## Bollettino

Unione Matematica Italiana

## Alex Iosevich

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Bollettino dell'Unione Matematica Italiana, Serie 8, Vol. 2-B (1999), n.2, p. 383-387.

Unione Matematica Italiana
[http://www.bdim.eu/item?id=BUMI_1999_8_2B_2_383_0](http://www.bdim.eu/item?id=BUMI_1999_8_2B_2_383_0)

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# Fourier Transform, $L^{2}$ Restriction Theorem, and Scaling. 

Alex Iosevich


#### Abstract

Sunto. - In questo lavoro facciamo vedere, con un argomento di omogeneità di tipo Knapp, che se vale un teorema di restrizione $\left(L^{p}, L^{2}\right)$ per una ipersuperficie compatta, convessa e di tipo finito, allora si possono provare stime isotropiche ottimali per la trasformata di Fourier della misura di indotta dalla misura di Lebesgue sulla superficie.


## Introduction.

Let $S$ be a smooth compact finite type hypersurface. Let $F_{S}(\xi)=$ $\int_{S} e^{-i\langle x, \xi\rangle} d \sigma(x)$, where $d \sigma$ denotes the Lebesgue measure on $S$. Let $\Re f=\left.\hat{f}\right|_{S}$, where $\hat{f}(\xi)$ denotes the standard Fourier transform of $f$. It is well known (see [T], [Gr]) that if $\left|F_{S}(\xi)\right| \leqslant C(1+|\xi|)^{-r}, r>0$, then $\mathcal{R}: L^{p}\left(\mathbb{R}^{n}\right) \rightarrow L^{2}(S)$ for $p \leqslant(2(r+1)) /(r+2)$. A natural question to ask is, does the boundedness of $\mathcal{R}: L^{(2(r+1)) /(r+2)}\left(\mathbb{R}^{n}\right) \rightarrow L^{2}(S), r>0$, imply that $\left|F_{S}(\xi)\right| \leqslant C(1+|\xi|)^{-r}$ ? In this paper we will show that this is indeed the case if $S$ is a smooth convex finite type hypersurface in the sense that the order of contact with every tangent line is finite. (See [BNW]).

Under a more general condition, called the finite polyhedral type assumption, (see Definition 1 below), we will show that the ( $L^{p}, L^{2}$ ) restriction theorem with $p=(2(r+1)) /(r+2)$ implies that $|B(x, \delta)| \leqslant C \delta^{r}$, where $B(x, \delta)=$ $\left\{y: \operatorname{dist}\left(y, T_{x}(S)\right) \leqslant \delta\right\}$, where $T_{x}(S)$ denotes the tangent hyperplane to $S$ at $x$.

Our plan is as follows. We will first use a variant of the Knapp homogeneity argument to show that if $S$ satisfies the finite polyhedral type condition and $\mathcal{R}: L^{p}\left(\mathbb{R}^{n}\right) \rightarrow L^{2}(S)$, with $p=(2(r+1)) /(r+2)$, then $|B(x, \delta)| \leqslant C \delta^{r}$ for each $x$. If the surface is, in addition, convex and finite type, then the result due to Bruna, Nagel, and Wainger (see [1]) implies that $\left|F_{S}(\xi)\right| \leqslant C(1+|\xi|)^{-r}$. If the surface is not convex finite type, then we do not, in general, know how to conclude that $|B(x, \delta)| \leqslant C \delta^{r}$ implies that $\left|F_{S}(\xi)\right| \leqslant C(1+|\xi|)^{-r}$. A gap remains.

## 1. - Statement of results.

Definition 1. - Let $S$ be a smooth compact hypersurface in $\mathbb{R}^{n}$. Let $B^{\pi}(x, \delta)$ denote the projection of $B(x, \delta)$ onto $T_{x}(S)$. We say that $S$ is of finite
polyhedral type if there exists a family of polyhedra $P(x, \delta)$ such that $B^{\pi}(x, \delta) \subset P(x, \delta), C_{1}\left|B^{\pi}(x, \delta)\right| \leqslant|P(x, \delta)| \leqslant C_{2}\left|B^{\pi}(x, \delta)\right|$, where $C_{1}, C_{2}$ do not depend on $\delta$, and the number of vertices of $P(x, \delta)$ is bounded above independent of $\delta$, where $\chi_{P(x, \delta)}$ denotes the characteristic function of $P(x, \delta)$.

Remark. - The motivation for the definition of finite polyhedral type is the standard homogeneity argument due to Knapp. In order to prove the sharpness of the ( $L^{p}, L^{2}$ ) restriction theorem for hypersurfaces with non-vanishing Gaussian curvature, Knapp approximated such a surface with a box with side-lengths $\left(\delta, \ldots, \delta, \delta^{2}\right), \delta$ small. He then took $f_{\delta}$ to be the inverse Fourier transform of the characteristic function of that box. It is not hard to see that $\|\mathscr{R} f\|_{2} \approx \delta^{(n-1) / 2}$. On the other hand, using the fact that the Fourier transform of the box in question is $\approx \sin \left(\delta^{2} x_{n}\right) / x_{n} \prod_{j=1}^{n-1} \sin \left(\delta x_{j}\right) / x_{j}$, it is not hard to see that $\left\|f_{\delta}\right\|_{p} \approx \delta^{(n+1) / p^{\prime}}$. It follows that $p \leqslant(2(n+1)) /(n+3)$, which is the known positive result due to Stein and Tomas. The crucial part of this calculation is the approximation of the surface with a box with appropriate dimensions. Definition 1 and Theorem 2 are generalizations of this phenomenon.

It should also be noted that it is not hard to see that the hypersurface $S=$ $\left\{x: x_{3}=x_{1} x_{2}\right\}$ does not satisfy the finite polyhedral type condition. Thus, it makes sense to think of the finite polyhedral type condition as a generalization of convexity.

Theorem 2. - Let $S$ be of finite polyhedral type. Consider the estimates

$$
(* *)
$$

$$
\begin{gather*}
\left|F_{S}(\xi)\right| \leqslant C(1+|\xi|)^{-r}  \tag{*}\\
\mathcal{R}: L^{p}\left(\mathbb{R}^{n}\right) \rightarrow L^{2}(S), \quad p \leqslant \frac{2(r+1)}{r+2}
\end{gather*}
$$

and
(***)

$$
|B(x, \delta)| \leqslant C \delta^{r}
$$

for each $x$.
Then( *) implies ( * * ) and ( * *) implies ( * * * ).Further, ( * * *) implies ( * ) if $S$ is in addition convex and finite type.

The fact that ( * ) implies ( $* *$ ) is essentially the Stein-Tomas restriction theorem. (See [T], [Gr]). The fact that ( $* * *$ ) implies ( $*$ ) in the case of convex finite type hypersurfaces is due to Bruna, Nagel, and Wainger. (See [BNW]). So it remains to prove that $(* *)$ implies $(* * *)$, and that convex finite type hypersurfaces are of finite polyhedral type. (See Theorems 3 and 4 below).

Theorem 3. - Let $S=\left\{x: x_{n}=Q\left(x^{\prime}\right)+R\left(x^{\prime}\right)+c\right\}$, where $x^{\prime}=\left(x_{1}, \ldots, x_{n-1}\right)$, $Q \in C^{\infty}$ is mixed homogeneous in the sense that there exist integers ( $a_{1}, \ldots, a_{n-1}$ ),
$a_{j} \geqslant 1$, such that $Q\left(t^{1 / a_{1}} x_{1}, \ldots, t^{1 / a_{n-1}} x_{n-1}\right)=t Q\left(x^{\prime}\right), Q\left(x^{\prime}\right) \neq 0$ if $x^{\prime} \neq(0, \ldots, 0)$, $R \in C^{\infty}$ is the remainder in the sense that $\lim _{t \rightarrow 0} R\left(t^{1 / a_{1}} x_{1}, \ldots, t^{1 / a_{n-1}} x_{n-1}\right) / t=$ 0 , and $c$ is a constant. Then $S$ is of finite polyhedral type.

Theorem 3 implies that convex finite type hypersurfaces are of finite polyhedral type via the following representation result due to Schulz. (See [Sch]). See also [IS2].)

Theorem 4. - Let $\Phi \in C^{\infty}\left(\mathbb{R}^{n-1}\right)$ be a convex finite type function such that $\Phi(0, \ldots, 0)=0$ and $\nabla \Phi(0, \ldots, 0)=(0, \ldots, 0)$. Then, after perhaps applying a rotation, we can write $\Phi(y)=Q(y)+R(y)$, where $Q$ is a convex polynomial, mixed homogeneous in the sense of Theorem 3 , and $R$ is the remainder in the sense of Theorem 3.

## 2. $-(* *) \rightarrow(* * *)$.

Locally, $S$ is a graph of a smooth function $\Phi$, such that $\Phi(0, \ldots, 0)=0$, and $\nabla \Phi(0, \ldots, 0)=(0, \ldots, 0)$. If we consider a sufficiently small piece of our hypersurface, $B^{\pi}(0, \ldots, 0, \delta)=\{y \in K: \Phi(y) \leqslant \delta\}$, where $K$ is a compact set in $\mathbb{R}^{n-1}$ containing the origin, and, without loss of generality, $\Phi(y) \geqslant 0$. Since $\left|B^{\pi}(x, \delta)\right| \approx|B(x, \delta)|$, it suffices to show that $|\{y \in K: \Phi(y) \leqslant \delta\}| \leqslant C \delta^{r}$.

Let $f_{\delta}$ be a function such that $\hat{f}_{\delta}$ is the characteristic function of the set $\left\{\left(x^{\prime}, x_{n}\right): x^{\prime} \in P_{\delta} ; 0 \leqslant x_{n} \leqslant \delta\right\}$, where $P_{\delta}$ is the polyhedron containing the set $\left\{x^{\prime}: \Phi\left(x^{\prime}\right) \leqslant \delta\right\}$ given by the definition of finite polyhedral type.

Let's assume for a moment that $\left\|f_{\delta}\right\|_{p} \leqslant C\left(\delta\left|P_{\delta}\right|\right)^{1 / p^{\prime}}$. Since the restriction theorem holds, we must have $\left\|\Re f_{\delta}\right\|_{2} \leqslant C\left\|f_{\delta}\right\|_{p}$, which implies that $\left|P_{\delta}\right| \leqslant$ $C \delta^{(2(p-1)) /(2-p)}$. Since $p=(2(r+1)) /(r+2)$, it follows that $\left|P_{\delta}\right| \leqslant C \delta^{r}$. By the definition of $P_{\delta}$ it follows that $|B(0, \ldots, 0, \delta)|=\left|B^{\pi}(0, \ldots, 0, \delta)\right|=$ $|\{y \in k: \Phi(y) \leqslant \delta\}| \leqslant C \delta^{r}$.

This completes the proof provided that we can show that $\left\|f_{\delta}\right\|_{p} \leqslant$ $C\left(\delta\left|P_{\delta}\right|\right)^{1 / p^{\prime}}$. More generally, we will show that if $P$ is a polyhedron in $\mathbb{R}^{n}$, then $\left\|\widehat{\chi}_{P}\right\|_{p} \leqslant C|P|^{1 / p^{\prime}}$, where $C$ depends on the dimension and the number of vertices of $P$ and $|P|$ denotes the volume of $P$. We give the argument in two dimensions, the argument in higher dimensions being similar. Break up $P$ as a union of disjoint (up to the boundary) triangles $t_{j}, j=1, \ldots, N$. Since $\chi_{P}(x)=$ $\sum \chi_{t_{j}}(x)$, it suffices to carry out the argument for $\chi_{P}$, where $P$ is assumed to be a triangle. Since translations don't contribute anything in this context, we may assume that one of the vertices of the triangle is at the origin. Break up this triangle, if necessary, into two right triangles. Refine the original decomposition so that it consists of right triangles. Rotate the right triangle so that it is in the first quadrant and one of the sides is on the $x_{1}$-axis. We now apply a linear trans-
formation mapping this triangle (denoted by $P^{\prime}$ ) into the triangle with the endpoints $(0,0),(1,0)$ and $(1,1)$. It is easy to check by an explicit computation that the Fourier transform of the characteristic function of this triangle has the $L^{p}$ norm (crudely) bounded by $2^{1 / p}$.

Let $T$ denote the linear transformation taking the triangle $P^{\prime}$ to the unit triangle above. We see that

$$
\widehat{\chi}_{T P^{\prime}}(\xi)=|T| \widehat{\chi}_{P^{\prime}}\left(T^{t} \xi\right),
$$

so

$$
\left\|\hat{\chi}_{T P^{\prime}}\right\|_{p}=|T|^{1 / p^{\prime}}\left\|\hat{\chi}_{P^{\prime}}\right\|_{p}
$$

Since $|T|=1 /\left|P^{\prime}\right|$, we see that $\left\|\hat{\chi}_{t_{j}}\right\|_{p} \leqslant C\left|t_{j}\right|^{1 / p^{\prime}}$, where the $t_{j}$ s are the triangles from the (refined) original decomposition. Adding up the estimates we get

$$
\left\|\hat{\chi}_{P}\right\|_{p} \leqslant C \sum_{j=0}^{N}\left|t_{j}\right|^{1 / p^{\prime}} \leqslant C N\left(\sum_{j=0}^{N}\left|t_{j}\right|\right)^{1 / p^{\prime}}=C N|P|^{1 / p^{\prime}}
$$

In higher dimensions the proof is virtually identical with triangles replaced by ( $n-1$ )-dimensional simplices, i.e the convex hull of $n$ points that are not contained in any ( $n-2$ )-dimensional plane.

Since we have assumed that the number of vertices of $P_{\delta}$ is bounded above, it follows that $\left\|f_{\delta}\right\|_{p} \leqslant C\left(\delta\left|P_{\delta}\right|\right)^{1 / p^{\prime}}$, as desired.

## 3. - Proof of Theorem 3.

As before, it is enough to consider the set $B^{\pi}(0, \ldots, 0)=\{y: Q(y)+$ $R(y) \leqslant \delta\}$. It will be clear from the proof below that if we shrink the support sufficiently, then $B^{\pi}(0, \ldots, 0) \approx B_{Q}^{\delta}=\{y: Q(y) \leqslant \delta\}$, due to our assumptions on the remainder term $R$.

Let $(n-1) / m=1 / a_{1}+\ldots+1 / a_{n-1}$. Our plan is as follows. We first prove that $\left|B_{Q}^{\delta}\right| \approx \delta^{(n-1) / m}$. Then, we will find a polyhedron of suitable area that contains the set $B_{Q}{ }^{1}$. We shall obtain the polyhedra for all values of $\delta$ by homogeneity.

Going into polar coordinates, $x_{1}=s^{m / a_{1}} \omega_{1}, \ldots, x_{n-1}=s^{m / a_{n-1}}, \quad \omega=$ $\left(\omega_{1}, \ldots, \omega_{n-1}\right) \in S^{n-2}$, we see that
$\int_{B_{Q}^{\delta}} d y=\int_{S^{n-2}} \int_{0}^{s^{1 / m} Q^{-1 / m}(\omega)} s^{n-2} d s d \omega=\delta^{(n-1) / m} \int_{S^{n-2}} Q^{-(n-1) / m}(\omega) d \omega=C_{Q} \delta^{(n-1) / m}$.
This proves that $\left|B_{Q}^{\delta}\right| \approx \delta^{(n-1) / m}$.
We now find a box $P_{1}$ with sides parallel to the coordinate axes, such that $B_{Q}^{1} \subset P_{1}$, and $\left|P_{1}\right|=c C_{Q}$, where $c>1$. Let $Q_{P}$ be a mixed homogeneous function
of degree $\left(a_{1}, \ldots, a_{n-1}\right)$ defined by the condition $\left\{y: Q_{P}(y)=1\right\}=\partial P_{1}$, where $\partial P_{1}$ denotes the boundary of $P_{1}$. Let $P_{\delta}$ be the polyhedron such that the boundary $\partial P_{\delta}=\left\{y: Q_{P}(y)=\delta\right\}$. It is not hard to see that $B_{Q}^{\delta} \subset P_{\delta}$. Moreover, $\left|P_{\delta}\right|=$ $c C_{Q} \delta^{(n-1) / m} \approx\left|B_{Q}^{\delta}\right|$ by the calculation made in the previous paragraph. This completes the proof of Theorem 3.

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Department of Matematics
Wright State University - Dayton, Ohio, USA

Pervenuta in Redazione
1l 20 dicembre 1997.

