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Abstract singular hyperbolic equations

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Analisi matematica. — *Abstract singular hyperbolic equations.* Nota di GIUSEPPE COPPOLETTA, presentata^(*) dal Corrisp. E. VESENTINI.

RIASSUNTO. — Si annunziano alcuni risultati di esistenza e unicità per l'equazione astratta singolare

$$\varphi(t) u'(t) = A(t) u(t) + f(t)$$

nel caso iperbolico.

INTRODUCTION

Let E be a Banach space (norm $|\cdot|_E$) and let $\{A(t)\}_{t \in [0, T]}$ be a family of linear operators $A(t) : D(t) \subseteq E \rightarrow E$ with dense domain in E .

Consider the problem

$$(P) \quad \varphi(t) u'(t) = A(t) u(t) + f(t) \quad t \in [0, T]$$

where $\varphi : [0, T] \rightarrow [0, +\infty]$ is an arbitrary function such that:

$$0 \leq \varphi(t) < +\infty \quad \text{a.e. in } [0, T]$$

$$\frac{1}{\varphi} \in L^1_{loc}([0, T]).$$

This formulation includes many kinds of singular and degenerate evolution equations which have been extensively studied, essentially in the parabolic framework (see for example [1], [6], [8], [10]).

In this note we study problem (P) in the hyperbolic case (see also [2], [3]). In section 1 we consider the case $\varphi(t) = 1$ and, by relaxing the assumptions on $\{A(t)\}$, we generalize the results of Da Prato–Grisvard [5], and Da Prato–Iannelli [7] for the classical evolution equation

$$(P_1) \quad \begin{cases} u'(t) = A(t) u(t) + f(t) \\ u(0) = x \end{cases} \quad t \in [0, T].$$

In section 2 we study the case $\varphi(t) = t$ and obtain existence and uniqueness results in an appropriate weighted space for the singular abstract equation

$$(P_2) \quad t u'(t) = A(t) u(t) + f(t) \quad t \in [0, T].$$

A priori no initial condition can be imposed here.

Finally, in section 3, the general problem (P) is reduced to cases (P₁) and (P₂) (depending on $\varphi(t)$) by means of suitable change of variables.

This note will appear in a more detailed form in a forthcoming paper.

(*) Nella seduta del 9 gennaio 1982.

0. NOTATIONS

If X is a Banach space and $L : D(L) \subseteq X \rightarrow X$ is a linear operator, we denote by $\rho(L)$ the resolvent set of L and by $R(\lambda, L)$ the corresponding resolvent operator. Let $\{A(t)\}_{t \in [0, T]}$ be a family of linear operators $A(t) : D(t) \subseteq E \rightarrow E$. The family is said to be ω -measurable⁽¹⁾ if there exists $\omega \in \mathbb{R}$ such that $[\omega, +\infty[\subseteq \rho(A(t))$ for any $t \in [0, T]$ and the mapping $t \rightarrow R(\lambda, A(t))x$ is measurable for any $x \in E$ and for any $\lambda \in [\omega, +\infty[$. On the other hand the family is said to be (M, ω) -stable⁽²⁾ if there exist $\omega \in \mathbb{R}$ and $M > 0$ such that:

$$|R(\lambda, A(t_1))R(\lambda, A(t_2)), \dots, R(\lambda, A(t_k))|_{\mathcal{L}(E)} \leq M(\lambda - \omega)^{-k}$$

for any $\lambda > \omega$, $k \in \mathbb{N}$ and $0 \leq t_1 \leq t_2 \leq \dots \leq t_k \leq T$.

In this note we always assume the following conditions:

- (H) $\left\{ \begin{array}{l} i) E \text{ is reflexive and } \{A(t)\} \text{ is } \omega\text{-measurable and } (M, \omega)\text{-stable in } E, (\omega \in \mathbb{R}, M > 0) \\ ii) \text{ there exists a Banach space } F \overset{\text{ds}}{\hookrightarrow} E^{\text{(3)}} \text{ such that } F \subseteq D(t) \text{ for any } t \in [0, T] \text{ and } \{A(t)_F\}^{\text{(4)}} \text{ is } \eta\text{-measurable and } (N, \eta) \text{ stable in } F, (\eta \in \mathbb{R}, N > 0). \\ iii) \text{ the map } t \rightarrow |A(t)|_{\mathcal{L}(F, E)} \text{ is measurable.} \end{array} \right.$

Now let $X \subseteq L^1_{\text{loc}}([0, T], E)$ be a Banach space; consider the following linear operators on X :

$$(1) \quad \left\{ \begin{array}{l} D(A) = \{u \in X \mid u(t) \in D(t) \text{ a.e. in } [0, T] \text{ and } t \rightarrow A(t)u(t) \in X\} \\ (Au)(t) = A(t)u(t) \end{array} \right.$$

$$(2) \quad \left\{ \begin{array}{l} D(B) = \{u \in X \mid \varphi(t)u'(t) \in X\}^{\text{(5)}} \\ (Bu)(t) = -\varphi(t)u'(t). \end{array} \right.$$

Then we can write (P) in the following form:

$$(3) \quad Bu + Au = -f.$$

(1) Cfr. [5].

(2) Cfr. [9].

(3) The symbol $\overset{\text{ds}}{\hookrightarrow}$ denote continuous and dense imbedding.

(4) $A(t)_F$ denotes the part of $A(t)$ in F , i.e. the operator

$$D(A(t)_F) = \{x \in D(t) \cap F \mid A(t)x \in F\}, \quad (A(t)_F)x = A(t)x \quad \forall x \in D(A(t)_F).$$

(5) The derivative is taken in the distributional sense.

We say that u is a strict solution of (3) in X if $u \in D(B) \cap D(A)$ and u satisfies (3). On the other hand u is said to be a strong solution of (3) in X if there exists a sequence $\{v_k\} \subseteq D(B) \cap D(A)$ such that

$$v_k \xrightarrow{X} u \quad \text{and} \quad Bv_k + Av_k \xrightarrow{X} -f.$$

We shall see that, depending on $\varphi(t)$, an initial condition may or may not be needed for uniqueness. In the former case we also require in the above definitions the condition $u(0) = x$ for strict solutions and $v_k(0) \xrightarrow{E} x$ for strong solutions.

1. THE CASE $\varphi(t) = 1$

In this section we solve the abstract Cauchy problem:

$$(P_1) \quad \begin{cases} u'(t) = A(t)u(t) + f(t) & t \in [0, T] \\ u(0) = x \end{cases}$$

To reach an adequate generality in the study of time-singularities for the general problem (P) we find it convenient to relax the following condition which has been assumed in [5] and [7]:

b) hypothesis (H) is verified and there exists $\beta > 0$ such that

$$|A(t)|_{\mathcal{L}(F, E)} \leq \beta \quad \forall t \in [0, T].$$

More precisely we obtain the following:

THEOREM 1. *Assume that (H) is verified and that*

$$(4) \quad \int_0^T |A(t)|_{\mathcal{L}(F, E)}^p dt < +\infty.$$

Then, for any $p \in [1, +\infty[, x \in E$ and $f \in L^p(0, T, E)$, problem (P₁) has a unique strong solution u in $L^p(0, T, E)$ such that $u \in C([0, T], E)$ and $u(0) = x$.

Moreover, if u_n is the solution of the Yosida approximating problem⁽⁶⁾

$$(P'_n) \quad \begin{cases} u'_n(t) = A_n(t)u_n(t) + f(t) & t \in [0, T] \\ u_n(0) = x \end{cases}$$

then $u_n \rightarrow u$ in $C([0, T], E)$.

Finally, if $x \in F$ and $f \in L^p(0, T, F)$, then the solution u is strict; if further F is reflexive, then $u \in L^\infty(0, T, F)$.

(6) $A_n(t) = n^2 R(n, A(t)) - nI$.

Remark 1. If we only look for solutions of (P_1) which vanish for $t = 0$, then we can replace (4) by the following condition:

$$(5) \quad \int_{\varepsilon}^T |A(t)|_{\mathcal{L}(F, E)}^p dt < +\infty \quad \forall \varepsilon \in]0, T[.$$

On the contrary, if $u(0) = x \neq 0$, we cannot simply drop the condition (4).

2. THE CASE $\varphi(t) = t$

Here we study the equation

$$(P_2) \quad tu'(t) = A(t)u(t) + f(t) \quad t \in]0, T].$$

For any $\alpha \in \mathbb{R}$ set:

$$X_\alpha = \{u :]0, T] \rightarrow E \mid t^{-\alpha} u(t) \in L^p(0, T, E)\}.$$

THEOREM 2. Assume that (H) and (5) are verified.

Then, for any $p \in [1, +\infty[, \alpha > \omega + \frac{1}{p}$ and for any $f \in X_\alpha$ equation (P_2) has a unique strong solution u in X_α such that

$$(6) \quad t^{-\alpha+(1/p)} u(t) \in C([0, T], E) \quad \text{and} \quad \lim_{t \rightarrow 0} t^{-\alpha+(1/p)} u(t) = 0.$$

Moreover, if u_n is the solution of the Yosida approximating problem

$$(P_2^n) \quad tu'_n(t) = A_n(t)u_n(t) + f(t) \quad t \in]0, T],$$

then

$$t^{-\alpha+(1/p)} u_n(t) \xrightarrow[n \rightarrow \infty]{} t^{-\alpha+(1/p)} u(t) \quad \text{in } C([0, T], E).$$

Finally, if (4) is verified, if F is reflexive, $\alpha > \eta + \frac{1}{p}$, $p > 1$, and if $t^{-\alpha} f(t) \in L^\infty(0, T, F)$, then the solution u is strict and

$$t^{-\alpha} u(t) \in L^\infty(0, T, F).$$

Remark 2. Observe that (6) gives an implicit "initial trend" of the solution u ; this make clear why one cannot a priori require an arbitrary initial condition.

3. THE GENERAL CASE

Let $\varphi : [0, T] \rightarrow [0, +\infty]$ be an arbitrary function such that

$$(7) \quad \begin{cases} 0 \leq \varphi(t) < +\infty & \text{a.e. in } [0, T[\\ \frac{1}{\varphi} \in L^1_{loc}([0, T]). \end{cases}$$

We distinguish two subcases:

$$\int_0^T \frac{ds}{\varphi(s)} < +\infty \quad \text{and} \quad \int_0^T \frac{ds}{\varphi(s)} = +\infty.$$

In the first subcase we solve the abstract Cauchy problem:

$$(P_c) \quad \begin{cases} \varphi(t) u'(t) = A(t) u(t) + f(t) & t \in [0, T] \\ u(0) = x. \end{cases}$$

THEOREM 3. *Assume that:*

$$i) \quad \int_0^T \frac{ds}{\varphi(s)} < +\infty \quad \text{and} \quad (7) \text{ is verified}$$

ii) *the family $\{A(t)\}$ verifies (H) and*

$$\int_0^T \frac{\|A(t)\|_{\mathcal{L}(F,E)}^p}{\varphi(t)} dt < +\infty.$$

Let μ denote the positive measure defined by:

$$\frac{d\mu}{dt} = \frac{1}{\varphi(t)}.$$

Then, for any $p \in [1, +\infty[, x \in E$ and $f \in L^p(0, T, \mu, E)$ ⁽⁷⁾ problem (P_c) has a unique strong solution u in $L^p(0, T, \mu, E)$ such that $u \in C([0, T], E)$ and $u(0) = x$.

Further results, analogous to those obtained in Theorem 1, are also valid if $x \in F$, $f \in L^p(0, T, \mu, F)$ and if F is reflexive.

The proof is obtained by reducing (P_c) to the case (P_1) with the transformation

$$u(t) = v \left(\int_0^t \frac{ds}{\varphi(s)} \right).$$

(7) This is the space of all functions $f : [0, T] \rightarrow E$ such that $|f(\cdot)|_E^p$ is μ -integrable.

In the second subcase we solve (P) without any initial condition:

THEOREM 4. *Assume that:*

$$i) \quad \int_0^T \frac{ds}{\varphi(s)} = +\infty \quad \text{and} \quad (7) \text{ is verified}$$

ii) *the family $\{\mathbf{A}(t)\}$ satisfies (H) and*

$$\int_{-\varepsilon}^T \frac{|\mathbf{A}(t)|_{\mathcal{L}(\mathbf{F}, \mathbf{E})}^p}{\varphi(t)} dt < +\infty, \quad \forall \varepsilon \in]0, T[$$

Let μ denote the positive measure defined by

$$\frac{d\mu}{dt} = \frac{1}{\varphi(t)} \exp \left[(\alpha p - 1) \int_t^T \frac{ds}{\varphi(s)} \right],$$

with $p \in [1, +\infty[$ and $\alpha > \omega + \frac{1}{p}$.

Then, for any $f \in L^p(0, T, \mu, \mathbf{E})$, problem (P) has a unique strong solution u in $L^p(0, T, \mu, \mathbf{E})$ such that

$$u(t) \exp \left[\left(\alpha - \frac{1}{p} \right) \int_t^T \frac{ds}{\varphi(s)} \right] \in C([0, T], \mathbf{E}),$$

$$\lim_{t \rightarrow 0} u(t) \exp \left[\left(\alpha - \frac{1}{p} \right) \int_t^T \frac{ds}{\varphi(s)} \right] = 0.$$

Once again further results, analogous to the corresponding ones of Theorem 2, are also valid.

The proof makes use of the following transformation

$$u(t) = v \left(\exp \left(- \int_t^T \frac{ds}{\varphi(s)} \right) \right)$$

which reduces (P) to the case (P₂).

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