## Atti Accademia Nazionale dei Lincei

# Classe Scienze Fisiche Matematiche Naturali RENDICONTI 

Eutiquio C. Young

## Comparison and oscillation theorems for singular hyperbolic equations

Atti della Accademia Nazionale dei Lincei. Classe di Scienze Fisiche, Matematiche e Naturali. Rendiconti, Serie 8, Vol. 59 (1975), n.5, p. 383-391.<br>Accademia Nazionale dei Lincei<br>[http://www.bdim.eu/item?id=RLINA_1975_8_59_5_383_0](http://www.bdim.eu/item?id=RLINA_1975_8_59_5_383_0)

L'utilizzo e la stampa di questo documento digitale è consentito liberamente per motivi di ricerca e studio. Non è consentito l'utilizzo dello stesso per motivi commerciali. Tutte le copie di questo documento devono riportare questo avvertimento.

> Articolo digitalizzato nel quadro del programma
> bdim (Biblioteca Digitale Italiana di Matematica)
> SIMAI \& UMI
> http://www.bdim.eu/

Equazioni a derivate parziali. - Comparison and oscillation theorems for singular hyperbolic equations. Nota di Eutiquio C. Young, presentata ${ }^{(*)}$ dal Socio M. Picone.

Riassunto. - In questa Nota si dimostrano teoremi di confronto e di oscillazione per equazioni singolari a derivate parziali del tipo iperbolico considerato in un dominio cilindrico.

È notevole uno dei risultati conseguiti, secondo il quale, una soluzione di una tale equazione che sia identicamente nulla sulla superficie laterale di un cilindro, ha nell'interno infiniti punti di zero.

## I. Introduction

The Sturmian comparison and oscillation theorems for ordinary differential equations have been extended extensively to partial differential equations of the elliptic type. For example, see Kuks [r], Swanson [2], [3], Diaz and McLaughlin [4], and Kreith and Travis [5], to mention only a few. In [6], by employing Swanson's technique, Dunninger obtained a comparison theorem for parabolic partial differential equations. His result was recently generalized by Chan and Young [7] to time-dependent quasilinear differential systems. However, for partial differential equations of hyperbolic type very little is known. As a matter of fact, certain Sturmian results for elliptic equations are false for hyperbolic equations without additional constraints. A simple example is the wave equation $u_{t t}-u_{x x}=0$ in the semi-infinite strip $\mathrm{S}=\{(x, t) \mid \mathrm{o} \leq x \leq \pi, \mathrm{o} \leq t<\infty\}$. Clearly $u(x, t)=\sin x \sin t$ is a solution of the wave equation which has infinitely many zeros in S while $u(x, t)=\mathrm{I}$ is also a solution which has no zero in S .

In [8] Kreith proved comparison and oscillation theorems for solutions of an initial boundary value problem for the damped wave equation in two variables. His results have been recently extended by Travis [9] to the normal hyperbolic equation in $n$ space variables. Other oscillation results for solutions of hyperbolic equations have also been obtained by Kahane [ro] under somewhat different conditions. The purpose of this paper is to present corresponding results for the pair of singular hyperbolic differential equations
and

$$
\mathrm{L} u \equiv u_{t t}+\frac{k}{t} u_{t}-\left(a_{i j}(x, t) u_{x_{i}}\right) x_{j}+p(x, t) u=\mathrm{o}
$$

$$
\mathrm{M} v \equiv v_{t t}+\frac{k}{t} v_{t}-\left(b_{i j}(x, t) v_{x_{i}}\right) x_{j}+q(x, t) v=0
$$

where $k$ is a real parameter $-\infty<k<\infty$, and the repeated indices are to be summed from i to $n$.
(*) Nella seduta del 15 novembre 1975.

The coefficient matrices ( $a_{i j}$ ) and ( $b_{i j}$ ) are assumed to be symmetric, positive definite, and of class $\mathrm{C}^{1}$ while $p$ and $q$ are simply continuous in the cylinder

$$
\Omega_{\tau}=\{(x, t) \mid x \in \mathrm{D}, \tau \leq t \leq \mathrm{T}\}
$$

$\tau \geq 0, \mathrm{~T}<\infty$, where D is a bounded domain in $\mathrm{E}^{n}$ with smooth boundary. By a solution of $\mathrm{L} u=0$ or $\mathrm{M} v=0$ we shall mean a function that is twice continuously differentiable in the interior of $\Omega_{\tau}$ and continuously differentiable in the closure $\bar{\Omega}_{\tau}$.

It will be seen that the parameter $k$ plays a role in our results.

$$
\text { 2. The Case }\left(a_{i j}\right)=\left(b_{i j}\right), i, j=\mathrm{I}, \cdots, n
$$

We treat first the case when $L$ and $M$ have the same principal parts, that is, $a_{i j}=b_{i j}$, for $i, j=\mathrm{I}, \cdots, n$. We consider the boundary value problems

$$
\begin{align*}
& u_{t t}+\frac{k}{t} u_{t}-\left(a_{i j} u_{x_{i}}\right)_{x_{j}}+p u=0 \quad \text { in } \Omega_{0}, \\
& \frac{\partial u}{\partial n}+r(x, t) u=0 \quad \text { on } \quad \partial \mathrm{D} \times[0, \mathrm{~T}] \tag{I}
\end{align*}
$$

and

$$
\begin{align*}
& v_{t t}+\frac{k}{t} v_{t}-\left(b_{i j} v_{x_{i}}\right)_{x_{j}}+q v=0 \quad \text { in } \quad \Omega_{0}, \\
& \frac{\partial v}{\partial n}+s(x, t) v=0 \quad \text { on } \quad \partial \mathrm{D} \times[\mathrm{o}, \mathrm{~T}] \tag{2}
\end{align*}
$$

where $\partial u / \partial n=a_{i j} u_{x_{i}} v_{j},\left(v_{1}, \cdots, v_{n}\right)$ being the outward unit normal vector on $\partial \mathrm{D}$, and $r$ and $s$ are continuous functions on $\partial \mathrm{D} \times[\mathrm{o}, \mathrm{T}]$. When $k>0$ we have the following result.

Theorem i. Let $k>0$ and suppose that $p \leq q$ and $r \leq s$. If there exists a solution of the problem ( I ) which is positive for $\mathrm{O}<t<\mathrm{T}$ such that $u(x, t)=0$, then every solution of the problem (2). has a zero in $\Omega_{0}$.

Proof. Let $v$ be a solution of the problem (2) and suppose that $v(y, t)>0$ in $\Omega_{0}$. Then by integrating the identity

$$
\begin{gathered}
t^{k}\left[v\left(u_{t t}+\frac{k}{t} u_{t}\right)-u\left(v_{t t}+\frac{k}{t} v_{t}\right)\right] \equiv \\
\equiv\left[t^{k}\left(u_{t} v-v_{t} u\right)\right]_{t}=t^{k}\left[a_{i j}\left(u_{x_{i}} v-v_{x_{i}} u\right)\right]_{x_{j}}+t^{k}(q-p) u v
\end{gathered}
$$

over $\Omega_{0}$ and using the divergence theorem, we obtain

$$
\begin{gather*}
\int_{\mathrm{D}}\left[t^{k}\left(u_{t} v-v_{t} u\right)\right]_{0}^{\mathrm{T}} \mathrm{~d} x=  \tag{3}\\
=\int_{0}^{\mathrm{T}} \int_{\partial \mathrm{D}} t^{k}\left(v \frac{\partial u}{\partial n}-u \frac{\partial v}{\partial n}\right) \mathrm{d} x \mathrm{~d} t+\iint_{\Omega_{0}} t^{k}(q-p) u v \mathrm{~d} x \mathrm{~d} t .
\end{gather*}
$$

Substituting the boundary conditions satisfied by $u$ and $v$, equation (3) yields
(4)

$$
\begin{gathered}
\int_{\mathrm{D}} \mathrm{~T}^{k} u_{t}(x, \mathrm{~T}) v(x, \mathrm{~T}) \mathrm{d} x= \\
=\int_{0}^{\mathrm{T}} \int_{\partial \mathrm{D}} t^{k}(s-r) u v \mathrm{~d} x \mathrm{~d} t+\iint_{\Omega_{0}} t^{k}(q-p) u v \mathrm{~d} x \mathrm{~d} t .
\end{gathered}
$$

From the assumption on $p, q, r$, and $s$, it follows that the righthand side of equation (4) is non-negative. But since $u>0$ for $0<t<\mathrm{T}$ and $u(x, \mathrm{~T})=0$, it follows that $u_{t}(x, \mathrm{~T})<0$, so that the lefthand side of equation (4) is negative. Thus we have a contradiction and so the theorem is proved.

It is clear from the proof that if $p<q$ or $r<s$, then we can conclude in the theorem that $v$ must have a zero in the interior of $\Omega_{0}$.

We note that in Theorem i no condition on $u$ need be prescribed at the singular line $t=0$. This is quite in contrast to the case when $k \leq \mathrm{o}$, which includes the normal hyperbolic equation ( $k=0$ ), as we shall see in the next theorem.

Theorem 2. Let $k \leq 0$ and suppose that $p \leq q$ and $r \leq s$. If there exists a solution $u$ of the adjoint of $\mathrm{L} u=\mathrm{o}$ that is,

$$
\mathrm{L}^{*} u=u_{t t}-\left(\frac{k}{t} u\right)_{t}-\left(a_{i j} u_{x_{i}}\right)_{x_{j}}+p u=0 \quad \text { in } \quad \Omega_{0}
$$

which is positive for $\mathrm{o}<t<\mathrm{T}$ such that $u(x, 0)=0, u(x, \mathrm{~T})=0$ for $x \in \mathrm{D}$ and $(\partial u / \partial n)+r u=0$ on $\partial \mathrm{D} \times[\mathrm{O}, \mathrm{T}]$, then every solution $v$ of the problem (2) has a zero in $\Omega_{0}$.

Proof. Again, let $v$ be a solution of the problem (2) and suppose that $v>0$ in $\Omega_{0}$. By integrating the identity

$$
\begin{gathered}
u \mathrm{M} v-v \mathrm{~L}^{*} u \equiv\left(u v_{t}-v u_{t}+k \frac{u v}{t}\right)_{t} \\
-\left[a_{i j}\left(u v_{x_{i}}-v u_{x_{i}}\right)\right]_{x_{j}}+(q-p) u v
\end{gathered}
$$

over $\Omega_{\varepsilon}$ and substituting the boundary conditions satisfied by $u$ and $v$, we obtain

$$
\begin{gather*}
\int_{\mathrm{D}}\left\{u_{t}(x, \mathrm{~T}) v(x, \mathrm{~T})+\left[u v_{t}-v u_{t}+k \frac{u v}{t}\right]_{t=\varepsilon}\right\} \mathrm{d} x  \tag{5}\\
=\iint_{\mathrm{s} \partial \mathrm{D}}(s-r) u v \mathrm{~d} x \mathrm{~d} t+\iint_{\Omega \varepsilon}(q-p) u v \mathrm{~d} x \mathrm{~d} t .
\end{gather*}
$$

Now we let $\varepsilon$ tend to zero. Since $u(x, 0)=0$, we note that $\lim _{\varepsilon \rightarrow 0} u(x, \varepsilon) / \varepsilon=$ $=u_{t}(x, 0+)$. Thus as $\varepsilon \rightarrow 0$, the boundary integral yields ${ }_{\varepsilon \rightarrow 0}$

$$
\int_{\mathrm{D}}\left[u_{t}(x, \mathrm{~T}) v(x, \mathrm{~T})+(k-\mathrm{I}) u_{t}(x, \mathrm{o}) v(x, \mathrm{o})\right] \mathrm{d} x
$$

which is negative since $u_{t}(x, 0)>0, u_{t}(x, \mathrm{~T})<0$, and $k \leq 0$. This contradicts the fact that the righthand side in equation (5) is non-negative.

If we consider the problems (I) and (2) in the cylinder $\Omega_{\tau}$ where $\tau>0$, then a combination of the conditions in Theorems i and 2 leads to the following result which is valid for any value of the parameter $k$.

Corollary i. If there exists a solution of $\mathrm{L} u=\mathrm{o}$ in $\Omega_{\tau}$ which is positive for $\tau<t<\mathrm{T}$ such that $u(x, \tau)=0, u(x, \mathrm{~T})=0$, and $\partial u / \partial n+r u=0$ on $\partial \mathrm{D} \times[\tau, \mathrm{T}]$, then every solution $v$ of $\mathrm{M} v=\mathrm{o}$ in $\Omega_{\tau}$ satisfying the condition $\partial v / \partial n+s v=0$ on $\partial \mathrm{D} \times[\tau, \mathrm{T}]$ has a zero in $\Omega_{\tau}$.

The proof is similar to that of Theorem I.

$$
\text { 3. The CASE }\left(a_{i j}\right) \leq\left(b_{i j}\right)
$$

The results obtained above can be extended to the case when $a_{i j} \leq$ $\leq b_{i j}, i, j=\mathrm{I}, \cdots, n$, provided the coefficients $a_{i j}, p, r$, and $b_{i j}, q, s$ are all independent of the variable $t$, so that $L$ and $M$ are both variable separable.

Theorem 3. Let u be a nontrivial solution of the problem

$$
\begin{align*}
& u_{t t}+\frac{k}{t} u_{t}-\left(a_{i j}(x) u_{x_{i}}\right)_{x_{j}}+p(x) u=0 \quad \text { in } \quad \Omega_{0} \\
& \frac{\partial u}{\partial n}+r(x) u=0 \quad \text { on } \quad \partial \mathrm{D} \times[\mathrm{o}, \mathrm{~T}] \tag{6}
\end{align*}
$$

such that $u(x, \mathrm{~T})=0$ for $k<0$ or $u(x \quad 0)=0$ and $u(x, \mathrm{~T})=0$ for $k \leq \mathrm{o}$,
where $p \geq 0, r \geq 0$, and $p, r$ are not both identically zero. If

$$
\begin{array}{ll}
a_{i j}(x) \leq b_{i j}(x), & i, j=\mathrm{I}, \cdots, n  \tag{7}\\
p(x) \leq q(x) \quad \text { and } \quad r(x) \leq s(x) &
\end{array}
$$

where at least one strict inequality holds throughout D , then every solution $v$ of

$$
\begin{aligned}
& v_{t t}+\frac{k}{t} v_{t}-\left(b_{i j}(x) v_{x_{i}}\right)_{x_{j}}+q(x) v=0 \quad \text { in } \Omega_{0} \\
& \frac{\partial v}{\partial n_{b}}+s(x) v=0 \quad \text { on } \quad \partial \mathrm{D} \times[\mathrm{o}, \mathrm{~T}]
\end{aligned}
$$

$\left(\partial v / \partial n_{b}=b_{i j} v_{x_{i}} \nu_{j}\right)$ has a zero in the interior of $\Omega_{0}$.
Proof. Let $\varphi$ and $\psi$ be the positive normalized eigenfunctions corresponding to the first eigenvalues $\lambda_{0}$ and $\mu_{0}$ of the problems
(9)

$$
-\left(a_{i j}(x) w_{x_{i}}\right)_{x_{j}}+p(x) w=\lambda w \quad \text { in } \quad \mathrm{D}
$$

$$
\frac{\partial w}{\partial n}+r(x) w=\mathrm{o} \quad \text { on } \quad \partial \mathrm{D}
$$

and

$$
-\left(b_{i j}(x) w_{x_{i}}\right)_{x_{j}}+q(x) w=\mu z^{\prime} \quad \text { in } \quad \mathrm{D}
$$

$$
\begin{equation*}
\frac{\partial w}{\partial n_{b}}+s(x) w=0 \quad \text { on } \quad \partial \mathrm{D} \tag{io}
\end{equation*}
$$

respectively. By using variational principles, we may characterize the eigenvalues $\lambda_{0}$ and $\mu_{0}$ as

$$
\begin{align*}
0<\lambda_{0} & =\min _{w \in \Phi} \int_{\mathrm{D}}\left(a_{i j} w_{x_{i}} x_{x_{j}}+p w^{2}\right) \mathrm{d} x+\int_{\partial \mathrm{D}} r w^{2} \mathrm{~d} x  \tag{II}\\
& =\int_{\mathrm{D}}\left(a_{i j} \varphi_{x_{i}} \varphi_{x_{j}}+p \varphi^{2}\right) \mathrm{d} x+\int_{\partial \mathrm{D}} r \varphi^{2} \mathrm{~d} x \\
& <\int_{\mathrm{D}}\left(b_{i j} \psi_{x_{i}} \psi_{x_{j}}+q \psi^{2}\right) \mathrm{d} x+\int_{\partial \mathrm{D}} s \psi^{2} \mathrm{~d} x \\
& =\min _{w \in \Psi} \int_{\mathrm{D}}\left(b_{i j} w_{x_{i}} w_{x_{j}}+q w^{2}\right) \mathrm{d} x+\int_{\partial \mathrm{D}} s w^{2} \mathrm{~d} x=\mu_{0}
\end{align*}
$$

where $\Phi$ and $\Psi$ are the sets of $C^{2}$ functions with unit $L^{2}$ norm satisfying the boundary conditions of the problems (9) and (io) respectively. Notice that the inequality in equation (II) is due to the assumption made on equation (7).

Now let $v$ be a solution of the problem (8) and let us define

$$
\mathrm{U}(t)=\int_{\mathrm{D}} u(x, t) \varphi(x) \mathrm{d} x \quad \text { and } \quad \mathrm{V}(t)=\int_{\mathrm{D}} v(x, t) \psi(x) \mathrm{d} x^{t}
$$

Then from equations (6) and (9), we have

$$
\begin{equation*}
\mathrm{U}^{\prime \prime}+\frac{k}{t} \mathrm{U}^{\prime}+\lambda_{0} \mathrm{U}=\mathrm{o} \tag{I2}
\end{equation*}
$$

with the boundary conditions $\mathrm{U}(\mathrm{T})=\mathrm{o}$ for $k>\mathrm{o}$, and $\mathrm{U}(\mathrm{o})=\mathrm{o}, \mathrm{U}(\mathrm{T})=\mathrm{o}$ for $k \leq \mathrm{o}$. Likewise from (8) and (io) we have

$$
\begin{equation*}
\mathrm{V}^{\prime \prime}+\frac{k}{t} \mathrm{~V}^{\prime}+\mu_{0} \mathrm{~V}=\mathrm{o} \tag{13}
\end{equation*}
$$

If $k \geq \mathrm{I}$, then a solution of equation (I2) which is bounded at $t=0$ is given by

$$
\mathrm{U}(t)=t^{(t-k) / 2} \mathrm{~J}_{(k-1) / 2}\left(\sqrt{\overline{\lambda_{0}}} t\right)
$$

where $\mathrm{J}_{k}$ is the Bessel function of the first kind of order $k$. The condition $U(T)=0$ thus implies that $J_{(k-1) / 2}\left(\sqrt{\lambda_{0}} \mathrm{~T}\right)=0$. This means that

$$
\mathrm{V}(t)=t^{(1-k) / 2} \mathrm{~J}_{(k-1) / 2}\left(\sqrt{\mu_{0}} t\right)
$$

which satisfies equation (I3), vanishes at $t=\left(\lambda_{0} / \mu_{0}\right)^{1 / 2} \mathrm{~T}<\mathrm{T}$. Since $\psi(x)>0$ we conclude from the definition of V that $v$ has a zero in the interior of $\Omega_{0}$ when $k \geq \mathrm{I}$.

For $\mathrm{o}<k<\mathrm{I}$, a solution of equation (12) which is bounded at $t=\mathrm{o}$ is given by

$$
\mathrm{U}(t)=t^{(1-k) / 2}\left[\mathrm{C}_{1} \mathrm{~J}_{(k-1) / 2}\left(\sqrt{\lambda_{0}} t\right)+\mathrm{C}_{2} \mathrm{~J}_{(1-k) / 2}\left(\sqrt{\lambda_{0}} t\right)\right]
$$

where $C_{1}$ and $C_{2}$ are some constants. Since $U(T)=0$, the constants $C_{1}, C_{2}$ can be determined, and hence the function

$$
\mathrm{V}(t)=t^{(1-k) / 2}\left[\mathrm{C}_{1} \mathrm{~J}_{(k-1) / 2}\left(\sqrt{\mu_{0}} t\right)+\mathrm{C}_{2} \mathrm{~J}_{(1-k) / 2}\left(\sqrt{\mu_{0}} t\right)\right]
$$

also vanishes at $t=\left(\lambda_{0} / \mu_{0}\right)^{1 / 2} \mathrm{~T}<\mathrm{T}$. By the same argument as in the previous case, we again see that $v$ has a zero in the interior of $\Omega_{0}$.

Finally, the case $k \leq 0$ can also be proved in exactly the same manner provided we note that a solution of equation (I2) which vanishes at $t=0$ is given by

$$
\mathrm{U}(t)=t^{(1-k) / 2} \mathrm{~J}_{(k-1) ; 2}\left(\sqrt{\lambda_{0}} t\right) .
$$

## 4. Oscillation Theorems

We shall now consider the oscillation phenomenon of solutions of the equation $\mathrm{L} u=0$ in the semi-infinite cylinder $\mathrm{G}=\{(x, t) \mid x \in \mathrm{D}, \mathrm{o} \leq$ $\leq t<\infty\}$. We shall say that $\mathrm{L} u=0$ is oscillatory if every solution of the equation which vanishes on the lateral surface of $G$ has arbitrarily large zeros in the interior of G. First, we shall establish an oscillation criterion in the case when the matrix ( $a_{i j}$ ) of L is independent of $t$.

Theorem 4. Let $p(x) \geq 0$ and $r(x) \geq 0$ in D where $p$ and $r$ are not both identically zero. If $p(x) \leq q(x, t)$ in G and $r(x) \leq s(x, t)$ on $\partial \mathrm{D} \times[\mathrm{o}, \infty)$, then every solution $v$ of

$$
v_{t t}+\frac{k}{t} v_{t}-\left(\alpha_{i j}(x) v_{x_{i}}\right)_{x_{j}}+q(x, t) v=0
$$

satisfying $\partial v / \partial n+s v=0$ on $\partial \mathrm{D} \times[0, \infty)$ has a zero in $\mathrm{G}_{\tau}=\{(x, t) \mid x \in \mathrm{D}$, $\tau \leq t<\infty\}$ for every $\tau$.

Proof. We shall give the proof only for the case $k>0$ as the proof for $k \leq \mathrm{o}$ is similar. Let $\varphi>0$ be the eigenfunction corresponding to the first eigenvalue $\lambda_{0}$ of the problem (9). Then

$$
u(x, t)=t^{(1-k) / 2} \mathrm{~J}_{(k-1) / 2}\left(\sqrt{\lambda_{0}} t\right) \varphi(x)
$$

is a nontrivial solution of problem (6) which vanishes at the sequence of points $t_{1}<t_{2}<\cdots<t_{n}<\cdots, t_{n}=z_{n} / \sqrt{\lambda_{0}}(n \geq \mathrm{I})$, where $z_{n}$ are the zeros of the Bessel function $\mathrm{J}_{(k-1) / 2}(z)$. The theorem then follows by applying Corollary I to each of the domains

$$
\mathrm{G}_{n}=\left\{(x, t) \mid x \in \mathrm{D}, t_{n} \leq t \leq t_{n+1}\right\} \quad, \quad n \geq \mathrm{I}
$$

More generally, let $h$ be any positive function that is continuous in $D$ with $L^{2}$ norm. Let $Q$ be a continuous function satisfying the inequality

$$
\mathrm{Q}(t) \leq \frac{(\mathrm{P} u, h)}{(u, h)}
$$

where

$$
\mathrm{P} u=-\left(a_{i j}(x, t) u_{x_{i}}\right)_{x_{j}}+p(x, t) u \text { and } \quad(u, h)=\int_{\mathrm{D}} u(x, t) h(x) \mathrm{d} x
$$

for all functions $u$ that are twice continuously differentiable and positive in $G$ for large $t$ and that vanish on the lateral boundary of G . Then the following two theorems generalize Theorems 6 and 7 and [9], respectively.

TheOrem 5. The hyperbolic equation

$$
n_{t t}+\frac{k}{t} u_{t}-\left(a_{i j}(x, t) u_{x_{i}}\right)_{x_{j}}+p(x, t) u=0
$$

is oscillatory in $G$ if the equation

$$
Z^{\prime \prime}+\frac{k}{t} Z^{\prime}+Q Z=0
$$

is oscillatory for $t>0$.
Theorem 6. The hyperbolic equation

$$
u_{t t}+\frac{k}{t} u_{x}-\left(a_{i j}(x) u_{x_{i}}\right)_{x_{j}}+p(x) u=0
$$

is oscillatory in $G$ if and only if the elliptic equation

$$
-\left(a_{i j}(x) u_{x_{i}}\right)_{x_{j}}+p(x) u=0
$$

is disconjugate in D .
The proofs are similar to those given in [9] with slight modification.

## 5. Concluding Remarks

When $k=\mathrm{o}$ the equation $\mathrm{L} u=\mathrm{o}$ reduces to the hyperbolic equation considered by Travis [9]. Hence our results here include those obtained in [9]. Finally, it should be pointed out that comparison results for the corresponding singular elliptic equation $u_{t t}+(k \mid t) u_{t}+\left(a_{i j} u_{x_{i}}\right)_{x_{j}}+p u=0$ have recently been given by Dunninger and Weinacht [II].

## References

[I] L.M. KUKS (1962) - Sturm's theorem and oscillation of solutions of strongly elliptic systems, "Dokl. Akad. Nauk. SSSR》, 142, 32-35.
[2] C. A. Swanson (1968) - Comparison and oscillation theory of linear differential equations, Academic Press, New York.
[3] C. A. Swanson - Strong oscillation of elliptic equations on general domains, "Canadian Math. Bull.» (to appear).
[4] J. B. Diaz and J. R. McLaughlin (1969) - Sturm separation and comparison theorems for ordinary and partial differential equations, "Atti Accad. Naz. Lincei, Mem. Cl. Sci. fis. mat. nat. », 9, 135-194.
[5] K. Kreith and C. Travis (1972) - Oscillation criteria for selfadjoint elliptic equations, "Pacific J. Math. 》, 4I, 743-753.
[6] D. R. Dunninger (1969) - Sturmian theorems for parabolic inequalities, «Rend. Accad. Sci. fis. mat., Napoli», 36, 406-410.
[7] C. Y. Chan and E. C. Young (1973) - Unboundedness of solutions and comparison theorems for time-dependent quasilinear differential matrix inequalities, "J. Diff. Eqs.», 14, 195-201.
[8] K. Kreith (1969) - Sturmian theorems for hyperbolic equations, "Proc. Amer. Math. Soc.», 22, 277-281.
[9] C. Travis - Comparison and oscillation theorems for hyperbolic equations, (to appear).
[10] C. Kahane (1973) - Oscillation theorems for solutions of hyperbolic equations "Proc. Amer. Math. Soc. 》, 4I, 183-188.
[II] D. R. Dunninger and R. J. Weinacht (1971) - Separation and comparison theorems for classes of singular elliptic inequalities and degenerate elliptic inequalities, "Applicable Analysis », I, 43-55.

