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Cylindrical real hyper surfaces in C^n

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Geometria differenziale. — *Cylindrical real hypersurfaces in \mathbb{C}^n* (*).
Nota di CLAUDIO REA, presentata (**) dal Socio E. MARTINELLI.

RIASSUNTO. — Si stabiliscono due condizioni sufficienti per un germe di ipersuperficie reale di classe C^∞ in \mathbb{C}^n , affinché esistano coordinate ologomorfe rispetto alle quali l'ipersuperficie risulti essere il luogo di zeri di una funzione di $k < n$ variabili e k sia minimale rispetto a questa proprietà. In altre parole si vuole che l'ipersuperficie, a meno di una trasformazione bi-ologomorfa, sia l'unione di sottovarietà lineari complesse, parallele di dimensione $n - k$.

§ 1. A common problem in complex analysis is to ask whether a real, smooth hypersurface $S \subset \mathbb{C}^n$ of equation

$$F(z_1, \dots, z_n) = 0$$

can be written in the form

$$(1) \quad \phi(\zeta_1, \dots, \zeta_k) = 0, \quad \text{with } k < n$$

by a suitable choice of the holomorphic coordinates ζ_1, \dots, ζ_n at some point $p \in S$. If k is as small as possible we say that S is a *irreducible $(n - k)$ -cylinder*. Scope of the present paper is to give a partial answer to this question when $k \geq 2$.

Let L be the Levi form of S restricted to the complex tangent space $T = \left\{ u = \sum_1^n u_j \partial_j \mid uF = 0 \right\}$ of S , and N the kernel of L as linear map on T .

THEOREM 1. *Let the hypersurface S satisfy the following two conditions for $k \geq 2$*

$$(2) \quad rkL_q = k - 1, \quad \text{for all } q \text{ near } p$$

$$(3) \quad \sum_{jkl}^n (F_{j\bar{k}l} F_{\bar{s}} - F_{j\bar{s}} F_{\bar{k}l}) v_j \bar{u}_l \bar{w}_h = 0, \quad (s = l, \dots, n)$$

for all $v \in N, u, w \in T$,

then

- (i) if S is not pseudoconvex, then S is an irreducible $(n - k)$ -cylinder,
- (ii) if S is pseudoconvex, say $L \geq 0$, then there are C^∞ complex coordinates ζ_1, \dots, ζ_n in a neighbourhood U of p , holomorphic on the pseudoconvex side

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U^- of U , such that S has equation (1) in U . In particular S is the limit (uniform with all derivatives) of irreducible $(n-k)$ -cylinders $S_\varepsilon \equiv \{\phi = \varepsilon\}$, for $\varepsilon \rightarrow 0^-$.

Only subscripts to F denote derivations.

The cross section of a cylinder S is the hypersurface S^0 of C^k_ε having (1) as equation. S^0 is unique up to a bi-holomorphism.

Equation (3) may seem strange. Its meaning is explained in proposition 1, anyway (3) is necessary in the sense of the following

Necessary condition. *Let S be a $(n-k)$ -cylinder at p . Then condition (2) is equivalent to the nondegeneracy of the Levi form of the cross section S^0 and equation (3) is a consequence of (2).*

In view of part (ii) we construct in § 3 a family of complex lines in C^3 whose union is a pseudoconvex hypersurface which satisfies (2) and (3) without being a cylinder, and the tangent space of the generating lines is the Levi kernel N .

Before considering further results, let us point out which cylinders are *not* recognizable with Theorem 1.

An irreducible $(n-k)$ -cylinder escapes Theorem 1 if

- 1) S is generated by complex hyperplanes, i.e. $k=1$,
- 2) S^0 has degenerate Levi form at p .
- 3) Finally, if S^0 is strictly pseudoconvex at p , then Theorem 1 (ii) only detects that S is a limit of irreducible $(n-k)$ -cylinders.

For inspecting those remaining cases, consider the module V of C^∞ complex vector fields tangent to the generating lines of a $(n-k)$ -cylinder. V satisfies trivially the conditions

$$(4) \quad [V, V] \subset V, [V, \bar{T}]^{10} \subset V. \quad (1)$$

Next theorem affirms that, under suitable hypothesis, the existence of such a module V is also sufficient.

THEOREM 1'. *Assume that S admits a module V of C^∞ complex tangent vector fields of constant dimension $n-k$ near p , with $k \geq 2$, fulfilling (4), then the conclusions (i) and (ii) of theorem 1 hold.*

By the argument above only $(n-1)$ -cylinders escape this theorem. However this result is much weaker than Theorem 1 because the hypothesis are not directly verifiable on the equation of the surface.

(1) Modules of C^∞ vector fields with this property are called by Freeman ([5]) straight modules. We will add the requirement that V has constant dimension.

Let us explain the meaning of conditions (3) and (4). If the rank of L is constantly equal to $k-1$, as condition (2) prescribes, then $q \mapsto N_q$ is a smooth map of S into the complex Grassmannian $G(n-k, n)$, call this map the *Levi-Gauss map*.

A C^1 function f on S is said to be a CR function if there is $\sum_1^n u_j \bar{\partial}_j f = 0$, for all $u \in T$. A CR map is a map whose components are CR functions.

PROPOSITION 1. *If the rank of the Levi form is constant, then (3) is equivalent to the property of the Levi-Gauss map to be a CR-map.*

In other words (3) means that N is a CR-bundle over S . Similarly Bedford and Kalka have proved in [3] that N is the largest involutive sub-bundle of T which is holomorphic with respect to its own foliation. Here also one can say that condition (3) implies that N is the largest sub-bundle of T which is a CR-bundle.

Let \mathcal{N} be the real representative of N , i.e. $\mathcal{N} \equiv \{v + \bar{v}, \text{ with } v \in N\}$. There is $[\mathcal{N}, \mathcal{N}] \subset \mathcal{N}$ ([9]), so \mathcal{N} is the tangent space of a foliation of S wherever L has constant rank. This is the *Levi foliation*; its leaves are complex manifolds.

Similarly, let \mathcal{V} be the real representative of V . Then (4) implies obviously $[\mathcal{V}, \mathcal{V}] \subset \mathcal{V}$. On the other hand, if $v \in V$ and $u \in T$ are vector fields, there is $[v, \bar{u}]^{10} F = \bar{u}(vF) - \sum_1^n F_{j\bar{h}} v_j \bar{u}_{\bar{h}}$, therefore $(4)_2$ implies that V is in the Levi kernel N . Hence V is the complex tangent space of a complex sub-foliation of the Levi foliation when the latter exists.

PROPOSITION 1'. *Let V be any module of C^∞ complex vector fields, of constant dimension $n-k$ near p , tangent to S . Condition $(4)_2$ implies that the map $z \mapsto V_z$ of S into the complex grassmannian $G(n-k, n)$ is a CR map, and vice versa.*

For $k=1$ (Levi-flat S) condition (3) is void and the problem of characterizing smooth $(n-1)$ -cylinders is somehow related to the search of sufficient conditions for the holomorphic extension of a C^∞ function from a C^∞ curve in \mathbb{C} . So there are few hopes for that. In the real analytic case all Levi flat submanifolds of any dimension are cylinders over a real curve. This is proved in [8] and Bedford improved the result for singular S ([2]). In [8] there is also an example of a 1-disk moving in \mathbb{C}^2 by a composition of a translation with an oscillating motion having diverging frequency and rapidly decreasing amplitude; the disk describes a Levi-flat hypersurface which is not a cylinder.

Theorem 1, in the real analytic case, is known for any k and any codimension of S ([5]). There condition (3) is replaced by an equivalent one similar to our (4), nonpseudoconvexity is unnecessary for the real analytic case. In [4] an

example is shown of a cubic hypersurface which satisfies (2) but is not a cylinder for not having fulfilled also (3). For a characterization of *complex* hypersurfaces which are cylinders see [1].

§ 2. Proofs.

LEMMA. Conditions (2) and (3) imply that N satisfies (4).

Proof. $(4)_1$ is a consequence of $[\mathcal{N}, \mathcal{N}] \subset \mathcal{N}$, so we must only prove

$$(5) \quad \sum_1^n {}_{jh} [v, \bar{u}]_j^{10} F_{j\bar{h}} \bar{w}_h = 0$$

for C^∞ vector fields $u, w \in T, v \in N$.

Assume $F_n = 1$ on S and set $c = \sum_1^n v_j F_{j\bar{n}}$. Since $v \in N$, there is $\sum_1^n v_j F_{j\bar{h}} = c F_{\bar{h}}$ for all $h \leq n$. Application of the operator $\sum_1^n \bar{u}_l \bar{\partial}_l$ to both sides and multiplication by \bar{w}_h give

$$\sum_1^n {}_{jk} [v, u]_j^{10} F_{j\bar{k}} \bar{w}_h = \sum_1^n {}_{jhl} F_{j\bar{h}\bar{l}} v_j \bar{u}_l \bar{w}_h - c \sum_1^n F_{\bar{h}\bar{l}} \bar{u}_l \bar{w}_h.$$

If we take $s = n$ in (3), we have the desired result.

COROLLARY. Theorem 1' and proposition 1' imply theorem 1 and proposition 1 respectively.

Proof. Take $V = N$ and apply the lemma above.

In the next proofs we take coordinates with origin at p , such that the (z_1, \dots, z_k) -plane is transversal to V at p , and set $z' = (z_1, \dots, z_k)$, $z'' = (z_{k+1}, \dots, z_n)$.

Proof of proposition 1'. For z^0 near p , $V(z^0)$ has equations

$$z_A - z_A^0 = \sum_{k+1}^n V_{aA}(z^0) (z_a - z_a^0), \quad A = 1, \dots, k.$$

We must prove

$$(6) \quad \sum_1^n \bar{u}_j \bar{\partial}_j V_{aA} = 0, \quad \text{for all } 1 \leq A \leq k < a \leq n, u \in T.$$

The vectors $e_a = \partial_a + \sum_1^k V_{aA} \partial_A$ are a basis for V ($a = k+1, \dots, n$). For all vector fields $v \in V, u \in T$ of class C^∞ , we have by (4)₂

$$\sum_1^n \bar{u}_j (\bar{\partial}_j v_h) \partial_h = \sum_{k+1}^n c_a e_a.$$

Replace here v by e_b ($k+1 \leq b \leq n$). Taking the last $n-k$ components of both sides we obtain $c_{k+1} = \dots = c_n = 0$. The consequent vanishing of the first k components of the left side gives (6). Viceversa (6) implies $[e_a, \bar{u}]^{10} = 0$, for all $u \in T$ and $a = k+1, \dots, n$, i.e. $(4)_2$.

Proof of theorem 1'. In both cases (i) and (ii) L is non degenerate at p , so, by (6), H. Lewy Theorem ([7] or [6] th. 2.6.13) applies to the restrictions to S of the functions V_{aA} and there exists a neighbourhood U of p such that those functions extend holomorphically to $U^- \equiv \{z \in U \mid F(z) < 0\}$, C^∞ on \bar{U}^- . In the case (i) U^- is not pseudoconvex, so V_{aA} can be furtherly continued to U (shrunk if necessary) past p . The new holomorphic functions V_{aA} satisfy by $(4)_1$ the identity

$$\partial_a V_{bA} - \partial_b V_{aA} + \sum_{B=1}^k V_{aB} (\partial_B V_{bA} - \partial_B V_{aA}) = 0, \quad \text{for } 1 \leq A \leq k < a, b \leq n,$$

on S , hence on U .

Hence, by the holomorphic version of Frobenius classical theorem, there is a holomorphic vector function $h = (h_{k+1}, \dots, h_n)$ on U such that

$$\partial_a h_A(z) = V_{aA}[h(z), z''], \quad \text{for } 1 \leq A \leq k < a \leq n, \quad \text{and } h(z', 0) = z'.$$

The coordinates ζ in U defined by $z' = h(\zeta', z'')$, $z'' = \zeta''$ give S the equation (1). For the second part we only need to note that the first one-sided holomorphic extension V_{aA} can be taken of class C^∞ on U .

Q.E.D.

Note that, for real analytic S , the CR condition (6) on V_{aA} allows to extend holomorphically those functions independently of the non convexity of S and of $k \geq 2$. This proves the mentioned Freeman's theorem in the case of hypersurfaces.

§ 3. *Example.* We want to show a pseudoconvex limit of 1-cylinders in \mathbb{C}^3 , satisfying the hypothesis of Theorem 1 (ii), which is not a cylinder. Let $\lambda(z_1)$ be holomorphic on $|z_1| < 1$, C^∞ up to the boundary, not holomorphically extendable past $z_1 = 1$. Consider the family of complex lines.

$$\mathcal{F} \begin{cases} z_1 = z_1^0 + \lambda(z_1^0) z_3 \stackrel{\text{def}}{=} h_1(z^0, z_3) \\ z_2 = z_2^0 + z_3 \stackrel{\text{def}}{=} h_2(z^0, z_3) \end{cases} \quad z^0 = (z_1^0, z_2^0), |z^0| = 1.$$

This family describes a hypersurface $S \subset \mathbb{C}^3$ which will be studied near the point $p = (1, 0, 0)$. If $z(\zeta)$ is a holomorphic disk on S , there must exist a smooth map $z^0(\zeta)$ such that $z_A(\zeta) = h_A[z^0(\zeta), z_3(\zeta)]$, ($A = 1, 2$). Derivation with respect to $\bar{\zeta}$ gives that $z^0(\zeta)$ must be holomorphic, and since $|z^0(\zeta)| = 1$, constant. Therefore S does not contain other 1-dimensional complex submanifold than the lines of \mathcal{F} . In particular S is not a 2-cylinder. If S were a 1-cylinder $\phi(\zeta_1, \zeta_2) = 0$, then the generating lines $\zeta_3 = \text{var.}$ must be the

family \mathcal{F} . Let $\zeta_j = f_j(z)$ be the change of coordinates, $z_j = g_j(\zeta)$ its inverse. By the previous argument $\partial g_3 / \partial \zeta_3$ is different from zero, so the equation $g_3(\zeta) = 0$ has an holomorphic solution $\zeta_3 = H(\zeta_1, \zeta_2)$. Consider the holomorphic function $\tilde{G}(z) = z_1 - g_1\{f_1(z), f_2(z), H[f_1(z), f_2(z)]\}$. There is $\tilde{G}[h_1(z^0, z_3), h_2(z^0, z_3), z_3] = z_1 - z_1^0$, for $|z^0| = 1$ near $(1, 0)$. Moreover $\tilde{G}(z_1, z_2, 0) = 0$. Hence $\tilde{G}(z) = z_3 G(z)$, and G is holomorphic near $(1, 0, 0)$. Then $G(z_1, z_2, 0) = \lambda(z_1)$ in a neighbourhood of $(1, 0)$ in \mathbb{C}^2 would be a continuation of λ past $z_1 = 1$. We still must prove that S satisfies (2) and (3). We will prove that S is the limit (uniform with derivatives) of 1-cylinders, independently of Theorem 1 (ii), since cylinders satisfy (3), S will also satisfy by continuity. Consider the hypersurface S_ε defined like S but with $|z^0| = 1 - \varepsilon$. For $\varepsilon > 0$ S_ε is a cylinder, with the coordinates ζ given by $z_A = h_A(\zeta_1, \zeta_2, z_3)$, ($A = 1, 2$), $z_3 = \zeta_3$. S_ε are, by the way, the same cylinders of Theorem 1 (ii). Since S_ε has strictly pseudoconvex section it satisfies (3) and $S_\varepsilon \rightarrow S$. Finally S is pseudoconvex as \mathbb{C}^2 -limit of pseudoconvex hypersurfaces, so the lines \mathcal{F} have, as complex tangent space the Levi kernel of S , hence S satisfies also (2) with $k = 2$.

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