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EUGENIO SINISTRARI

**Asymptotic behaviour of solutions of a non linear
model of population dynamics**

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Analisi matematica. — *Asymptotic behaviour of solutions of a non linear model of population dynamics.* Nota (*) di EUGENIO SINISTRARI (**), presentata dal Socio G. SANSONE.

RIASSUNTO. — Si studia l'esistenza e l'unicità delle soluzioni stazionarie di una equazione funzionale non lineare proveniente dalla dinamica di popolazione e se ne dimostra la stabilità.

1. INTRODUCTION

In a previous paper [1] we introduced a non linear version of the classical Lotka-Von Foerster equations which leads to the problem of finding $u(a, t) \geq 0$ such that

$$(P) \quad \begin{cases} Du(a, t) = -m(a, u(a, t)) u(a, t) & 0 \leq a < \omega, t \geq 0. \\ u(0, t) = \int_0^{\omega} b(a, u(a, t)) u(a, t) da & t > 0 \\ u(a, 0) = p(a) & 0 \leq a < \omega \end{cases}$$

where $Du(a, t) = \lim_{h \rightarrow 0} \frac{u(a+h, t+h) - u(a, t)}{h}$, m, b and p are given

functions and ω is a given positive number. We will set $A = [0, \omega[$ and $u(0, t) = B(t)$. For the physical meaning of the problem we refer to [1].

Global existence and uniqueness results for the solution to (P) were obtained under the following assumptions:

(m_1) $m(a, u)$ is continuous and non negative on $A \times \mathbb{R}_+$

(m_2) $u \rightarrow m(a, u)$ is non decreasing

(m_3) given $a \in A$ and $\delta > 0$, $\lim_{k \rightarrow \infty} \int_a^k m(x, u) dx = +\infty$ uniformly for $u \leq \delta$

(b_1) $b(a, u)$ is continuous and non negative on $A \times \mathbb{R}_+$ and $b^* = \sup b < +\infty$

(b_2) given $\delta > 0$, there exists $L = L(\delta)$ such that $|b(a, u') - b(a, u'')| \leq L |u' - u''|$ for $a \in A$ and $0 \leq u', u'' \leq \delta$.

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(**) Istituto Matematico «G. Castelnuovo», Università di Roma.

(p_1) p is piecewise continuous and non negative on A

(p_2) $p^* = \sup p$ and $P_0 = \int_0^\omega p(a) da$ are finite.

In this paper we need also the following conditions:

(m_4) $m_u(a, u)$ exists continuous on $A \times \mathbb{R}_+$

(b_3) $b_u(a, u) \leq 0$ and is continuous on $A \times \mathbb{R}_+$

2. STATIONARY SOLUTIONS

In this section we want to give conditions for the existence of stationary solutions of problem (P): they correspond to the equilibrium age distributions for the population.

DEFINITION 1. A function $a \rightarrow p(a)$ from A to \mathbb{R}_+ is a stationary solution of (P) if the following equations are satisfied:

$$(S) \quad \begin{cases} p'(a) = -m(a, p(a)) p(a) \\ p(0) = \int_0^\omega b(a, p(a)) p(a) da \end{cases} \quad a \in A$$

We shall assume $p(0) = \varepsilon > 0$ so that $p \not\equiv 0$; in [1] we proved the existence and uniqueness of the solution of (S₁) in A , when $p(0)$ is a prescribed positive number.

PROPOSITION 1. Let $p_\varepsilon: A \rightarrow \mathbb{R}_+$ be a solution to

$$(I) \quad \begin{cases} p'(a) = -m(a, p(a)) p(a) \\ p(0) = \varepsilon \end{cases} \quad a \in A$$

then p_ε is a stationary solution to (P) if and only if

$$F(\varepsilon) = \int_0^\omega b(a, p_\varepsilon(a)) p_\varepsilon(a) \cdot \varepsilon^{-1} da = 1.$$

LEMMA 1. The function $\varepsilon \rightarrow F(\varepsilon)$ is non increasing on $]0, +\infty[$ so that there exist $F(0^+)$ and $F(\infty)$. If $u \rightarrow m(a, u)$ and $u \rightarrow b(a, u)$ are strictly monotonic then F is strictly decreasing.

Proof. If $0 < \varepsilon < \varepsilon'$, then $p_\varepsilon < p_{\varepsilon'}$. From (I) we deduce that $p_\varepsilon(a) = \varepsilon \exp\left(-\int_0^a m(x, p_\varepsilon(x)) dx\right)$ hence $\varepsilon \rightarrow p_\varepsilon(a) \varepsilon^{-1}$ is non increasing by (m_2);

from (b_3) it follows that $\varepsilon \rightarrow F(\varepsilon)$ is non increasing. The last part of the theorem is obvious.

We give now conditions for the existence and uniqueness of stationary solutions to (P).

THEOREM 1. *If there is a stationary solution then $F(0^+) \geq 1$ and $F(\infty) \leq 1$. Conversely let $F(0^+) > 1$ and $F(\infty) < 1$: then there exists stationary solutions; if in addition $u \rightarrow m(a, u)$ and $u \rightarrow b(a, u)$ are strictly monotonic then the stationary solution is unique.*

The proof is a consequence of lemma 1.

In many practical situations, $p_\varepsilon(a)$ can be written in closed form so that $F(0^+)$ and $F(\infty)$ can be computed explicitly.

3. STABILITY OF STATIONARY SOLUTIONS.

In this section we shall suppose that there exists a stationary solution $p_\varepsilon(a)$ to (P) and we want to investigate the asymptotic behaviour of a solution to (P), close to p_ε at $t = 0$.

Let $u: A \times \mathbb{R}_+ \rightarrow \mathbb{R}_+$ be a solution to (P). Set

$$\begin{cases} r(a, t) = u(a, t) - p_\varepsilon(a) \\ R(t) = r(0, t) = B(t) - \varepsilon \\ \rho(a) = r(a, 0) = p(a) - p_\varepsilon(a). \end{cases}$$

With these notations and taking into account (P) and (S) we can write the equations satisfied by $r(a, t)$:

$$(R) \quad \begin{cases} Dr(a, t) = -\lambda(a, t)r(a, t) & a \in A, t \geq 0 \\ r(0, t) = \int_0^\infty H(a, t)r(a, t) da & t > 0 \\ r(a, 0) = \rho(a) & a \in A \end{cases}$$

where

$$\begin{cases} \lambda(a, t) = m_u(a, p_\varepsilon(a) + \theta r(a, t))p_\varepsilon(a) + m(a, p_\varepsilon(a) + r(a, t)) \\ H(a, t) = b_u(a, p_\varepsilon(a) + \theta' r(a, t))p_\varepsilon(a) + b(a, p_\varepsilon(a) + r(a, t)) \end{cases}$$

with suitable $\theta, \theta' \in [0, 1]$.

From (R) it follows that

$$r(a, t) = \begin{cases} R(t-a) \exp \left(- \int_0^a \lambda(x, t-a+x) dx \right) & a < t \\ \rho(a-t) \exp \left(- \int_0^t \lambda(a-t+x, x) dx \right) & a \geq t \end{cases}$$

hence from (R₂) we obtain an integral equation which is satisfied by $R(t)$:

$$(2) \quad R(t) = \int_0^t K(a, t) R(t-a) da + f(t) \quad t \geq 0$$

where:

$$K(a, t) = \begin{cases} H(a, t) \exp \left(- \int_0^a \lambda(x, t-a+x) dx \right) & a \leq t, a < \omega \\ 0 & a \geq t, a \geq \omega \end{cases}$$

and

$$f(t) = \begin{cases} \int_t^\omega H(a, t) \exp \left(- \int_0^t \lambda(a-t+x, x) dx \right) \rho(a-t) da, & 0 \leq t \leq \omega \\ 0 & t \geq \omega. \end{cases}$$

We give now a theorem about the stability of a stationary solution to (P).

THEOREM 2. *Let $p_*(a)$ be a stationary solution such that the following condition holds:*

$$(L) \quad \int_0^\omega |b_u(a, p_*(a)) p_*(a) + b(a, p_*(a))| \exp \left(- \int_0^a (m_u(x, p_*(x)) p_*(x) + m(x, p_*(x))) dx \right) da < 1$$

Then p_ is locally stable i.e. for each $\eta > 0$ there exists δ_η such that if u is a solution to (P) with $|u(a, 0) - p_*(a)| < \delta_\eta$ for $a \in A$ then $|u(a, t) - p_*(a)| \leq \eta$ for $a \in A$ and each $t \geq 0$.*

Condition (L) is verified for example when $b_u(a, u) < 0$ and $b_u(a, u)u + b(a, u) \geq 0$ or when b does not depend on u and for each \bar{u} , $m_u(a, \bar{u}) \equiv 0$ on A . When $b_u \equiv m_u \equiv 0$, i.e. in the linear case, the behaviour of solutions is well known (see [2]).

Proof. Let us denote by L the integral in condition (L). From (b_3) and (m_4) it is not difficult to prove that given $\gamma \in]L, 1[$ there exists $\delta > 0$ such that if $t > \omega$ and $|R(s)| < \delta$ for $s \in [0, t[$ then

$$(3) \quad \int_0^\omega |K(a, t)| da < \gamma < 1.$$

By using Theorem 5 of [1] it is possible to find a constant c such that if $|\rho(a)| < 1$ then for $0 \leq t < \omega$

$$(4) \quad |R(t)| \leq c \int_0^\omega |\rho(a)| da.$$

Let us choose $\eta < 1$. Then by taking $\delta_\eta = \min(\eta, \delta(\omega c)^{-1}, \eta(\omega c)^{-1})$ it can be proved by contradiction that (3) holds for every t . From this the conclusion follows easily.

We give now a last result which gives more precise informations about the behaviour of the birth rate $B(t) = u(0, t)$ for large t .

THEOREM 3. *Let p_ε be a stationary solution such that (L) holds; then there exist c and $\delta > 0$ such that if u is a solution to (P) with $|u(a, 0) - p_\varepsilon(a)| < \delta$ for $a \in A$ then we have $|u(0, t) - \varepsilon| \sim \exp(-ct)$.*

Proof. Take $\gamma \in]L, 1[$ and choose $c > 0$ such that $\gamma \exp(c\omega) < 1$. Set $G(t) = R(t) \exp(ct)$. We must show that $G(t)$ is bounded when $|\rho(a)| < \delta$ where δ is defined in the proof of Theorem 2. From (2) we get for $t \in [\omega, T]$:

$$|G(t)| \leq \sup_{t \in [0, T]} |G(t)| \int_0^\omega |K(a, t)| \exp(ca) da \leq \left(\sup_{t \in [0, \omega]} |G(t)| + \sup_{t \in [\omega, T]} |G(t)| \right) \gamma \exp(c\omega).$$

Hence

$$(1 - \gamma \exp(c\omega)) \sup_{t \in [\omega, T]} |G(t)| \leq \sup_{t \in [0, \omega]} |G(t)|.$$

Letting $T \rightarrow +\infty$, the conclusion follows.

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