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SEZIONE SCIENTIFICA BREVI NOTE

A note on a global existence result of R. Conti

AARON STRAUSS (*) (U.S.A.)

Summary. - If $V(t, x) \to \infty$ as $|x| \to \infty$ for each fixed t, and if $\dot{V}(t, x) \leq 0$, then all solutions of x' = f(t, x) exist in the future. This corrects a previous result due to R. Conti.

1. - Main results.

Let $|\cdot|$ denote any norm in Euclidean *n*-space R^n and let R denote R^1 . Consider the ordinary differential equation

(E)
$$x' = f(t, x)$$
 $(' = d/dt)$

where $f: R \times R^n \to R^n$ is continuous. Let (E) have uniqueness, i.e., for each (t_0, x_0) in $R \times R^n$ there is a unique solution $x(t; t_0, x_0)$ of (E), defined in a neighborhood of t_0 , such that $x(t_0; t_0, x_0) = x_0$.

Let I be an interval, possibly unbounded, and let $V: I \times \mathbb{R}^n \to \mathbb{R}$. We say that V is *locally Lipschitz* if it is continuous on $I \times \mathbb{R}^n$ and if for each (t, x) in $I \times \mathbb{R}^n$ there is a neighborhood N of (t, x) and a constant k > 0 such that

$$|V(s, y) - V(s, z)| \le k |y - z|$$

for all (s, y) and (s, z) in $N \cap (I \times R^n)$. Let

$$J = I - \sup I.$$

Define $\dot{V}: J \times R^n \to R$ by

$$\dot{V}(t, x) = \limsup_{h \to 0^+} h^{-1}(V(t+h, x+hf(t, x)) - V(t, x)).$$

(*) Supported by a National Science Foundation postdoctoral fellowship. The author is indebted to Professor ROBERTO CONTI for many helpful discussions regarding this paper. If V is locally LIPSCHITZ on $I \times R^n$, then

$$\dot{V}(t, x) = \limsup_{h \to 0+} h^{-1}(V(t+h, x(t+h; t, x)) - V(t, x))$$

on the set $J \times \mathbb{R}^n$, as is proved in [6, p. 3].

CONTI [1] has stated the following result.

THEOREM 1. - Let $V: R \times R^n \rightarrow R$ be locally Lipschitz. Let

(1)
$$V(t, x) \to \infty \text{ as } |x| \to \infty \text{ for each fixed } t$$
,

and

(2)
$$V(t, x) \leq \varphi(t, V(t, x))$$

Suppose $\varphi: R \times R \to R$ is continuous and for every real t_0 and r_0 the maximal solution $r(t; t_0, r_0)$ of the comparison equation

$$(CE) r' = \varphi(t, r)$$

exists in the future (exists for all $t \ge t_0$). Then every solution of (E) exists in the future.

In the proof, CONTI showed that if. in fact, some solution $x(\cdot)$ of (E) fails to exist in the future. then

$$(3) |x(t)| \to \infty \text{ as } t \to \omega^-$$

for some finite w; hence

(4) $V(t, x(t)) \rightarrow \infty$

as $t \to \omega^-$. Since V(t, x(t)) is a solution of

$$r' \leq \varphi(t, r),$$

it follows that

$$V(t, x(t)) \leq r(t; t_0, V(t_0, x(t_0))).$$

Therefore, from (4), $r(t; t_0, V(t_0, x(t_0))) \rightarrow \infty$ as $t \rightarrow \omega^-$, a contradiction to the existence assumption on (*CE*).

The flaw in this argument is that (3) does not immediately imply (4). This implication is immediate, however, if (1) is replaced by

(1*)
$$V(t, x) \to \infty \text{ as } |x| \to \infty$$

uniformly in t for t in any compact set.

Indeed, Theorem 1 was proved under this stronger hypothesis, using the above argument, by LASALLE and LEFSCHETZ [4, p. 108]. Furthermore, KATO and STRAUSS [3] have shown that if all solutions of (E) exist in the future, then there exists a locally LIP-SCHITZ $V: R \times R^n \to R$ satisfying (1*) and (2). Thus there would seem to exist a natural correspondence between existence in the future on one hand and locally LIPSCHITZ V satisfying (1*) and (2) on the other.

The purpose of this note is threefold: first, to prove that CONTI'S result (Theorem 1) is true; then, to show by an example that a particular V satisfying (1) and (2) need not satisfy (1*), so that KATO and STRAUSS' result shows some other V must satisfy (1*) and (2); and finally, to prove the following theorem, thereby establishing conditions under which (1) and (1*) are equivalent.

THEOREM 2. – Let $V: R \times R^n \rightarrow R$ be locally Lipschitz, let (1) hold, and let

(5)
$$\psi(t, V(t, x)) \leq \dot{V}(t, x) \leq \varphi(t, V(t, x)).$$

Suppose φ and ψ are continuous, all maximal solutions of

 $r' = \psi(t, r)$

exist in the future, and all maximal solutions of

 $r' = \psi(t, r)$

exist in the past. Then all solutions of (E) exist forever (past and future) and V satisfies (1^*) .

REMARK. - KATO and STRAUSS [3] proved a converse to Theorem 2, namely, if all solutions of (E) exist forever, then there exists a locally LIPSCHITZ V satisfying (1^*) and (5). Thus the natural correspondence mentioned earlier is not quite right. The natural correspondences seem to be between existence in the future on one hand and locally LIPSCHITZ V satisfying (1) and (2)on the other, and between existence forever on one hand and locally LIPSCHITZ V satisfying (1^*) and (5) on the other.

2. - Proofs.

PROOF OF THEOREM 1. – Suppose the result does not hold, so that some solution $x(\cdot)$ of (E) fails to exist in the future. This means that

 $|x(t)| \rightarrow \infty$ as $t \rightarrow \omega^{-}$,

436

for some ω . Choose $t_0 < \omega$ sufficiently close to ω that some solution $\tilde{x}(\cdot)$ exists on $[t_0, \omega]$. Let L be the line segment

$$L = \{z_{\lambda} = \lambda \tilde{x}(t_{o}) + (1-\lambda)x(t_{o}) : 0 \leq \lambda \leq 1\},\$$

and let

$$\lambda_* = \inf \{\lambda : x(\omega; t_0, z_u) \text{ is finite for } \lambda < \mu \leq 1\}.$$

From $z_1 = \tilde{x}(t_0)$ and continuous dependence, we see that $0 \le \lambda_* < 1$.

We claim that $x(t; t_0, z_{\lambda_*})$ does not exist on $t_0 \le t \le \omega$. If it did, then $\lambda_* > 0$, and by continuous dependence, $x(\omega; t_0, z)$ would be finite for all z in a neighborhood of z_{λ_*} , contradicting the definition of λ_* . This establishes the claim.

Thus

(6)
$$|x(t; t_0, z)| \rightarrow \infty \text{ as } t \rightarrow \omega_*^-$$

for some $t_0 < \omega_* \le \omega$. If the set

$$B = \{ x(\omega_*; t_0, z_\lambda) : \lambda_* < \lambda \le 1 \}$$

were bounded, we could choose $\lambda_i \rightarrow \lambda_*$ such that

 $x(\omega_*; t_0, z_{\lambda_0}) \rightarrow v$

for some $v \in R^n$. By continuous dependence and (6),

(7)
$$|x(t_{0}; t_{0}, z_{\lambda_{0}})| \rightarrow \infty$$

for some sequence $t_i \rightarrow \omega_*^{-}$. By local existence at (ω_*, v) , the solution $x(t; \omega_*, v)$ exists on $\omega_* - \varepsilon \leq t \leq \omega_*$ for some $\varepsilon > 0$. Therefore by continuous dependence

$$x(t_i; t_0, z_{\lambda_i}) = x(t_i; \omega_*, x(\omega_*; t_0, z_{\lambda_i})) \rightarrow v,$$

contradicting (7). Hence B is unbounded.

Thus we can choose $x_i \in B$ such that $|x_i| \to \infty$, and

$$oldsymbol{x}_i = oldsymbol{x}(\omega_*; \ oldsymbol{t}_0, \ oldsymbol{z}_{\lambda_i})$$

for some $\lambda_* < \lambda_i \leq 1$. From (1)

(8)
$$V(\omega_*, x(\omega_*; t_0, z_{i_0})) \to \infty \text{ as } i \to \infty.$$

Let $m_i(t) = V(t, x(t; t_0, z_{i_i}))$ for $t_0 \leq t \leq \omega_*$.

Since the line segment L is compact and V is continuous,

$$r_0 = \sup \{V(t_0, z) : z \in L\}$$

is finite. Then the maximal solution $r(t: t_0, r_n)$ of (CE) exists in the future. Now $m_i(\cdot)$ is a solution of the differential inequality

$$r' \leq \varphi(t, r)$$

(in the upper right-and derivative sense) and $m_i(t_0) \le r_0$ for all *i* Therefore (see [2, p. 26] or [5, Theorem 9.5 and Remark 9.3])

$$m_{i}(t) \leq \varphi(t; t_{0}, r_{0})$$

for all $t_0 \leq t \leq \omega_*$ and all *i*, a contradiction to (8) at $t = \omega_*$. This proves Theorem 1.

The following result can easily be proved with analogous arguments. It should be noted that \dot{V} is still an upper right-hand derivative (see [5, Theorem 9.6]).

COROLLARY. - Let $V: R \times R^n \rightarrow R$ be locally Lipschitz and satisfy (1) and

$$\dot{V}(t, x) \geq \psi(t, V(t, x)).$$

Suppose $\psi: R \times R \to R$ is continuous and for every real t_{u} and r_{0} the maximal solution $\rho(t; t_{0}, r_{0})$ of $r' = \psi(t, r)$ exists in the past. Then every solution of (E) exists in the past.

In the example below we construct a locally LIPSCHITZ function V satisfying (1) and (2), but not (1^*) .

EXAMPLE. - Consider (E) where $f(t, x) = -x_{\perp}x_{\perp}$ for x real. Since f is continuously differentiable, (E) has uniqueness. Furthermore, all solutions exist in the future (although not in the past) and all tend to zero as $t \to \infty$. In fact

(9)
$$x(s; t, y) = \begin{cases} y(y(s-t)+1)^{-1} & \text{if } y \ge 0, \\ -y(y(s-t)-1)^{-1} & \text{if } y < 0. \end{cases}$$

We define V on $[0, 1] \times R$ by

(10)
$$V(t, y) = \begin{cases} (x(1; t, y) - 1)^{s}(1 - t)(y^{4} + 2y^{3}) + x^{t}(1; t, y) \\ \text{if } 0 < t < 1 \text{ and } y > 0, \\ y^{2} \text{ elsewhere on } [0, 1] \times R. \end{cases}$$

438

Using (9), we have

(11)
$$V(t, y) = \begin{cases} [(yt-1)^2(1-t)(y^4+2y^3) + y^4][y(1-t)+1]^{-2} \\ & \text{if } 0 < t < 1 \text{ and } y > 0, \\ y^2 \text{ elsewhere on } [0, 1] \times R. \end{cases}$$

Using (11), we see that $V(t, y) \to \infty$ as $|y| \to \infty$ for each fixed t, hence (1) holds. However

$$V(t, t^{-1}) \equiv 1$$
 for $0 < t < 1$.

Thus $V(t, y) \rightarrow \infty$ as $|y| \rightarrow \infty$ non-uniformly in t for $t \in [0, 1]$, so that (1^*) does not hold.

Clearly $\partial V/\partial y$ is continuous on $(0, 1) \times R$ and V is continuous on $[0, 1] \times R$. Furthermore, by a long but straightforward computation, $\partial V/\partial y$ is continuous on $[0, 1] \times R$. Thus V is locally LIP-SCHITZ there. Therefore we may compute \dot{V} on $[0, 1] \times R$ by taking the (upper right-hand) derivative of V(s, x(s)).

Let $0 \le t < 1$ and $y \in R$. If $y \le 0$, then for s > t,

$$V(s, x(s; t, y)) = x^{i}(s; t, y) \leq y^{2}.$$

Therefore

$$\dot{V}(t, y) \leq 0.$$

If y > 0, then using (10) for s > t, we have

$$V(s, x(s; t, y)) = x^{2}(1; t, x) + (x(1; t, y) - 1)^{2}(1 - s)(x^{4}(s; t, y) + 2x^{3}(s; t, y)).$$

Thus, from (E),

$$\begin{split} \dot{V}(t, y) &= \frac{d}{ds} V(s, x(s; t, y))|_{s=t} = \\ &= -(x(1; t, y) - 1)^2 (y^4 + 2y^3) - \\ &- (x(1, t, y) - 1)^2 (1 - t) (4y^5 + 6y^4) \le 0, \end{split}$$

so that $\dot{V}(t, y) \leq 0$ for all (t, y) in $[0, 1) \times R$.

Now we extend V to $R \times R$ by periodicity, i.e., so that

$$V(t+1, y) = V(t, y)$$

for all real t and y. Then V and $\partial V/\partial y$ are continuous on $R \times R$, hence V is locally LIPSCHITZ there. Furthermore, (1) holds but

(1*) fails for t in any compact interval of length greater than one. Since in this example (E) is autonomous, the solutions on [i, i + 1) are merely translates of those on [0, 1) for every i = 1, 2, ...,. Hence

$$\dot{V}(t, y) \leq 0$$

on $R \times R$. Thus (2) holds with $\varphi \equiv 0$.

REMARK. – In the above example we defined V to have period t for convenience. The same type of construction can be used to prove that given any $\alpha > 0$, there exists a locally LIPSCHITZ V_{α} satisfying (1) and (2), but not satisfying (1*) on any compact interval of length greater than α . Thus the following question arises: is there a locally LIPSCHITZ V satisfying (1) and (2) such that (1*) fails on every compact interval of positive length? This question remains open.

PROOF OF THEOREM 2. – Because of Theorem 1 and its corollary, we need only prove that such V satisfy (1*). Suppose there were a locally LIPSCHITZ V satisfying (1) and (5) but not (1*). Then there exist M > 0, t_0 real, and sequences $|x_i|$ and $|t_i|$ such that $|x_i| \rightarrow \infty$, $t_i \rightarrow t_0$ monotonically, and

 $V(t_1, x_1) \leq M.$

We shall assume $t_i \nearrow t_0$ and use the second inequality of (5); if it were the case that $t_i \searrow t_0$ we would use the first.

Since the solution $x(t; t_i, x_i)$ exists in the future for every i, we see that

$$x(t_0, t_i, x_i) \equiv y_i$$

is finite. The sequence $|y_i|$ is unbounded by the same argument as that used to prove B is unbounded in the proof of Theorem 1. Thus we may assume that $|y_i| \to \infty$ as $i \to \infty$. Therefore

(12)
$$V(t_0, y_i) \to \infty \text{ as } i \to \infty.$$

Let $m_i(t) = V(t, x(t; t_i, x_i))$ for $t_i \leq t \leq t_0$. Then $m_i(t_i) \leq M$ for every *i*. Now φ is bounded on the square

$$|(t, r): |t - t_0| \le 1, |r - M| \le 1$$

and $m_i(\cdot)$ is a solution (in the upper right-hand derivative sense) of

$$r' \leq \varphi(t, r)$$
.

440

for $t_i \leq t \leq t_0$. Thus, by comparison with solutions of $r' = \varphi(t, r)$, there exists Q > 0 such that $m_i(t) \leq Q$ for all *i* and $t_i \leq t \leq t_0$. This contradicts (12) at $t = t_0$, completing the proof.

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