# Rendiconti Lincei Matematica E Applicazioni 

## Lucio Boccardo <br> Positive solutions for some quasilinear elliptic equations with natural growths

Atti della Accademia Nazionale dei Lincei. Classe di Scienze Fisiche, Matematiche e Naturali. Rendiconti Lincei. Matematica e Applicazioni, Serie 9, Vol. 11 (2000), n.1, p. 31-39.

Accademia Nazionale dei Lincei
[http://www.bdim.eu/item?id=RLIN_2000_9_11_1_31_0](http://www.bdim.eu/item?id=RLIN_2000_9_11_1_31_0)

L'utilizzo e la stampa di questo documento digitale è consentito liberamente per motivi di ricerca e studio. Non è consentito l'utilizzo dello stesso per motivi commerciali. Tutte le copie di questo documento devono riportare questo avvertimento.

> Articolo digitalizzato nel quadro del programma
> bdim (Biblioteca Digitale Italiana di Matematica)
> SIMAI \& UMI
> http://www.bdim.eu/

Atti della Accademia Nazionale dei Lincei. Classe di Scienze Fisiche, Matematiche e Naturali. Rendiconti Lincei. Matematica e Applicazioni, Accademia Nazionale dei Lincei, 2000.

Equazioni a derivate parziali. - Positive solutions for some quasilinear elliptic equations with natural growths. Nota di Lucio Boccardo, presentata (*) dal Socio S. Spagnolo.

Авstract. - We shall prove an existence result for a class of quasilinear elliptic equations with natural growth. The model problem is

$$
\begin{cases}-\operatorname{div}\left(\left(1+|u|^{r}\right) \nabla u\right)+|u|^{m-2} u|\nabla u|^{2}=f & \text { in } \Omega \\ u=0 & \text { on } \partial \Omega .\end{cases}
$$

Key words: Quasilinear elliptic equations; Natural growth coefficients; Euler-Lagrange equations.

Riassunto. - Soluzioni positive per alcune equazioni ellittiche con crescite naturali. È provato un teorema di esistenza di soluzioni per una classe di equazioni ellittiche quasi-lineari, con coefficienti a crescite naturali (come suggerito dal Calcolo delle variazioni). Il problema modello è il seguente

$$
\begin{cases}-\operatorname{div}\left(\left(1+|u|^{r}\right) \nabla u\right)+|u|^{m-2} u|\nabla u|^{2}=f & \text { in } \Omega \\ u=0 & \text { su } \partial \Omega .\end{cases}
$$

## 1. Introduction

It is well known that the minimization in $W_{0}^{1,2}(\Omega)$ ( $\Omega$ is a bounded domain in $\mathbb{R}^{N}$ ) of simple functionals like

$$
I(v)=\frac{1}{2} \int_{\Omega} a(x, v)|\nabla v|^{2}-\int_{\Omega} f(x) v(x),
$$

where $a$ is a bounded, smooth function and $f \in L^{2}(\Omega)$, leads to the following EulerLagrange equation

$$
\begin{cases}-\operatorname{div}(a(x, u) \nabla u)+\frac{1}{2} a^{\prime}(x, u)|\nabla u|^{2}=f & \text { in } \Omega  \tag{1}\\ u=0 & \text { on } \partial \Omega\end{cases}
$$

(for a direct study of the existence of bounded solutions of boundary value problems of type (1), if $f \in L^{q}(\Omega), q>\frac{N}{2}$, see [8]). Recall that the functional $I$ is not Gateauxdifferentiable. It is only differentiable along directions of $W_{0}^{1,2}(\Omega) \cap L^{\infty}(\Omega)$ (see [11]). Moreover, if we consider

$$
J(v)=\frac{1}{2} \int_{\Omega}\left(1+|v|^{m}\right)|\nabla v|^{2}-\int_{\Omega} f(x) v(x), \quad m>1
$$

(*) Nella seduta del 12 novembre 1999.
the Euler-Lagrange equation is

$$
\begin{cases}-\operatorname{div}\left(\left(1+|u|^{m}\right) \nabla u\right)+\frac{m}{2}|u|^{m-2} u|\nabla u|^{2}=f & \text { in } \Omega \\ u=0 & \text { on } \partial \Omega .\end{cases}
$$

Remark that the direct study of Dirichlet problems similar to the previous one, like

$$
u \in W_{0}^{1,2}(\Omega):-\operatorname{div}\left(\left(1+|u|^{m}\right) \nabla u\right)+|u|^{r-2} u|\nabla u|^{2}=f \in L^{2}(\Omega)
$$

( $m>0, r>1$ ) gives some difficulties, due to the fact that now the boundary value problems may not be the Euler-Lagrange equation of some functional and that, even if $m=0, u$ may be unbounded. The first difficulty is due to the fact that the principal part of the differential operator $-\operatorname{div}\left(\left(1+|v|^{m}\right) \nabla v\right)$ is not well defined on the whole $W_{0}^{1,2}(\Omega)$. The second and main one is that the lower order term $|v|^{r-2} v|\nabla v|^{2}$ not only is not well defined on the whole $W_{0}^{1,2}(\Omega)$, but, even if $v \in L^{\infty}(\Omega) \cap W_{0}^{1,2}(\Omega)$, $|v|^{r-2} v|\nabla v|^{2}$ does not belong to $W^{-1,2}(\Omega)$. However, the lower order term has the nice property that $v \cdot\left(|v|^{r-2} v|\nabla v|^{2}\right) \geq 0$; a generalization of this fact will be assumption (6), below.

In a more general setting, we will study here the Dirichlet problem

$$
\begin{equation*}
u \in W_{0}^{1,2}(\Omega):-\operatorname{div}(a(x, u) \nabla u)+g(x, u, \nabla u)=f . \tag{2}
\end{equation*}
$$

On the right hand side $f$ we assume that

$$
\begin{gather*}
f \in L^{2}(\Omega)  \tag{3}\\
f \geq 0 \tag{4}
\end{gather*}
$$

Moreover $a(x, s): \Omega \times \mathbb{R} \times \mathbb{R}^{N} \rightarrow \mathbb{R}, g(x, s, \xi): \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ are functions which are measurable with respect to $x$ and continuous with respect to $(s, \xi)$, such that

$$
\begin{gather*}
0<\alpha \leq a(x, s) \leq \beta(s)  \tag{5}\\
g(x, s, \xi) s \geq 0  \tag{6}\\
|g(x, s, \xi)| \leq \gamma(s)\left(h(x)+|\xi|^{2}\right), \tag{7}
\end{gather*}
$$

where $\beta, \gamma$ are continuous, increasing (possibly unbounded) functions of a real variable and $h(x)$ is a given nonnegative function in $L^{1}(\Omega)$.

Contributions to the existence and nonexistence of solutions of (2), if the dependence on $u$ of the principal part is bounded, can be found in $[2,7,6,9,10,12]$.

We refer to $[5,6,15]$ for the existence of solutions of (2) if the right hand side belongs to $L^{1}(\Omega)$.

Other developments and general existence results are contained in [14].
The results of this paper have been presented in [3].
The results are quite easy to prove thanks to assumption (4), but the linearity with respect to the gradient of the principal part of the differential operator is never used. Moreover we want to underline that we cannot expect that the presence of the term
$\beta(u)$ can have a regularizing effect on the solution, because $a(x, s)$ is controlled by $\beta(s)$ only from above (see (5)); observe that, conversely, the assumption

$$
\begin{equation*}
0<\alpha \beta(s) \leq a(x, s) \leq \beta(s) \tag{8}
\end{equation*}
$$

lies that $\beta(u) \nabla u \in L^{2}(\Omega)$, while, under our assumption (5), we will not even be able to prove that $\beta(u) \nabla u \in L^{1}(\Omega)$. Indeed (formally) the use of $B(u)$ as test function (where $\left.B(s)=\int_{0}^{s} \beta(t) d t\right)$ in (2) implies

$$
c_{0}\left(\int_{\Omega}|B(u)|^{2^{*}}\right)^{\frac{2}{2^{*}}} \leq \alpha \int_{\Omega} \beta(u)^{2}|\nabla u|^{2} \leq \int_{\Omega} f B(u) \leq\|f\|_{L^{\frac{2 N}{N+2}(\Omega)}}\|B(u)\|_{L^{2^{*}}(\Omega)}
$$

Observe also that the stronger assumption $f \in L^{q}(\Omega), q>\frac{N}{2}$, implies thanks to (6) that $u$ is bounded, so that the existence of bounded solutions follows from the general results of [8].

## 2. Approximation

The existence of a solution of the Dirichlet problem (2) will be proved by approximation. Our techniques will follow those of [2, 4].

Define

$$
g_{n}(x, s, \xi)=\frac{g(x, s, \xi)}{1+\frac{1}{n}|g(x, s, \xi)|}
$$

and

$$
a_{n}(x, s)=a\left(x, T_{n}(s)\right)
$$

where

$$
T_{n}(s)= \begin{cases}s & \text { if }|s| \leq n \\ \frac{s n}{|s|} & \text { if }|s|>n\end{cases}
$$

Consider the approximate Dirichlet problems

$$
\begin{equation*}
u_{n} \in W_{0}^{1,2}(\Omega):-\operatorname{div}\left(a_{n}\left(x, u_{n}\right) \nabla u_{n}\right)+g_{n}\left(x, u_{n}, \nabla u_{n}\right)=f . \tag{9}
\end{equation*}
$$

Thanks to the boundedness of $a_{n}(x, s)$ and $g_{n}(x, s, \xi)$, the existence of a solution $u_{n}$ (which is positive thanks to (4) and (6)) of the boundary value problem (9) is a classical result of nonlinear elliptic equations (see [13]).

The assumptions (5), (6) and the use of $u_{n}$ as test function in (9) imply the following lemma.

Lemma 2.1. There exists a positive constant $c_{1}$ such that

$$
\begin{gather*}
\int_{\Omega} a_{n}\left(x, u_{n}\right) \nabla u_{n} \nabla u_{n} \leq c_{1},  \tag{10}\\
\left\|u_{n}\right\|_{W_{0}^{1,2}(\Omega)} \leq \frac{c_{1}}{\alpha},  \tag{11}\\
\int_{\Omega} u_{n} g_{n}\left(x, u_{n}, \nabla u_{n}\right) \leq c_{1} . \tag{12}
\end{gather*}
$$

Thus there exist a positive function $u \in W_{0}^{1,2}(\Omega)$ and a subsequence of $\left\{u_{n}\right\}$ (still denoted by $\left.\left\{u_{n}\right\}\right)$ such that $u_{n}$ converges to $u$ weakly in $W_{0}^{1,2}(\Omega)$ and strongly in $L^{2}(\Omega)$.

This section is devoted to the proof of the strong convergence of $u_{n}$ to $u$ in $W_{0}^{1,2}(\Omega)$.
Define

$$
G_{k}(v)=v-T_{k}(v) .
$$

The use of $G_{k}\left(u_{n}\right)$ as test functions in (9) imply, thanks to the fact that $f \in L^{2}(\Omega)$, the following lemma.

Lemma 2.2. There exists a positive constant $c_{2}$ such that

$$
\begin{equation*}
\int_{\left\{x \in \Omega: u_{n}(x) \geq k\right\}}\left|\nabla u_{n}\right|^{2} \leq c_{2} \int_{\left\{x \in \Omega: u_{n}(x) \geq k\right\}}|f|^{2} . \tag{13}
\end{equation*}
$$

Now we study the behaviour of the positive part of $u_{n}-T_{b}(u)$.
Lemma 2.3. For any $\epsilon>0$, there exists $h_{\epsilon}$ such that

$$
\limsup _{n \rightarrow \infty}\left\|\left[u_{n}-T_{b_{\epsilon}}(u)\right]^{+}\right\|_{W_{0}^{1,2}(\Omega)} \leq 2 \epsilon,
$$

and

$$
\left\|u-T_{h_{\epsilon}}(u)\right\|_{W_{0}^{1,2}(\Omega)} \leq \epsilon .
$$

Proof. Since $u$ is positive, on the subset $\left\{x \in \Omega: k \leq u_{n}(x)-T_{b}(u(x))\right\}$, it is $u_{n}(x) \geq k$. Therefore

$$
\begin{aligned}
& \int_{\Omega}\left|\nabla G_{k}\left[u_{n}-T_{h}(u)\right]^{+}\right|^{2}=\int_{\left\{x \in \Omega: k \leq u_{n}(x)-T_{h}(u(x))\right\}}\left|\nabla\left[u_{n}-T_{h}(u)\right]\right|^{2} \leq \\
& \leq 2 \int_{\left\{x \in \Omega: k \leq u_{n}(x)\right\}}\left|\nabla u_{n}\right|^{2}+2 \int_{\left\{x \in \Omega: k \leq u_{n}(x)\right\}}|\nabla u|^{2} .
\end{aligned}
$$

Thus, thanks to Lemma 2.2, we get the following inequality

$$
\begin{equation*}
\int_{\Omega}\left|\nabla G_{k}\left[u_{n}-T_{b}(u)\right]^{+}\right|^{2} \leq \int_{\left\{x \in \Omega: k \leq u_{n}(x)\right\}}\left\{c_{2}|f|^{2}+|\nabla u|^{2}\right\} . \tag{14}
\end{equation*}
$$

The previous inequality implies, since the measure of the set $\left\{u_{n}(x) \geq k\right\}$ tends to zero as $k$ tends to infinity, uniformly in $n$, that, if we fix $\epsilon>0$, there exists $k_{\epsilon}>0$ such that, for every $n$ in $\mathbb{N}$, and for every $h>0$,

$$
\begin{equation*}
\int_{\Omega}\left|\nabla G_{k_{\epsilon}}\left[u_{n}-T_{b}(u)\right]^{+}\right|^{2} \leq \epsilon \tag{15}
\end{equation*}
$$

The use of $T_{k_{\epsilon}}\left[u_{n}-T_{b}(u)\right]^{+}$(for any $h>0$ ) as test function in (9) and the assumption (6) imply that

$$
\begin{equation*}
\int_{\Omega}\left|\nabla T_{k_{e}}\left[u_{n}-T_{b}(u)\right]^{+}\right|^{2} \leq c_{3} \int_{\Omega} f T_{k_{e}}\left(G_{b}(u)\right)+\epsilon_{n} \tag{16}
\end{equation*}
$$

for some positive constant $c_{3}$, where $\epsilon_{n} \rightarrow 0$.

Now we choose $h_{\epsilon}$ such that (for $n>n_{\epsilon}$ )

$$
\int_{\Omega}\left|\nabla T_{k_{\epsilon}}\left[u_{n}-T_{h_{\epsilon}}(u)\right]^{+}\right|^{2}, \quad\left\|u-T_{h_{\epsilon}}(u)\right\|_{W_{0}^{1,2}(\Omega)} \leq \epsilon
$$

The fact that $\left\|u-T_{h_{e}}(u)\right\|_{W_{0}^{1,2}(\Omega)} \leq \epsilon$ follows from the fact that $u$ belongs to $W_{0}^{1,2}(\Omega)$.
Now we study the behaviour of the negative part of $u_{n}-T_{b_{\epsilon}}(u)$.
Define

$$
\varphi_{\lambda}(s)=s e^{\lambda s^{2}}, \quad \lambda=\lambda\left(h_{\epsilon}\right)=\frac{\gamma\left(h_{\epsilon}\right)^{2}}{\alpha^{2}} .
$$

Even if the principal part of the differential operator is unbounded with respect to $u$ the following lemma, proved in [2], still holds. Remark that, since $u$ is positive, $\left\{x \in \Omega: u_{n}(x)-T_{b}(u(x)) \leq 0\right\}=\left\{x \in \Omega: 0 \leq u_{n}(x) \leq T_{b}(u(x))\right\}$.

Lemma 2.4. The use of $\varphi_{\lambda}\left(\left[u_{n}-T_{b}(u)\right]^{-}\right)$as test function in (9) implies that

$$
\begin{equation*}
\lim _{n \rightarrow \infty} \int_{\Omega}\left|\nabla\left[u_{n}-T_{b}(u)\right]^{-}\right|^{2}=0 \tag{17}
\end{equation*}
$$

for any $h>0$.
Thus we have the following result.
Proposition 2.5. The use of Proposition 2.3 and Lemma 2.4 implies that the sequence $\left\{u_{n}\right\}$ converges strongly to $u$ in $W_{0}^{1,2}(\Omega)$.

Proof. We have

$$
\begin{aligned}
& \left\|u_{n}-u\right\|_{W_{0}^{1,2}(\Omega)} \leq \\
& \quad \leq\left\|\left[u_{n}-T_{h}(u)\right]^{+}\right\|_{W_{0}^{1,2}(\Omega)}+\left\|\left[u_{n}-T_{b}(u)\right]^{-}\right\|_{W_{0}^{1,2}(\Omega)}+\left\|T_{h}(u)-u\right\|_{W_{0}^{1,2}(\Omega)} .
\end{aligned}
$$

## 3. Existence

We have proved that

$$
u_{n} \rightarrow u \text { strongly in } W_{0}^{1,2}(\Omega) .
$$

Thus (again for some subsequence) we have that

$$
\begin{equation*}
\nabla u_{n}(x) \rightarrow \nabla u(x), \text { almost everywhere in } \Omega . \tag{18}
\end{equation*}
$$

In order to pass to the limit in (9) we need the $L^{1}$ compactness of the sequence $g_{n}\left(x, u_{n}, \nabla u_{n}\right)$ proved (see again [2]) in the following lemma, by means of Proposition 2.5 and (12).

Lemma 3.1. The sequence $g_{n}\left(x, u_{n}, \nabla u_{n}\right)$ converges in $L^{1}(\Omega)$ to $g(x, u, \nabla u)$.

Observe that, even if we have both (11) and the fact that $u_{n}$ converges strongly to $u$ in $W_{0}^{1,2}(\Omega)$, we are not able to say that the sequence $a_{n}\left(x, u_{n}\right) \nabla u_{n}$ converges in $L^{1}(\Omega)$ to $a(x, u) \nabla u$. So, in order to pass to limit in (9), we will use the approach of [1].

We use in (9) $T_{k}\left[u_{n}-\varphi\right]$ as test function, where $\varphi \in W_{0}^{1,2}(\Omega) \cap L^{\infty}(\Omega)$. We can then pass to the limit, thanks to Proposition 2.5 and Lemma 3.1, and we obtain our main result.

Theorem 3.2. There exists a solution $u$ of (2) in the following sense

$$
\left\{\begin{array}{l}
u \in W_{0}^{1,2}(\Omega), \quad g(x, u, \nabla u) \in L^{1}(\Omega)  \tag{19}\\
\int_{\Omega} a(x, u) \nabla u \nabla T_{k}[u-\varphi]+\int_{\Omega} g(x, u, \nabla u) T_{k}[u-\varphi]=\int_{\Omega} f T_{k}[u-\varphi] \\
\forall \varphi \in W_{0}^{1,2}(\Omega) \cap L^{\infty}(\Omega), \quad \forall k>0
\end{array}\right.
$$

Remark 3.3. We point out that, in the previous equality, any term is well defined: in the second and the third integral $g(x, u, \nabla u), f \in L^{1}(\Omega)$ and $T_{k}[u-\varphi] \in L^{\infty}(\Omega)$; in the first $\nabla T_{k}[u-\varphi]$ is not zero on the subset $\{x \in \Omega: \varphi(x)-k \leq u(x) \leq \varphi(x)+k\}$, that is in a subset where $u$ (and also $a(x, u))$ is bounded.

We repeat (see Introduction) that under our assumption (5), we are not able to prove that $a(x, u) \nabla u \in L^{1}(\Omega)$, so that the usual definition of weak solution

$$
\int_{\Omega} a(x, u) \nabla u \nabla \varphi+\int_{\Omega} g(x, u, \nabla u) \varphi=\int_{\Omega} f \varphi, \quad \forall \varphi \in W_{0}^{1,2}(\Omega) \cap L^{\infty}(\Omega)
$$

does not make sense and thus the previous definition of solution is useful.
Corollary 3.4. Choosing $\varphi=0$ in (19), letting $k$ tend to infinity, and using Fatou Lemma implies that

$$
\begin{align*}
& a(x, u) \nabla u \nabla u \in L^{1}(\Omega)  \tag{20}\\
& u g(x, u, \nabla u) \in L^{1}(\Omega) \tag{21}
\end{align*}
$$

Remark 3.5. If $a(x, u) \nabla u \in L^{2}(\Omega)$ (see Introduction and (8)), we take in (19) $\varphi=G_{b}(u)-\psi, \psi \in W_{0}^{1,2}(\Omega) \cap L^{\infty}(\Omega)$, and we pass to limit (for $h \rightarrow \infty$ ), thanks to Lebesgue Theorem and (20). Thus if $a(x, u) \nabla u \in L^{2}(\Omega)$ we deduce the existence of usual weak solutions

$$
\int_{\Omega} a(x, u) \nabla u \nabla \psi+\int_{\Omega} g(x, u, \nabla u) \psi=\int_{\Omega} f \psi, \quad \forall \psi \in W_{0}^{1,2}(\Omega) \cap L^{\infty}(\Omega)
$$

4. $L^{1}(\Omega)$ Right hand side

Our approach can also be adapted to the case of $L^{1}$ right hand side, using some techniques of [5], but we need a slightly stronger assumption on $g(x, s, \xi)$.

In this section, we assume again (4), (5), (7) and the following (22), (23).

There exist $\sigma \geq 0, \lambda>0$ such that

$$
\begin{equation*}
|g(x, s, \xi)| \geq \lambda|\xi|^{2} \tag{22}
\end{equation*}
$$

when $|s| \geq \sigma$, and

$$
\begin{equation*}
0 \leq f \in L^{1}(\Omega) \tag{23}
\end{equation*}
$$

Consider now the approximate Dirichlet problems

$$
\begin{equation*}
u_{n} \in W_{0}^{1,2}(\Omega):-\operatorname{div}\left(a_{n}\left(x, u_{n}\right) \nabla u_{n}\right)+g_{n}\left(x, u_{n}, \nabla u_{n}\right)=f_{n} \tag{24}
\end{equation*}
$$

where $a_{n}(x, s), g_{n}(x, s, \xi)$ are defined in Section 2 and $f_{n}$ is a sequence of smooth functions converging to $f$ in $L^{1}(\Omega)$.

The use in (24) of the test function $T_{k}\left(u_{n}\right)$ yields for any $k>0$ (see [5], if necessary),

$$
\begin{gathered}
\int_{\Omega}\left|\nabla T_{k}\left(u_{n}\right)\right|^{2} \leq \int_{\Omega} f_{n} T_{k}\left(u_{n}\right) \leq c_{4} k, \\
k \int_{\left\{x \in \Omega: u_{n}(x)>k\right\}} g_{n}\left(x, u_{n}, \nabla u_{n}\right) \leq \int_{\Omega} f_{n} T_{k}\left(u_{n}\right) \leq c_{4} k .
\end{gathered}
$$

In particular, the choice $k=\sigma$ implies that

$$
\int_{\left\{x \in \Omega: u_{n}(x)>\sigma\right\}}\left|\nabla u_{n}\right|^{2}+\int_{\left\{x \in \Omega: u_{n}(x)>\sigma\right\}}\left|\nabla u_{n}\right|^{2} \leq c_{5} .
$$

Thus again there exist a positive function $u \in W_{0}^{1,2}(\Omega)$ and a subsequence of $\left\{u_{n}\right\}$ (still denoted by $\left\{u_{n}\right\}$ ) such that $u_{n}$ converges to $u$ weakly in $W_{0}^{1,2}(\Omega)$ and strongly in $L^{2}(\Omega)$.

The use of $T_{1}\left(G_{k}\left(u_{n}\right)\right)$ as test function in (24) implies that, for any $k>0$,

$$
\int_{\left\{x \in \Omega: k+1 \leq u_{n}(x)\right\}} g_{n}\left(x, u_{n}, \nabla u_{n}\right) \leq \int_{\left\{x \in \Omega: k \leq u_{n}(x)\right\}}|f|,
$$

so that the choice $k \geq \sigma$ gives the following lemma.
Lemma 4.1.

$$
\begin{equation*}
\int_{\left\{x \in \Omega: k+1 \leq u_{n}(x)\right\}}\left|\nabla u_{n}\right|^{2} \leq \int_{\left\{x \in \Omega: k \leq u_{n}(x)\right\}}|f| . \tag{25}
\end{equation*}
$$

Thanks to the use of Lemma 4.1 instead of Lemma 2.2, Lemma 2.3 still holds. Lemma 2.4 holds even if the right hand side belongs to $L^{1}(\Omega)$. Remark that the test function of Lemma 2.4 is uniformly bounded in $L^{\infty}(\Omega)$ by $\varphi_{\lambda}(2 h)$. Thus, also in this case, the sequence $\left\{u_{n}\right\}$ strongly converges to $u$ in $W_{0}^{1,2}(\Omega)$ and (again for some subsequence) we have (18).

In order to pass to the limit in (24), we also need the following lemma.
Lemma 4.2. The sequence $g_{n}\left(x, u_{n}, \nabla u_{n}\right)$ converges in $L^{1}(\Omega)$ to $g(x, u, \nabla u)$.

Proof. We prove that $g_{n}\left(x, u_{n}, \nabla u_{n}\right)$ is uniformly equiintegrable. For any measurable subset $E$ of $\Omega$ and for any $m \in \mathbb{R}^{+}$we have

$$
\begin{aligned}
& \int_{E} g_{n}\left(x, u_{n}, \nabla u_{n}\right)=\int_{\left\{x \in E: 0 \leq u_{n}(x)<m\right\}} g_{n}\left(x, u_{n}, \nabla u_{n}\right)+\int_{\left\{x \in \Omega: m \leq u_{n}(x)\right\}} g_{n}\left(x, u_{n}, \nabla u_{n}\right) \leq \\
& \leq \int_{E} \gamma(m)\left[h(x)+\left|\nabla u_{n}\right|^{2}\right]+\int_{\left\{x \in \Omega: m \leq u_{n}(x)\right\}}|f|,
\end{aligned}
$$

which proves the uniform equiintegrability of $g_{n}\left(x, u_{n}, \nabla u_{n}\right)$. In view of (18) we thus have $g_{n}\left(x, u_{n}, \nabla u_{n}\right) \rightarrow g(x, u, \nabla u)$ strongly in $L^{1}(\Omega)$.

So it is now easy to pass to the limit in (24) to obtain that $u$ is a solution. We use again $T_{k}\left[u_{n}-\varphi\right]$ as test function in (24), where $\varphi \in W_{0}^{1,2}(\Omega) \cap L^{\infty}(\Omega)$. So it is now easy to pass to the limit in (24) to obtain that $u$ is a solution and we obtain the following result.

Theorem 4.3. Assume (4), (5), (7), (22), (23). There exists a solution u of (2) in the following sense

$$
\left\{\begin{array}{l}
u \in W_{0}^{1,2}(\Omega), \quad g(x, u, \nabla u) \in L^{1}(\Omega),  \tag{26}\\
\int_{\Omega} a(x, u) \nabla u \nabla T_{k}[u-\varphi]+\int_{\Omega} g(x, u, \nabla u) T_{k}[u-\varphi]=\int_{\Omega} f T_{k}[u-\varphi] \\
\forall \varphi \in W_{0}^{1,2}(\Omega) \cap L^{\infty}(\Omega), \quad \forall k>0 .
\end{array}\right.
$$

Remark 4.4. With respect to Theorem 3.2 we cannot say that in this case $a(x, u) \nabla u \nabla u \in L^{1}(\Omega)$, nor that $u g(x, u, \nabla u) \in L^{1}(\Omega)$.

## Acknowledgements

The author would like to thank Luigi Orsina, Andrea Dall'Aglio and the students of the PhD course of Calcolo delle Variazioni (Roma 1 University, 1996) for several useful discussions on the subject of this paper.

This paper was presented at the Workshop «Models of Continuum Mechanics in Analysis and Engineering», Technische Universität Darmstadt, October 2, 1998.

## References

[1] P. Benilan - L. Boccardo - T. Gallouët - R. Gariepy - M. Pierre - J. L. Vazquez, An L ${ }^{1}$-theory of existence and uniqueness of solutions of nonlinear elliptic equations. Ann. Scuola Norm. Sup. Pisa Cl. Sci., 22, 1995, 241-273.
[2] A. Bensoussan - L. Boccardo - F. Murat, On a nonlinear partial differential equation having natural growth terms and unbounded solution. Ann. Inst. H. Poincaré Anal. Non Linéaire, 5, 1988, 347-364.
[3] L. Boccardo, Calcolo delle Variazioni. Roma 1 University PhD course, 1996.
[4] L. Boccardo, Some nonlinear Dirichlet problems in $L^{1}$ involving lower order terms in divergence form. In: A. Alvino et al. (eds), Progress in elliptic and parabolic partial differential equations (Capri, 1994). Pitman Res. Notes Math. Ser., 350, Longman, Harlow 1996, 43-57.
[5] L. Boccardo - T. Gallouët, Strongly nonlinear elliptic equations having natural growth terms and $L^{1}$ data. Nonlinear Anal., 19, 1992, 573-579.
[6] L. Boccardo - T. Gallouët - L. Orsina, Existence and nonexistence of solutions for some nonlinear elliptic equations. J. Anal. Math., 73, 1997, 203-223.
[7] L. Boccardo - F. Murat - J.-P. Puel, Existence de solutions non bornées pour certaines équations quasilineaires. Portugal. Math., 41, 1982, 507-534.
[8] L. Boccardo - F. Murat - J.-P. Puel, $L^{\infty}$ estimate for some nonlinear elliptic partial differential equations and application to an existence result. SIAM J. Math. Anal., 23, 1992, 326-333.
[9] H. Brezis - F. E. Browder, Some properties of higher order Sobolev spaces. J. Math. Pures Appl., 61, 1982, 245-259.
[10] H. Brezis - L. Nirenberg, Removable singularities for nonlinear elliptic equations. Topol. Methods Nonlinear Anal., 9, 1997, 201-219.
[11] B. Dacorogna, Direct methods in the calculus of variations. Applied Mathematical Sciences, 78. Springer-Verlag, Berlin-New York 1989.
[12] T. Del Vecchio, Strongly nonlinear problems with Hamiltonian having natural growth. Houston J. Math., 16, 1990, 7-24.
[13] J.-L. Lions, Quelques méthodes de résolution des problèmes aux limites non linéaires. Dunod, Paris 1969.
[14] A. Porretta, Some remarks on the regularity of solutions for a class of elliptic equations with measure data. Preprint, Dip. Mat. Roma 1.
[15] A. Porretta, Existence for elliptic equations in $L^{1}$ having lower order terms with natural growth. Preprint, Dip. Mat. Roma 1.

