); but note that so far only (9) has been used everywhere (see also [6, 7] to get the Lagrange-like stability.

REMARK 1. Recently the present author has shown [8] that also the oscillatory restoring term without (9) may imply the Lagrange-like stability of (1), provided the distances between the zero points of h(x) are large enough.

On the other side, J. Voráček has proved [7] that (1) admits a solution tending to the infinity for  $t \rightarrow \infty$ , provided besides (2), (3), (7), (8) the reversal

534

condition to (9), namely

(12) 
$$\limsup_{|x|\to\infty} h(x) \operatorname{sgn} x < -\varepsilon \quad (\varepsilon \operatorname{-suitable positive real}).$$

A natural problem arises: whether there exists besides unbounded solutions of (1) a bounded one as well, taking into account the same restrictions. In the following text we will give an affirmative answer to this question in the special case  $g(x) \equiv b$ . However, we would like to mention something before.

2. D'-CLASS AND THE AUTONOMOUS EQUATION (1)

DEFINITION. We say that (1) has D'-property (in the sense of Levinson) if such a constant D' exists that

$$\limsup_{t\to\infty} \left( |x'(t)| + |x''(t)| \right) < \mathcal{D}'$$

holds for all solutions x(t) of (1).

It can be easily verified either by the Liapunov-Yoshizawa function

(13) 
$$U(x', x'') = (a^2 + 2b) x'^2 + 2 ax' x'' + 2 x''^2$$

or by virtue of the Cauchy formula (see [6]) and hence also by the planar geometrical methods used in the (x, y)-phase-space for

$$\frac{\mathrm{d}x''}{\mathrm{d}x'} = -a - b \frac{x'}{x''} - \frac{1}{x''} (h(x(t)) - p(t))$$

that (1) has under (3), (7) the D'-property for  $g(x) \equiv b > 0$ .

However, we remember here an analytical approach by J. Voráček [7] leading to the same result even for more general than (1) equations, when (2) is satisfied with  $G < a^2$ , namely

(14) 
$$0 < b \leq g(x) \leq G < a^2 \quad \text{for all} \quad x \in \mathbb{R}^1.$$

LEMMA 1. If the conditions (3), (7) and (14) are satisfied, then (1) has the D'-property.

CONSEQUENCE 1. If the assumptions of Lemma 1 are satisfied for  $p(t) \equiv 0$  together with (9), where  $R \equiv 0$  and

(15) 
$$h'(0) > 0$$
,  $ag(0) - h'(0) > 0$ ,  $g'(0) = 0$ ,

then (11) holds for all the solutions of (1).

Proof. At first we will verify the Lagrange-like stability of (1).

For this aim let us assume (on the contrary) that x(t) is an unbounded solution of (1).

Since we have according to Lemma 1 that

|x'(t)| < D', |x''(t)| < D' for large enough t, say  $t \ge T$ , substituting x(t) into (1), integrating the obtained identity from T to t and multiplying it by sgn x, we get the following inequality:

$$b\left(|x\left(t\right)|-|x\left(\mathrm{T}\right)|\right) \leq |\int_{x\left(\mathrm{T}\right)}^{x\left(t\right)}g\left(s\right)\,\mathrm{d}s| < -\int_{\mathrm{T}}^{t}|h\left(x\left(s\right)\right)|\,\mathrm{d}s+2\left(a+1\right)\mathrm{D}' \leq \\ \leq 2\left(a+1\right)\mathrm{D}'$$

a contradiction to  $\limsup_{t\to\infty} |x(t)| = \infty$ .

Thus all the solutions of (1) must be bounded (without any loss of generality we arrive at the same statement under (8) in the non-autonomous case).

Using the same argument as above, we still obtain the relation

$$\left|\int_{0}^{\infty} h(x(t)) dt\right| \leq G\left(|x(T)| + \lim_{t \to \infty} |x(t)|\right) + 2(a+1)D' < \infty,$$

leading (for more details see [8]) either to (11) or to

$$\liminf_{t\to\infty} |x(t)| = 0 < \limsup_{t\to\infty} |x(t)|.$$

The latter possibility can be however neglected under (15) with respect to the asymptotical stability of the origin (see [9]). This completes the proof.

CONSEQUENCE 2. Let the assumptions of Lemma 1 be satisfied for  $p(t) \equiv \mathbf{0}$ and let the function h(x) be oscillatory everywhere with isolated zero points  $\overline{x}$ . If there exist such positive constants  $\varepsilon$ , R that the condition

(16) 
$$ag(x) - h'(x) \ge \varepsilon$$

holds for |x| > R with  $g'(\bar{x}) = 0$ , then all the solutions of (1) are bounded.

*Proof.* Remember again that Lemma 1 implies the existence of such a constant D' that every solution x(t) of (1) satisfies the relation

(17) 
$$|x'(t)| \leq D' \text{ for } t \geq T_x$$
 (T<sub>x</sub>-large enough).

Furthermore, it is clear that either the situation of Consequence 1 appears (not to be analysed here) or such sequences of the asymptotically stable (for more details see [9]) zero points  $\overline{x}_{\pm i}$  with  $\lim \overline{x}_{\pm i} = \pm \infty$ , namely  $\{\overline{x}_i\}$ ,  $\{\overline{x}_{-i}\}$ , can be found that their basins of attraction are determined (see [9]) by means of a suitable positive constant  $\delta_x$  from

$$|g'(x(t)) x'(t)| \leq \delta_x$$

and by the validity of  $h(x) \operatorname{sgn} (x - \overline{x}) > \mathbf{0}$ .

Therefore since we have (for  $t \ge T_x$ )

$$\lim_{x(t)\to\overline{x}} g'(x(t)) x'(t) = \mathbf{0}$$

for an unbounded solution x(t) of (1) and a certain zero point  $\overline{x}$  of h(x) with respect to (17) and  $g'(\overline{x}) = 0$ , the relation (18) will be realized in a small enough neighbourhood of  $\overline{x}$  and consequently x(t) will be attracted by it. Thus (1) is stable in the sense of Lagrange, which was to be proved.

REMARK 2. More precisely, only one of two possibilities from the proof of Consequence 1 can be satisfied for every solution of (1) (see [8]). Hence (11) holds for all the solutions of (1), when  $g(x) \equiv b$ , with respect to (18).

## 3. EXISTENCE OF A BOUNDED SOLUTION UNDER (12)

Now we come to the most controversial case via the asymptotic Poincaré boundary value problem.

LEMMA 2. If all the solutions of (1) satisfying a one-parameter family of boundary conditions

(19) 
$$x'(T) - x(0) = x'(T) - x'(0) = x''(T) - x''(0) = 0$$

are "a priori" uniformly bounded together with their two first derivatives independently of  $T \in (0, \infty)$ , then (1) admits a bounded solution, provided (12) holds with  $\varepsilon = |p(0)|$ .

*Proof.* The proof concerning the solvability of (1), (19) for a finite  $T \in R^1(T = \mu\omega)$ , where  $\mu \in (0, 1 >)$  can be found e.g. in [10] and the one of the limit case for  $T \rightarrow \infty$  is then guaranteed by the lemma of Krasnosel'skii [11, pp. 178-180].

THEOREM. Under the assumptions (3), (7), (8), (12) with  $\varepsilon = |p(0)|$  and  $g(x) \equiv b > 0$  the equation (1) admits a bounded solution.

*Proof.* According to Lemma 2 it is sufficient to prove the uniform "a priori" boundedness of the solutions of (1), (19) together with their two first

derivatives. For this purpose we will proceed by the well-known Yoshizawa's technique [12] of Liapunov functions.

Since the time-derivative of (13) with respect to (1) reads for  $g(x) \equiv b$ :

$$U_{(1)}(x', x'') = -2ax''^{2} - 2abx'^{2} + (4x'' + 2ax')(p(t) - h(x)),$$

such a positive constant S must exist that  $U'_{(1)}(x', x'')$  is negative definite for |x'| + |x''| > S,  $t \in \mathbb{R}^+$ ,  $x \in \mathbb{R}^1$  and simultaneously that

(20) 
$$\inf_{|x'|+|x''| \ge S_0} U(x', x'') > \sup_{|x'|+|x''|=S} U(x', x'')$$

is holding for some  $S_0 > S$  with respect to  $U(x', x'') \rightarrow \infty$  for  $|x'| + |x''| \rightarrow \infty$ .

Since the bound  $S_0$  is a uniform one with respect to (20), only two troublesome possibilities may occur; either the relation |x'(t)| + |x''(t)| > S holds for x(t) of (1), (19) on all the interval  $\langle 0, T \rangle$  or it is satisfied for  $0 \leq t < T_0 \leq T$  with  $|x'(T_0)| + |x''(T_0)| = S$ . Both possibilities however contradict to (19), because in the first case we come to U(x'(T), x''(T)) < U(x'(0), x''(0)), while in the second one to  $|x'(T)| + |x''(T)| \leq S_0 < |x(0)| + |x''(0)|$  (for  $S < |x'(0)| + |x''(0)| \leq S_0$  we might get some bound  $S_1 > S_0$ , when replacing  $S_0$  by  $S_1$  and S by  $S_0$  in (19), analogically).

Although only  $|x'(t)| + |x''(t)| \le S_1$  can be satisfied for all the solutions of (1), (19) as we could see, x(t) may be yet arbitrary. Therefore let us consider still another Liapunov function, namely

$$2V(t, x, x', x'') = 2\int_{0}^{x} h(s) ds + (bx + ax' + x'' - \int_{0}^{t} p(s) ds)^{2},$$

implying obviously the existence of such a positive constant R that the relation

(21) 
$$\inf_{|x|\geq R_0} V(t, x, x', x'') > \sup_{|x|=R} V(t, x, x', x'')$$

holds for some  $R_0 > R$ ,  $|x'| + |x''| \le S_1$  and  $t \in R^+$ .

Similarly, since its time-derivative with respect to (1), namely

$$V'_{(1)}(t, x, x', x') = -bh(x)x - h(x)(x'' + (a + 1)x' - \int_{0}^{t} p(s) ds),$$

is this time positive definite under our assumptions for |x| > R and  $|x'| + |x''| \le S_1$ ,  $t \in R^+$ , a uniform "a priori" boundedness result is given. Indeed, because otherwise if there exists such a point  $t_0 \in \langle 0, T \rangle$  with  $|x(t_0)| \ge R$ , and such a first point  $T_0 \in (t_0, T > \text{with } |x(T_0)| = R$ , then it should be satisfied V  $(t_0) > V(T_0)$  according to (21) and V  $(t_0) < V(T_0)$  with respect to the positive definiteness of  $V_1(t, x, x', x'')$  altogether. Moreover,  $|x(t)| > R_0$  for all  $t \in \langle 0, T \rangle$  would imply that V(T) > V(0), a contradiction to (19). This completes the proof.

REMARK 3. Recently we have proved [13] that such a bounded solution belongs under (10) to the class  $L_2 < 0$ ,  $\infty$ ), provided  $h(x) \operatorname{sgn} x < 0$  for  $x \neq 0$ .

### 4. Equations like (1) without D'-property

Equations without D'-property have been considered only rarely (see e.g. [13, 14]) and mainly similar dichotomy results have been obtained for them.

#### References

- [1] R. REISSIG, G. SANSONE and R. CONTI (1969) Nichtlineare Differentialgleichungen höherer Ordnung. Cremonese, Roma.
- [2] J.O.C. EZEILO and H.O. TEJUMOLA (1973) Boundedness theorems for certain third order equations. «Atti Accad. Naz. Lincei», (8), 55, 194-201.
- [3] J.O.C. EZEILO (1968) On the boundedness of solutions of the equation x''' + a x'' + f(x) x' + g(x) = p(t). «Ann. Mat. Pura Appl.», 4, 80, 281-299.
- [4] K.E. SWICK (1974) Boundedness and stability for nonlinear third order differential equations. «Atti Accad. Naz. Lincei», (8), 56, 859-865.
- [5] K.E. SWICK (1970) Asymptotic behavior of the solutions of certain third order differential equations. «SIAM J. Appl. Math.», 19, 96-102.
- [6] J. VORÁČEK (1966) Einige Bemerkungen über eine nichtlineare Differentialgleichungen dritten Ordnung. «Arch. Math.», 2, 19-26.
- [7] J. VORÁČEK (1970) Über eine nichtlineare Differentialgleichung dritter Ordnung.
  « Czech. Math. J. », 20, 207-219.
- [8] J. ANDRES (1986) Boundedness of solutions of the third order differential equation with the oscillatory restoring and forcing terms. «Czech. Math. J.», 1, 1-6.
- [9] J. ANDRES (1986) On stability and instability of the roots of the oscillatory function in a certain nonlinear differential equation of the third order. «Čas. pěst. mat.», 3, 225-229.
- [10] R. REISSIG (1973/74) Phasenraum-Methoden zum Studium nichtlinearerer Differentialgleichungen. « Jber. Deutch. Math.-Verein », 75 (3), 1, 130-139.
- [11] M.A. KRASNOSEL'SKI (1966) Translation operator along the trajectories of differential equations. « Nauka, Moscow » (in Russian).
- [12] T. YOSHIZAWA (1966) Stability theory by Liapunov's second method. « Math. Soc. Japan », Tokyo.
- [13] J. ANDRES Dichotomies for solutions of a certain third order nonlinear differential equation which is not from the class D. To appear in «Fasc. Math.».
- [14] L.R. ANDERSON (1970) Integral manifolds of a class of third order autonomous differential equations. « J. Diff. Eqs. », 7, 274-286.