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Linear elliptic equations with BMO coefficients

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Analisi matematica. — *Linear elliptic equations with BMO coefficients.* Nota di Menita Carozza, Gioconda Moscariello e Antonia Passarelli di Napoli, presentata (*) dal Socio E. Magenes.

ABSTRACT. — We prove an existence and uniqueness theorem for the Dirichlet problem for the equation $\operatorname{div}(a(x)\nabla u)=\operatorname{div} f$ in an open cube $\Omega\subset\mathbb{R}^N$, when f belongs to some $L^p(\Omega)$, with p close to 2. Here we assume that the coefficient a belongs to the space $BMO(\Omega)$ of functions of bounded mean oscillation and verifies the condition $a(x)\geq \lambda_a>0$ for a.e. $x\in\Omega$.

KEY WORDS: Dirichlet problem; Existence and regularity; BMO-space.

RIASSUNTO. — Equazioni lineari ellittiche a coefficienti BMO. Si prova un teorema di esistenza ed unicità per il problema di Dirichlet per l'equazione div $(a(x)\nabla u)=\operatorname{div} f$ in un cubo aperto $\Omega\subset\mathbb{R}^N$, dove f appartiene a $L^p(\Omega)$, con p vicino a 2. Si assume che il coefficiente a appartenga allo spazio $BMO(\Omega)$ delle funzioni ad oscillazione media limitata e verifichi la condizione $a(x)\geq \lambda_n>0$ per q.o. $x\in\Omega$.

1. Introduction

The main objective of this paper is to investigate the existence and uniqueness of solutions $u \in W_o^{1,p}(\Omega)$ of the Dirichlet problem

(1.1)
$$\begin{cases} \operatorname{div}(a(x)\nabla u) = \operatorname{div} f & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega \end{cases}$$

where Ω is an open cube of \mathbb{R}^N , $(N \ge 2)$, f belongs to $L^p(\Omega; \mathbb{R}^N)$, with p close to 2, and a is a function verifying the following assumptions

(i)
$$a(x) \ge \lambda_a > 0$$
 for a.e. $x \in \Omega$

(ii)
$$a(x) \in BMO(\Omega)$$
.

 $BMO(\Omega)$ denotes the space of John and Nirenberg of functions of bounded mean oscillation (for the definition see Section 2 below).

We say that $u \in W_a^{1,p}(\Omega)$ is a solution of problem at (1.1) if u verifies

$$\int_{\Omega} a(x) \nabla u \nabla \varphi = \int_{\Omega} f \nabla \varphi \qquad \forall \varphi \in C_o^{\infty}(\Omega).$$

We establish the following

Theorem A. Under the assumptions (i), (ii), there exists $\varepsilon_o > 0$, depending on λ_o and the BMO-norm of a, such that for every $f \in L^{2-\varepsilon}(\Omega;\mathbb{R}^N)$, $|\varepsilon| < \varepsilon_o$, problem (1.1) admits a

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unique solution $u \in W_a^{1,2-\varepsilon}(\Omega)$ and the following estimate

$$||u||_{W_a^{1,2-\varepsilon}} \le c||f||_{L^{2-\varepsilon}}$$

with $c = c(\lambda_0, ||a||_{BMO}, N)$, holds.

The main tool in the proof of this theorem is an a priori estimate obtained by using the Hodge decomposition in conjunction with a local version of a regularity result of div-curl quantities on the Hardy space \mathcal{H}^1 (see [2] and Proposition 2.5 below).

Let us remark that Theorem A is an extension of a well known result due to Meyers who considered the case when a(x) is bounded (see [6]).

It is worth pointing out that for a(x) bounded, the result of Meyers gives ε which gets small as $||a||_{\infty}$ tends to ∞ . From this point of view Theorem A is somewhat surprising.

2. Definitions and preliminary results

Here and subsequently, Ω is a cube in \mathbb{R}^N . In order to introduce the Hardy space $\mathcal{H}^1(\Omega)$, we consider a function $\varphi \in C_0^{\infty}(\Omega)$ such that $\operatorname{supp} \varphi \subset B_1(0) = \{x \in \mathbb{R}^N : |x| < 1\}$ and $\int \varphi dx = 1$. For every t > 0 we consider the mollifying function $\varphi_t(x) = t^{-n}\varphi(t^{-1}x)$ and given any function $h \in L^1_{loc}(\Omega)$ we set

$$h_{\star}(x) = h \star \varphi_{\star}(x)$$
 for $a.e.$ $x \in \Omega$,

whenever $0 \le t < \operatorname{dist}(x, \partial \Omega)$. Then we define the radial maximal function of f by

$$\mathcal{M}h(x) = \mathcal{M}_{\Omega}h(x) = \sup\{|h_t(x)|; \ 0 < t < \operatorname{dist}(x, \partial\Omega)\}$$

for all $x \in \Omega$. Now, we are in position to give the following

Definition 2.1. The Hardy space $\mathcal{H}^1(\Omega)$ consists of the functions $h \in L^1_{loc}(\Omega)$ such that

(2.1)
$$||h||_{\mathcal{H}^{1}(\Omega)} = ||\mathcal{M}_{\Omega}h(x)||_{L^{1}(\Omega)} < \infty$$

The functional $\|\cdot\|_{\mathcal{H}^1}$ is a norm which makes $\mathcal{H}^1(\Omega)$ a Banach space (see [7, 5]).

Let us remark that the Definition 2.1 does not depend on the choice of the function φ up to equivalence of norms and that if $\Omega = \mathbb{R}^N$ it is the classical definition of $\mathcal{H}^1(\mathbb{R}^N)$.

It is well known that the dual space of $\mathcal{H}^1(\mathbb{R}^N)$ is $BMO(\mathbb{R}^N)$, where

$$BMO(\mathbb{R}^N) = \left\{ g \in L^1_{loc}(\mathbb{R}^n) : \quad ||g|| = \sup_Q \oint_Q |g - g_Q| < \infty \right\}$$

is the space of all functions of bounded mean oscillation.

Definition 2.2. The space $BMO(\Omega)$ is the space of functions $g \in L^1(\Omega)$ such that

$$(2.2) ||g|| = \sup_{Q \subseteq \Omega} \oint_{Q} |g - g_{Q}| + \oint_{\Omega} |g| < \infty.$$

In order to establish our result we need the following

Theorem 2.3. For every $g \in BMO(\Omega)$ there exists a unique $T \in (\mathcal{H}^1(\Omega))'$ such that

(2.3)
$$T(h) = \int_{\Omega} h(x)g(x)dx \quad \text{for all} \quad h \in \mathcal{H}^{1}(\Omega).$$

Conversely, for every $T \in (\mathcal{H}^1(\Omega))'$ there exists a unique $g \in BMO(\Omega)$ which satisfies (2.3). The correspondence $T \to g$ determined by (2.3) is a Banach space isomorphism between $(\mathcal{H}^1(\Omega))'$ and $BMO(\Omega)$.

Proof. See Theorem 2 in [7, p. 223].

It is well known that the space $BMO(\Omega)$ is related to the $L^p(\Omega)$ space, for 0 , by the following continuous embeddings

$$L^{\infty}(\Omega) \hookrightarrow BMO(\Omega) \hookrightarrow L^{p}(\Omega)$$
.

Let us consider two vector fields $E = (E^1, ..., E^n)$ and $B = (B^1, ..., B^n)$ such that

$$\operatorname{curl} E = \left(\frac{\partial E_i}{\partial x_j} - \frac{\partial E_j}{\partial x_i}\right)_{i,j=1,\dots,n} = 0$$

and

$$\operatorname{div} B = \sum_{i=1}^{n} \frac{\partial B_{i}}{\partial x_{i}} = 0.$$

The scalar product of such vector fields enjoy a higher degree of regularity than generic products of arbitrary vector fields. The first result in such direction goes back to the div-curl Lemma due to Murat and Tartar (see [8, 9]) and the subsequent theory of compensated compactness. More recently in [2] the following celebrated result was proved

Theorem 2.4. Let $B \in L^p(\mathbb{R}^N, \mathbb{R}^N)$ and $E \in L^q(\mathbb{R}^N, \mathbb{R}^N)$ where p, q are Hölder conjugate exponents, be two vector fields such that $\operatorname{div} B = 0$ and $\operatorname{curl} E = 0$. Then the scalar product $E \cdot B$ belongs to the Hardy space $\mathcal{H}^1(\mathbb{R}^N)$ and

$$||E \cdot B||_{\mathcal{H}^1} \le c||E||_{L^q}||B||_{L^p}$$

where c is a constant depending only on the dimension N.

From now on it is essential to consider Ω an open cube of \mathbb{R}^N in order to apply a local version of the previous theorem (see [5]), namely

PROPOSITION 2.5. Let $B \in L^p(\Omega, \mathbb{R}^N)$ and $E \in L^q(\Omega, \mathbb{R}^N)$ be two vector fields such that $\operatorname{div} B = 0$ and $\operatorname{curl} E = 0$, where 1/p + 1/q = 1. Then their scalar product $E \cdot B$ belongs to the Hardy space $\mathcal{H}^1(\Omega)$ and

$$||E \cdot B||_{\mathcal{H}^1(\Omega)} \le c||E||_{L^q(\Omega)}||B||_{L^p(\Omega)}$$

where c is a constant depending on the dimension N.

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Finally we recall the following

Theorem 2.6 (Hodge decomposition). Let $w \in W_0^{1,r}(\Omega)$, r > 1 and let $1 - r < \varepsilon < 1$. Then there exist $\psi \in W_0^{1,\frac{r}{1-\varepsilon}}(\Omega)$ and a divergence free vector field $H \in L^{\frac{r}{1-\varepsilon}}(\Omega;\mathbb{R}^N)$ such that

$$|\nabla w|^{-\varepsilon} \nabla w = \nabla \psi + H$$

and

$$\begin{aligned} ||H||_{\frac{r}{1-\varepsilon}} &\leq c_1 |\varepsilon| ||\nabla w||_r^{1-\varepsilon}, \\ ||\nabla \psi||_{\frac{r}{1-\varepsilon}} &\leq c_2 ||\nabla w||_r^{1-\varepsilon} \end{aligned}$$

where $c_i = c_i(N)$.

Proof. See Theorem 3 in [4]. □

3. Proof of Theorem A

Before proving the existence and uniqueness result stated in Theorem A, we have to establish a Lemma which is a refined version of a result contained in [3].

Lemma 3.1. Let us consider the Dirichlet problem

(3.1)
$$\begin{cases} \operatorname{div}(\alpha(x)\nabla u) = \operatorname{div} f & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega \end{cases}$$

where α is a function verifying the following assumptions

$$\begin{aligned} 0 &< \lambda_{\scriptscriptstyle o} \leq \alpha(x) & \text{for a.e. } x \in \Omega \\ \alpha &\in L^{\infty}(\Omega). \end{aligned}$$

Then for every $|\varepsilon| < \varepsilon_o = \frac{\lambda_o}{\widetilde{\varepsilon}||\alpha||_{BMO}} \widetilde{c}$ positive number, and for $f \in L^{2-\varepsilon}(\Omega; \mathbb{R}^N)$ the problem (3.1) admits a unique solution u and the following estimate

$$||u||_{W_o^{1,2-\varepsilon}} \le c||f||_{L^{2-\varepsilon}}$$

with $c = c(\lambda_0$, $||\alpha||_{\mathit{BMO}}$, N), holds.

PROOF. Let $f_j \in L^2(\Omega;\mathbb{R}^N)$ converge to f in $L^{2-\varepsilon}(\Omega;\mathbb{R}^N)$ and u_j be the solution to the problem

$$\left\{ \begin{array}{ll} \operatorname{div}\left(\alpha(x)\nabla u_j\right) = \operatorname{div} f_j & \text{in} \quad \Omega \\ u_j = 0 & \text{on} \quad \partial\Omega . \end{array} \right.$$

By the stability of the Hodge decomposition stated in Theorem 2.6, for every j, k there exist $\psi \in W_o^{1,\frac{2-\varepsilon}{1-\varepsilon}}(\Omega)$ and a divergence free vector field $H \in L^{\frac{2-\varepsilon}{1-\varepsilon}}(\Omega, \mathbb{R}^N)$ such that

$$|\nabla u_i - \nabla u_k|^{-\varepsilon} (\nabla u_i - \nabla u_k) = \nabla \psi + H$$

and

(3.2)

$$||H||_{\frac{2-\varepsilon}{1-\varepsilon}} \le c_1 |\varepsilon| ||\nabla u_j - \nabla u_k||_{2-\varepsilon}^{1-\varepsilon}$$

$$||\nabla \psi||_{\frac{2-\varepsilon}{1-\varepsilon}} \le c_2 ||\nabla u_j - \nabla u_k||_{2-\varepsilon}^{1-\varepsilon}$$

where c_1 , c_2 are constants depending only on N.

From our assumptions it follows that for every j, k

$$\begin{split} \lambda_o \int_{\Omega} |\nabla u_j - \nabla u_k|^{2-\varepsilon} & \leq \int_{\Omega} \langle \alpha(x) (\nabla u_j - \nabla u_k) \,,\, |\nabla u_j - \nabla u_k|^{-\varepsilon} (\nabla u_j - \nabla u_k) \rangle = \\ & = \int_{\Omega} \langle \alpha(x) (\nabla u_j - \nabla u_k) \,,\, \nabla \psi + H \rangle = \\ & = \int_{\Omega} (f_j - f_k) \nabla \psi + \int_{\Omega} \alpha(x) \langle \nabla u_j - \nabla u_k \,,\, H \rangle = I + II. \end{split}$$

To estimate I, it suffices to apply Hölder inequality and (3.2) to get

To estimate II we observe that since $\operatorname{div} H = 0$ and $\operatorname{curl}(\nabla u_j - \nabla u_k) = 0$, by Proposition 2.5 their scalar product belongs to the Hardy space $\mathcal{H}^1(\Omega)$ and moreover

$$||\langle H, \nabla u_j - \nabla u_k \rangle||_{\mathcal{H}^1} \le c_3 ||H||_{\frac{2-\varepsilon}{1-\varepsilon}} ||\nabla u_j - \nabla u_k||_{2-\varepsilon}$$

Since $\alpha \in L^{\infty}(\Omega) \subset BMO(\Omega)$ by Theorem 2.3, thanks to (3.2) we obtain

$$(3.4) \quad \text{II} \leq c_4 ||\alpha||_{BMO} ||\langle H, \nabla u_j - \nabla u_k \rangle||_{\mathcal{H}^1} \leq c_3 c_4 ||\alpha||_{BMO} ||H||_{\frac{2-\varepsilon}{1-\varepsilon}} ||\nabla u_j - \nabla u_k||_{2-\varepsilon} \leq c_1 c_3 c_4 |\varepsilon| ||\alpha||_{BMO} ||\nabla u_j - \nabla u_k||_{2-\varepsilon}^{2-\varepsilon}.$$

From estimates (3.3) and (3.4) we have

$$\lambda_o \int_{\Omega} |\nabla u_j - \nabla u_k|^{2-\varepsilon} \leq c_2 ||f_j - f_k||_{2-\varepsilon} ||\nabla u_j - \nabla u_k||_{2-\varepsilon}^{1-\varepsilon} + c_1 c_3 c_4 |\varepsilon| ||\alpha||_{BMO} ||\nabla u_j - \nabla u_k||_{2-\varepsilon}^{2-\varepsilon}$$
 and then

$$||\nabla u_i - \nabla u_k||_{2-\varepsilon} \le c||f_i - f_k||_{2-\varepsilon}.$$

Then for every ε such that

$$|\varepsilon| < \frac{\lambda_o}{c_1 c_3 c_4 ||\alpha||_{BMO}}$$

we have that

$$||u_{j} - u_{k}||_{W_{0}^{1,2-\varepsilon}} \le c||f_{j} - f_{k}||_{L^{2-\varepsilon}}.$$

Formula (3.5) implies that u_j is a Cauchy sequence and then it converges to a function u in $W_o^{1,2-\varepsilon}(\Omega)$. One can easily check that u solves problem (3.1).

Now, we are in position to give the proof of Theorem A.

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Proof of Theorem A. Let us consider the sequence a_i defined by

$$a_{j}(x) = \begin{cases} a(x) & \text{if} \quad a(x) \le j \\ j & \text{if} \quad a(x) \ge j \end{cases}$$

and the Dirichlet problems

(3.6)
$$\begin{cases} \operatorname{div}(a_j(x)\nabla u_j) = \operatorname{div} f & \text{in } \Omega \\ u_j = 0 & \text{on } \partial\Omega. \end{cases}$$

Since $||a_j||_{BMO} \leq 2||a||_{BMO}$ for every j [1, Lemma A.2], by Lemma 3.1, if $|\varepsilon| \leq \frac{\lambda_o}{c||a||_{BMO}}$ and $f \in L^{2-\varepsilon}(\Omega)$, each problem (3.6) admits a unique solution u_j in $W_o^{1,2-\varepsilon}(\Omega)$. As before we use the Hodge decomposition to get

$$|\nabla u_j|^{-\varepsilon}(\nabla u_j) = \nabla \psi_j + H_j$$

where $\operatorname{div} H_i = 0$ and

$$\begin{aligned} ||H_j||_{\frac{2-\varepsilon}{1-\varepsilon}} &\leq c|\varepsilon| ||\nabla u_j||_{2-\varepsilon}^{1-\varepsilon} \\ ||\nabla \psi_j||_{\frac{2-\varepsilon}{1-\varepsilon}} &\leq c||\nabla u_j||_{2-\varepsilon}^{1-\varepsilon} \end{aligned}$$

where c denotes a constant depending only on N.

Using that $a(x) \ge \lambda_a$ and arguing as in the previous Lemma we get

$$\lambda_o\!\!\int_{\Omega}\!|\nabla u_j|^{2-\varepsilon}\!\le\!\int_{\Omega}\!\!f\nabla\psi_j+\!\int_{\Omega}\!\!a_j(\mathbf{x})\langle\nabla u_j\,,\,H_j\rangle\!\le c||f||_{2-\varepsilon}||\nabla u_j||_{2-\varepsilon}^{1-\varepsilon}+c|\varepsilon|||\mathbf{a}||_{\mathit{BMO}}||\nabla u_j||_{2-\varepsilon}^{2-\varepsilon}\,.$$

Then

$$||\nabla u_j||_{2-\varepsilon} \le c||f||_{2-\varepsilon}$$

with $c = c(\lambda_0, ||a||_{BMO}, N)$. The sequence (u_j) is bounded in $W_o^{1,2-\varepsilon}(\Omega)$, and then there exist a subsequence of (u_j) , still denoted by (u_j) , and a function u such that

$$u_j \to u$$
 weakly in $W^{1,2-\varepsilon}(\Omega)$.

Since, for $\varphi \in C_o^{\infty}(\Omega)$, $a_j \nabla \varphi$ converges strongly to $a \nabla \varphi$ in $L^p(\Omega)$ for every $p < \infty$ and ∇u_j converges weakly to ∇u in $L^{2-\varepsilon}(\Omega)$, we obtain that u solves the problem (1.1), *i.e.* that

$$\int_{\Omega} a(x) \nabla u \nabla \varphi = \int_{\Omega} f \nabla \varphi \qquad \forall \varphi \in C_o^{\infty}(\Omega).$$

Moreover, we have that

$$(3.7) ||\nabla u||_{2-\varepsilon} \le c||f||_{2-\varepsilon}$$

with $c = c(\lambda_0, ||a||_{BMO}, N)$. The uniqueness is an easy consequence of the previous estimate. \square

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