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Some chain rules for certain derivatives of double tensors depending on other such tensors and some point variables. II. On the Lagrangian spatial derivative in relativity

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Fisica matematica. — *Some chain rules for certain derivatives of double tensors depending on other such tensors and some point variables.*
 II. *On the Lagrangian spatial derivative in relativity.* Nota (*) del Corrisp. ALDO BRESSAN.

§ 6. ON THE MOTION $\mathcal{M}$ OF A MATERIAL BODY $\mathcal{C}$
 IN THE RELATIVISTIC SPACE TIME S_4

Part II is substantially the extension of Part I (on $\tilde{T}^{\dots}_{\dots}{}_{;R}$) to relativity theory, for which the Lagrangian spatial derivative $\tilde{T}^{\dots}_{\dots}{}_{;R}$ is relevant. The description of this part is included in the introduction to Part I—see [3], § 1.

Now let us identify S_μ for $\mu = 4$ with a Riemannian space-time S_4 of special or general Relativity. For every event point $\mathcal{E} \in S_4$ the metric $ds^2 = -g_{\alpha\beta} dx^\alpha dx^\beta$ is assumed to be reducible, at $\mathcal{E}$, to the pseudo-Pitagorical form

$$(6.1) \quad ds^2 = -\delta'_{\alpha\beta} dx^\alpha dx^\beta \quad \text{with} \quad \delta'_{\alpha R} = \delta_{\alpha R} \quad \text{and} \quad \delta'_{\alpha 0} = -\delta_{\alpha 0}$$

by a suitable choice of frame ϕ , i.e. (x) ; in this paper $\delta_{\alpha\beta}$ is Kronecker's delta and Greek [Latin] indices run from 0 to 3 [1 to 3].

Let $\mathcal{C}$ be a body moving in S_4 regularly enough to regard it as a set of material points—see § 52 in [2], p. 138—. Hence its world tube $W_\mathcal{C}$ is the union of the world lines W_{P^*} of these points ($P^* \in \mathcal{C}$). Furthermore $\mathcal{C}$'s 4-velocity u^α and intrinsic acceleration $A^\alpha = Du^\alpha/Ds$ exist at every $\mathcal{E} \in W_\mathcal{C}$. Then the spatial projector $\overset{\perp}{g}_{\alpha\beta}$ and spatial metric $\overset{\perp}{ds}^2$ exist in $W_\mathcal{C}$:

$$(6.2) \quad \overset{\perp}{ds}^2 = \overset{\perp}{g}_{\alpha\beta} dx^\alpha dx^\beta \quad \text{with} \quad \overset{\perp}{g}_{\alpha\beta} = g_{\alpha\beta} + u_\alpha u_\beta.$$

Fix a physically possible space time S_4^* , with metric tensor $g_{\alpha\beta}^*$, and an admissible frame (y) in it—see [2], p. 139—⁽¹⁾.

Consider the intersection of $\mathcal{C}$'s world tube $W_\mathcal{C}^*$ in S_4^* with the (space-like) hypersurface $y^0 = 0$; and endow it with the following Riemannian metric

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(1) The frame (x) is *admissible* if x^0 increases towards future and the hypersurfaces $x^0 = \text{const}$ are space-like, i.e. $ds^2 > 0$ for dx^α tangent to them.

ds^{*2} , which is strictly positive definite:

$$(6.3) \quad ds^{*2} = a_{LM}^* dy^L dy^M \quad \text{with} \quad a_{rs}^* = \hat{a}_{rs}^*(y^1, y^2, y^3) = \\ = \stackrel{\perp}{g}_{rs}^*(0, y^1, y^2, y^3),$$

$\stackrel{\perp}{g}_{\alpha\beta}$ being the spatial projector in $W_{\mathcal{C}}^*$. Identify S_3^* with the resulting Riemannian space. Furthermore for $P^* \in \mathcal{C}$ call the co-ordinate y^L of the intersection $\mathcal{C}^*$ of S_3^* with P^* 's world line $W_{P^*}^*$ in S_3^* L -th material co-ordinate of $\mathcal{C}^*$ or P^* . Thus a frame, or co-ordinate system has been determined on S_3^* or $\mathcal{C}$; it will be denoted by (y) or ϕ^* . It is convenient to identify P^* with $\mathcal{C}^* = \phi^{*-1}(y)$.

As well as in [2] lower case [capital] indices refer to S_μ [S_μ^*], i.e. are space-time [material] indices.

The equations or functions

$$(6.4) \quad x^\alpha = \hat{x}^\alpha(t, y^1, y^2, y^3), \quad \text{or} \quad x = \hat{x}(t, y), \quad \text{with} \quad \partial \hat{x}^0 / \partial t > 0$$

are said to *represent* $\mathcal{C}$'s motion $\mathcal{M}$ in S_μ if, for every $P^* \in \mathcal{C}$, the function $t \mapsto \hat{x}^\alpha(t, y^1, y^2, y^3)$ with $(y^1, y^2, y^3) = \phi^*(P^*)$ describes $W_{P^*}^*$.

In the sequel the functions $(6.4)_1$ are tacitly supposed to be regular in the sense that (i) they are one-to-one, (ii) of class $C^{(2)}$, (iii) for every $t \in \mathbf{R}$, the hypersurface $S_3(t)$ represented by $y \mapsto \hat{x}(t, y)$ for $y \in \phi^*(S_3^*)$ is space-like, and (iv) in S_3 we have

$$(6.5) \quad \frac{\partial(x^1, x^2, x^3)}{\partial(y^1, y^2, y^3)} \neq 0, \quad \text{hence} \quad \frac{\partial(x^0, \dots, x^3)}{\partial(t, y^1, y^2, y^3)} \neq 0.$$

By $(6.5)_2$ equation $(6.4)_1$ can be solved by

$$(6.6) \quad t = \hat{t}(x), \quad y^L = y^L(x).$$

The motion $\mathcal{M}$ determines and is determined by $(6.6)_2$; the function $(6.6)_1$, i.e. the *time parameter* $\hat{t}$, characterizes the arbitrary part of $\mathcal{M}$'s representation $(6.4)_1$; more in detail this representation is determined up to a change of the time parameter:

$$(6.7) \quad t = t(\hat{t}, y) \quad \text{with} \quad \partial \hat{t} / \partial \hat{t} > 0 \quad [t = \hat{t}(x) \quad \hat{t} = \hat{t}(x)].$$

Having fixed $\mathcal{C} \in W_{\mathcal{C}}$ arbitrarily, we can choose $\hat{t}$ *time-orthogonal* at $\mathcal{C}$ in the sense that we have there

$$(6.8) \quad u_L^\dagger = 0 \quad \text{with} \quad u_L^\dagger \equiv u_\rho x_L^\rho \quad \text{and} \quad x_L^\rho = \frac{\partial \hat{x}^\rho}{\partial y^L} \text{—see (6.4)—}.$$

§ 7. PSEUDO-ABSOLUTE DERIVATIVE AND LAGRANGIAN SPATIAL DERIVATIVE OF A DOUBLE TENSOR FIELD SUCH AS (2.4)

Consider the double tensor field $\hat{T}^{\dots}$ —see (2.4)—. Now, within relativity, it is regarded to change with the frames ϕ and ϕ^* in the obvious way, and

also with the time parameter $\hat{t}$: the determination $\bar{T}^{\dots}$ of $\tilde{T}^{\dots}$ for $\bar{\phi} = \phi$, $\bar{\phi}^* = \phi^*$, and $\bar{t}$ —see (6.7)—is given by

$$(7.1) \quad \bar{T}^{\dots} (H^{\dots}_1, \dots, H^{\dots}_m, x, \bar{t}, y) = \tilde{T}^{\dots} [H^{\dots}_1, \dots, H^{\dots}_m, x, t(\bar{t}, y), y].$$

In order to give (2.4) an interpretation completely independent of ϕ , ϕ^* , and $\hat{t}$, let us remember that, by the representation (6.4) of $\mathcal{M}$, (t, y) determines the event point $\mathcal{E} = \phi^{-1}[x(t, y)]$. Of course the argument x in (7.1) is meant to refer to $\mathcal{E}$ again, for many practical purposes. However, for other such purposes, e.g. calculating partial derivatives with respect to x^α , t , and y^R , these variables have to be able to run independently of one another. Therefore it is useful to set $E = \phi^{-1}(x)$ and to regard (7.1) as an expression in ϕ , ϕ^* , and $\hat{t}$ of the double tensor field

$$(7.2) \quad \mathbf{T} = \tilde{\mathbf{T}}(\mathbf{H}_1, \dots, \mathbf{H}_m, E, \mathcal{E}),$$

whose values are attached at E and $P^* \in \mathcal{C}$, where P^* is determined by the condition $\mathcal{E} \in W_{P^*}$.

The *pseudo-absolute derivative* of the field (2.4) (connected with $\mathcal{M}$) can be defined by

$$(7.3) \quad \frac{D}{D^P s} \tilde{T}^{\sigma_1 \dots \sigma_{l-1} \dots s_{l-1} \dots}_{\rho_1 \dots \rho_{l-1} \dots R_{l-1} \dots} = \left(\tilde{T}^{\dots}_{\dots \alpha} \frac{\partial \hat{x}^\alpha}{\partial t} + \frac{\partial \tilde{T}^{\dots}}{\partial t} \right) \frac{Dt}{Ds} \quad \left(\frac{Ds}{Dt} = \right. \\ \left. = \left(-g_{\alpha\beta} \frac{\partial \hat{x}^\alpha}{\partial t} \frac{\partial \hat{x}^\beta}{\partial t} \right)^{-1/2} \right)$$

and is independent of the choice of $\hat{t}$. For $m=0$ this derivative is simply denoted by $D \dots /Ds$, is called *absolute derivative*, and is a double tensor.

In order to deal with solid materials, the *Lagrangian spatial* (or *transverse derivative*

$$(7.4) \quad \tilde{T}^{\sigma_1 \dots \sigma_{l-1} \dots s_{l-1} \dots}_{\rho_1 \dots \rho_{l-1} \dots R_{l-1} \dots} = T^{\dots}_{\dots} ;_A + \frac{DT^{\dots}}{D^P s} u_A^\dagger \quad (u_A^\dagger = u_\rho x_A^\rho)$$

(connected with $\mathcal{M}$ —see (6.4)₁ or (6.6)₂—) was introduced in [1] for $m=0$ —see [2], p. 142. In (7.4) $\tilde{T}^{\dots}_{\dots|A}$ is determined in connection with the map $y \mapsto \hat{x}(t, y)$ —see (6.4)₂ and (2.8)—for any $m \geq 0$.

The usefulness of $\tilde{T}^{\dots}_{\dots|A}$ for $m=0$ is due to its independence of the choice of $\hat{t}$, which generally fails to hold for each of the last two terms in (7.4) ⁽²⁾.

(2) In fact, on the one hand, the present definition (7.4) of $\tilde{T}^{\dots}_{\dots|A}$ yields the equality $\tilde{T}^{\dots}_{\dots|A} = \bar{T}^{\dots}_{\dots};_A$ for $u_A^\dagger = 0$, which is the condition by which $\bar{T}^{\dots}_{\dots|A}$ is defined in [2], p. 142 (for $m=0$); and on the other hand, in [2], p. 143, $\bar{T}^{\dots}_{\dots|A}$ is also proved to have the expression (7.4) for every choice of $\hat{t}$ ($m=0$). The value of m is irrelevant as far as the independence of $\tilde{T}^{\dots}_{\dots|A}$ of $\hat{t}$ is concerned.

Note that for any $m \geq 0$, $(\alpha) \tilde{T}^{\dots}_{|A} = \tilde{T}^{\dots}_{;A}$ if and only if either $u_A^\dagger = 0$ or $D\tilde{T}^{\dots}/D^P s = 0$; hence $(\beta) \tilde{T}^{\dots}_{;A}$ is independent of the choice of $\hat{t}$ if and only if $D\tilde{T}^{\dots}/D^P s = 0$.

One also has—see (53.9) in [2], p. 143—⁽³⁾

$$(7.5) \quad \tilde{T}^{\dots}_{|A} = \tilde{T}^{\dots}_{|P} \alpha_A^P + \tilde{T}^{\dots}_{;A} + \frac{\partial \tilde{T}^{\dots}}{\partial t} \frac{Dt}{Ds} u_A^\dagger,$$

where

$$(7.6) \quad \alpha_A^P = g_{\sigma}^P x_A^\sigma = x_A^P + u^P u_A^\dagger = \hat{x}_A^P + \frac{\partial \hat{x}^P}{\partial t} \frac{Dt}{Ds} u_A^\dagger.$$

§ 8. SOME ANALOGUES FOR $D\tilde{T}^{\dots}/D^P s$ AND $\tilde{T}^{\dots}_{|R}$ OF THE CONNECTIONLESS AND STATIONARY DERIVATIVES INTRODUCED IN §§ 3-4

In dealing with the fields $\tilde{T}^{\dots}$, $\tilde{H}^{\dots}_i$, and $\tilde{T}^{\dots}$ —see (2.4) or (7.2), and (3.1-2)—we identify $x = \hat{x}(t, y)$ with the representation $(6.4)_2$ of $\mathcal{M}$. In order to write natural analogues for $D\tilde{T}^{\dots}/D^P s$ and $\tilde{T}^{\dots}_{|R}$, of the chain rules (3.5) and (4.8) for $\tilde{T}^{\dots}_{;R}$, let us introduce the following analogues $\partial \tilde{T}^{\dots}/\partial^P s$ and $\tilde{T}^{\dots}_{||R}$ of $\tilde{T}^{\dots}_{;R}$ —see (3.4)—, and the subsequent analogues $D\tilde{T}^{\dots}/D^{St} s$ and $\tilde{T}^{\dots}_{St|R}$ of $\tilde{T}^{\dots}_{St;R}$ —see (4.6-7)—: the *connectionless (pseudo-) absolute derivative*

$$(8.1) \quad \frac{\partial \tilde{T}^{\dots}}{\partial^P s} = \left(\frac{\partial \tilde{T}^{\dots}}{\partial x^P} \frac{\partial \hat{x}^P}{\partial t} + \frac{\partial \tilde{T}^{\dots}}{\partial t} \right) \frac{Dt}{Ds} = \tilde{T}^{\dots}_{,P} u^P + \frac{\partial \tilde{T}^{\dots}}{\partial t} \frac{Dt}{Ds};$$

the *connectionless Lagrangian spatial derivative*

$$(8.2) \quad \tilde{T}^{\dots}_{||R} = \tilde{T}^{\dots}_{;R} + \frac{\partial \tilde{T}^{\dots}}{\partial^P s} u_R^\dagger \quad \text{—see (7.4);}$$

the *stationary (or covariant partial) absolute derivative*

$$(8.3) \quad \frac{D\tilde{T}^{\dots}}{D^{St} s} \left(\tilde{H}^{\dots}_i, \dots, \tilde{H}^{\dots}_m, x, t, y \right) = \frac{D\tilde{T}^{\dots}}{Ds} \quad \text{for } \tilde{H}^{\dots}_i = \tilde{H}^{\dots}_i$$

—see (3.2), ($i = 1, \dots, m$),

(3) Fix the index ρ and set $l(x) = x^\rho$. Then $x_A^\rho = l(x)_{;A}$ and $\alpha_A^\rho = l(x)_{|A}$. This justifies writing $x_A^\rho = x^\rho_{;A}$ and $\alpha_A^\rho = x^\rho_{|A}$, and shows that α_A^ρ is independent of the choice of $\hat{t}$. However that x_A^ρ , and hence α_A^ρ are double tensors of covariant [contravariant] order $(0, 1)$ [(1, 0)] has to, and can easily be proved directly—see [2], (A 2.5) on p. 260 and (53.8) on p. 143.

where the fields $\check{H}_i^{\dots}$ satisfy the local conditions (4.2)₁ and

$$(8.4) \quad \frac{D}{Ds} \check{H}_i^{\dots}(x, t, y) = 0;$$

and lastly the *stationary* (or *covariant partial*) *Lagrangian spatial derivative*

$$(8.5) \quad \tilde{T}_i^{\dots}(\check{H}_i^{\dots}, \dots, \check{H}_m^{\dots}, x, t, y)_{St|R} = \hat{T}_i^{\dots}|_R \text{ for } \check{H}_i^{\dots} = \check{H}_i^{\dots} \\ (i = 1, \dots, m),$$

where the fields $\check{H}_i^{\dots}$ satisfy the local conditions (4.2) and (8.4), or at least (4.2)₁ and $\check{H}_i^{\dots}|_R = 0$ ($i = 1, \dots, m$).

Note that (8.1-2), (3.4), and (7.6) imply the equality

$$(8.6) \quad \tilde{T}_i^{\dots}|_R = \tilde{T}_i^{\dots}{}_{,p} \alpha_R^p \tilde{T}_i^{\dots}{}_{,R} + \frac{\partial \tilde{T}_i^{\dots}}{\partial t} \frac{Dt}{Ds} u_R^{\dagger},$$

which is to (7.5) as (8.2) is to (7.4).

By (8.1), (7.3), and (2.5)₁,

$$(8.7) \quad \frac{D}{D^p s} \tilde{T}_i^{\dots} = \frac{\partial \tilde{T}_i^{\dots}}{\partial^p s} - \frac{Dt}{Ds} \frac{\partial \hat{x}^p}{\partial t} St_{,p} \tilde{T}_i^{\dots},$$

while by (8.6), (7.5), and (2.5)

$$(8.8) \quad \tilde{T}_i^{\dots}|_R = \tilde{T}_i^{\dots}|_R - St_{||R} \tilde{T}_i^{\dots}$$

with

$$(8.9) \quad St_{||R} \tilde{T}_i^{\dots} = (St_{,p} \tilde{T}_i^{\dots}) \alpha_R^p + St_{,R} \tilde{T}_i^{\dots} \quad \text{---see (2.6).}$$

Remark that, by (8.8), for ϕ and ϕ^* fixed, $\tilde{T}_i^{\dots}|_R$ is independent of the choice of $\hat{t}$. (In fact this obviously holds for $St_{||R} \tilde{T}_i^{\dots}$ and $\tilde{T}_i^{\dots}|_R$).

§ 9. FOUR CHAIN RULES FOR PSEUDO-ABSOLUTE DERIVATIVES AND LAGRANGIAN SPATIAL DERIVATIVES. EXPLICIT EXPRESSION FOR $D\tilde{T}_i^{\dots}/D^{St} s$ AND $\tilde{T}_i^{\dots}|_{St|R}$

By (3.2), (7.3), and (8.1) we have the chain rule

$$(9.1) \quad \frac{D\tilde{T}_i^{\dots}}{Ds} = \sum_{i=1}^m \frac{\partial \tilde{T}_i^{\dots}}{\partial \check{H}_i^{\dots}} \frac{\partial \check{H}_i^{\dots}}{\partial^p s} + \frac{D\tilde{T}_i^{\dots}}{D^p s} \quad \left(\frac{D\tilde{T}_i^{\dots}}{Ds} = \frac{D\tilde{T}_i^{\dots}}{D^p s} \right)$$

for the compound function (3.2) with generally noncovariant terms.

By applying relation (8.7) (in $\tilde{T}^{\dots}_i$) to $\tilde{H}^{\dots}_i$, one turns (9.1) into

$$(9.1') \quad \frac{D\tilde{T}^{\dots}}{Ds} = \sum_{i=1}^m \frac{\partial \tilde{T}^{\dots}}{\partial H^{\dots}_i} \left(\frac{D\tilde{H}^{\dots}_i}{D^P s} + \frac{Dt}{Ds} \frac{\partial \hat{x}^p}{\partial t} St_{,p} H^{\dots}_i \right) + \frac{DT^{\dots}}{D^P s}.$$

Now, first, identify $\tilde{H}^{\dots}_i$ with a field $\tilde{H}^{\dots}_i$ that satisfies (4.2)_i, and (8.4) ($i = 1, \dots, m$). Then by (9.1') one can *render* (8.3) *explicit*:

$$(9.2) \quad \frac{D\tilde{T}^{\dots}}{D^{St} s} = \frac{D\tilde{T}^{\dots}}{D^P s} + \frac{Dt}{Ds} \frac{\partial x^p}{\partial t} \sum_{i=1}^m \frac{\partial \tilde{T}^{\dots}}{\partial H^{\dots}_i} St_{,p} H^{\dots}_i.$$

Furthermore, by considering $\tilde{H}^{\dots}_i$ to $\tilde{H}^{\dots}_m$ as arbitrary, from (9.1') and (9.2) one deduces the *chain rule*

$$(9.3) \quad \frac{D\hat{T}^{\dots}}{Ds} = \sum_{i=1}^m \frac{\partial \tilde{T}^{\dots}}{\partial H^{\dots}_i} \frac{D\tilde{H}^{\dots}_i}{Ds} + \frac{D\tilde{T}^{\dots}}{D^{St} s} \quad \left(\frac{D\tilde{H}^{\dots}_i}{Ds} = \frac{D\tilde{H}^{\dots}_i}{D^P s} \right)$$

for compound function (3.2), all of whose terms are covariant.

From (3.2) and (8.6) we easily obtain the equality

$$(9.4) \quad \tilde{T}^{\dots}|_R = \sum_{i=1}^m \frac{\partial \tilde{T}^{\dots}}{\partial H^{\dots}_i} \tilde{H}^{\dots}_i|_R + \tilde{T}^{\dots}|_R$$

which, by (8.8), yields the *chain rule*

$$(9.5) \quad \tilde{T}^{\dots}|_R = \sum_{i=1}^m \frac{\partial \tilde{T}^{\dots}}{\partial H^{\dots}_i} \tilde{H}^{\dots}_i|_R + \tilde{T}^{\dots}|_R$$

for the compound function (3.2), with generally noncovariant terms. By (8.8), (9.5) is equivalent to

$$(9.5') \quad \tilde{T}^{\dots}|_R = \sum_{i=1}^m \frac{\partial \tilde{T}^{\dots}}{\partial H^{\dots}_i} \left(\tilde{H}^{\dots}_i|_R + St_{||R} H^{\dots}_i \right) + \tilde{T}^{\dots}|_R.$$

First identify $\bar{H}_{\dots}^{\dots}$ with a field $\bar{H}_{\dots}^{\dots}$ that satisfies (4.2)₁ and the condition $\bar{H}_{\dots}^{\dots}|_R = 0$ locally ($i = 1, \dots, m$). Then by (9.5') we can render (8.5) explicit:

$$(9.6) \quad \tilde{T}_{\dots}^{\dots}(H_{\dots}^{\dots}, \dots, H_{\dots}^{\dots}, x, t, y)_{St;R} = \tilde{T}_{\dots}^{\dots}|_R + \sum_{i=1}^m \frac{\partial \tilde{T}_{\dots}^{\dots}}{\partial H_{\dots}^{\dots}} St_{||R} H_{\dots}^{\dots} \quad \text{---see (8.9).}$$

Furthermore, regarding $\bar{H}_{\dots}^{\dots}$ to $\bar{H}_{\dots}^{\dots}$ as arbitrary, (9.5') and (9.6) yield the chain rule

$$(9.7) \quad \tilde{T}_{\dots}^{\dots}|_R = \sum_{i=1}^m \frac{\partial \tilde{T}_{\dots}^{\dots}}{\partial H_{\dots}^{\dots}} \bar{H}_{\dots}^{\dots}|_R + \tilde{T}_{\dots}^{\dots} St_{||R}$$

for the compound function (3.2), all of whose terms are covariant and independent of the choice of $\hat{t}$.

Of course by replacing $\tilde{T}_{\dots}^{\dots} St_{||R}$ with $\tilde{T}_{\dots}^{\dots}|_R$ in (9.7) we turn (9.7) into a generally false equality (like (3.6)).

§ 10. EXPRESSIONS FOR THE STRESS DIVERGENCE OF A RELATIVISTIC HYPERELASTIC BODY AFFORDED BY TWO AMONG THE CHAIN RULES ABOVE

Consider the hyper-elastic body $\mathcal{C}'$, introduced in § 5, within (general) relativity, mutatis mutandis (according to [2]). Then the first Piola-Kirchhoff stress tensor K^{aB} is spatial ($u_a K^{aB} \equiv 0$); and it is given by a constitutive function of the form

$$(10.1) \quad K^{\alpha B} = \tilde{K}^{\alpha B}(y, \alpha_A^\mu, g_{\lambda\mu}, u^\lambda, \phi^*) \quad (g_{\lambda\mu} u^\lambda u^\mu = -1),$$

where $g_{\lambda\mu}$ can be the metric tensor at some $\mathcal{C} \in S_4$ in admissible coordinates ⁽⁴⁾

Assume that $X^{\rho\sigma}$ is the Euler spatial stress tensor and $\mathcal{D}$ is the actual proper volume per unit reference proper volume. Then, by the dynamic equation

(4) $\tilde{K}^{\alpha B}$ behaves under changes of ϕ^* in the obvious way; and it is determined by the function induced by it for any particular choice $\bar{\phi}^*$ of ϕ^* , and for $g_{\lambda\mu} = \delta'_{\lambda\mu}$ —see (6.1)₂₋₃—and $u^\lambda = \delta_0^\lambda$. More in detail express $\bar{\phi}^* \circ \phi^{*-1}$ by $\bar{y} = \bar{y}(y)$, consider any matrix $\bar{x}_L^\rho$ for which $g_{\lambda\mu} = \delta'_{\rho\sigma} \bar{x}_\lambda^\rho \bar{x}_\mu^\sigma$ and $u^\lambda = x_0^\lambda$, where $(x_0^\lambda) = (x_\lambda^\rho)^{-1}$. Then (10.1) holds if and only if

$$K^{\alpha B} = x_p^\alpha \frac{\delta y^B}{\delta y^S} \tilde{K}^{\rho S}(\bar{y}, \bar{\alpha}_R^\lambda, \delta'_{\lambda\mu}, u^\lambda, \bar{\phi}^*) \quad \text{where} \quad \bar{\alpha}_R^\lambda = \bar{\alpha}_A^\mu x_\mu^\lambda \frac{\delta y^A}{\delta y^R}.$$

In fact, as far as the cronotopic indices are concerned the equivalence above follows from the objectivity principle—see [2] p. 209—or from a relativistic principle of 1st order physical indistinguishability of locally natural (i.e. geodesic and pseudo-Euclidean) frames. The latter principle is related to the physical indistinguishability of inertial frames.

(24.8) for $q^\alpha \equiv 0$ and formula (60.9) in [2], the resultant I^ρ of the contact forces per unit reference proper volume has the expressions

$$(10.2) \quad I^\rho = - \mathcal{D} g_\alpha^\rho X^{\alpha\beta} /_\gamma g_\beta^\gamma = - g_\alpha^\rho K^{\alpha B} |_{\mathcal{B}} [X^{\alpha B} = X^{\alpha B}(x), K^{\alpha B} = K^{\alpha B}(t, y)].$$

Since ϕ^* , ϕ , and the representation (6.4) of $\mathcal{M}$ have to be regarded as given, this holds also for the functions $\alpha_A^\mu = \alpha_A^\mu(t, y)$ —see (7.6)—, $g_{\lambda\mu} = g_{\lambda\mu}(x)$, and $u^\lambda = u^\lambda(t, y) = [\partial \hat{x}(t, y)/\partial t] Dt/Ds$. Hence by (8.6)

$$(10.3) \quad \alpha_{A||B}^\mu = \alpha_{A,B}^\mu + \frac{Dt}{Ds} \frac{\partial \alpha_A^\mu}{\partial t} u_B^\dagger, \quad g_{\lambda\mu||B} = g_{\lambda\mu,\sigma} \alpha_B^\sigma,$$

$$u^\lambda_{||B} = u^\lambda_{,B} + \frac{Dt}{Ds} \frac{\partial u^\lambda}{\partial t} u_B^\dagger.$$

Rules (9.5) and (9.7) can be applied to function (10.1) for $\bar{H}_A^\mu(t, y) = \alpha_A^\mu$, $\bar{H}_{\lambda\mu}(x) = g_{\lambda\mu}$, and $\bar{H}^\lambda(t, y) = u^\lambda$. Furthermore, by (10.1)₂, $\partial \bar{K}^{\alpha B}/\partial u^\lambda = \xi u_\lambda$ for some $\xi \in \mathbf{R}$. Hence—see (10.3)₃—

$$(10.4) \quad (\partial \bar{K}^{\alpha B}/\partial u^\lambda) u^\lambda_{||B} = 0, \quad (\partial \bar{K}^{\alpha B}/\partial u^\lambda) u^\lambda_{|B} = 0.$$

Now call $K^{\alpha B} = \hat{K}^{\alpha B}(t, y)$ the field induced by $\tilde{K}^{\alpha B}$ along $\mathcal{M}$. Then, on the one hand, by (9.5) and (10.4)₁

$$(10.5) \quad \hat{K}^{\alpha B} |_{\mathcal{B}} = \frac{\partial \tilde{K}^{\alpha B}}{\partial \alpha_A^\mu} \alpha_{A||B}^\mu + \frac{\partial \tilde{K}^{\alpha B}}{\partial g_{\lambda\mu}} g_{\lambda\mu||B} + \tilde{K}^{\alpha B} |_{\mathcal{B}} (\hat{K}^{\alpha B} |_{\mathcal{B}} = \bar{K}^{\alpha B} |_{\mathcal{B}}).$$

Furthermore by (10.1) and (7.4) $\tilde{K}^{\alpha B} |_{\mathcal{B}} = \tilde{K}^{\alpha B} /_{\mathcal{B}}$. Hence, by (10.3)₁₋₂, (10.2) affords the expression

$$(10.6) \quad I^\rho = - g_\alpha^\rho \left[\frac{\partial \tilde{K}^{\alpha B}}{\partial \alpha_A^\mu} \left(\alpha_{A,B}^\mu + \frac{Ds}{Dt} \frac{\partial \alpha_A^\mu}{\partial t} u_B^\dagger \right) + \frac{\partial \tilde{K}^{\alpha B}}{\partial g_{\lambda\mu}} g_{\lambda\mu,\sigma} \alpha_B^\sigma + \tilde{K}^{\alpha B} /_{\mathcal{B}} \right]$$

for I^ρ . Thus — I^ρ appears as the spatialization of a sum whose terms are generally noncovariant *but* (for ϕ and ϕ^* fixed) *are independent of the choice of $\hat{t}$* .

On the other hand, (9.7) and (10.4)₂ yield the 1st of the equalities

$$(10.7) \quad \hat{K}^{\alpha B} |_{\mathcal{B}} = \frac{\partial \tilde{K}^{\alpha B}}{\partial \alpha_A^\mu} \alpha_{A|B}^\mu + \frac{\partial \tilde{K}^{\alpha B}}{\partial g_{\lambda\mu}} g_{\lambda\mu|B} + \tilde{K}^{\alpha B} S_{\mathcal{B}} |_{\mathcal{B}}, \quad g_{\lambda\mu|B} = 0,$$

while (10.7)₂ follows from (7.4). Furthermore (9.6), (8.9), and (2.6) easily yield, by (10.7)₂,

$$(10.8) \quad \tilde{K}^{\alpha B}_{S|B} = \tilde{K}^{\alpha B}_{|B} + \frac{\partial \tilde{K}^{\alpha B}}{\partial \alpha_A^\mu} \left(\{S_{AB}\}^* \alpha_S^\mu - \{\rho\sigma\}^\mu \alpha_A^\sigma \alpha_B^\rho \right) + \frac{\partial \tilde{K}^{\alpha B}}{\partial g_{\lambda\mu}} g_{\lambda\mu,\rho} \alpha_B^\rho - \\ - \frac{\partial \tilde{K}^{\alpha B}}{\partial u^\lambda} \{\rho\sigma\}^\lambda u^\sigma \alpha_B^\rho ;$$

in fact by (10.7)₂ the last but one term in (10.8) equals the term in $\partial \tilde{K}^{\alpha B} / \partial g_{\lambda\mu}$ and in the Christoffel's symbols $\{ \}$ that arises directly by (9.6), (8.9), and (2.6). It has been preferred, because it is simpler than the latter, and also this contains partial derivatives of $g_{\lambda\mu}$ through $\{ \}$. Instead Christoffel's symbols have been left in other terms of (10.8), because thus the use of $\alpha_{S,B}^\mu$ or $u^\mu_{,B}$ is avoided.

By (10.7) and (10.2), we have the simple expression

$$(10.9) \quad I^\rho = - \frac{1}{g_\alpha^\rho} \left[\frac{\partial \tilde{K}^{\alpha B}}{\partial \alpha_A^\mu} \alpha_{A|B}^\mu + \tilde{K}^{\alpha B}_{S|B} \right] \quad \text{---see (10.8)---}$$

for I^ρ , by which — I^ρ appears as the spatialization of a sum of two terms that are both independent of $\hat{t}$ and covariant.

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