
ATTI ACCADEMIA NAZIONALE DEI LINCEI
CLASSE SCIENZE FISICHE MATEMATICHE NATURALI
RENDICONTI

LU-SAN CHEN, CHEH-CHIH YEH

**Comparison theorems and integrability of
nonoscillatory solutions of n-th order functional
differential equations**

*Atti della Accademia Nazionale dei Lincei. Classe di Scienze Fisiche,
Matematiche e Naturali. Rendiconti, Serie 8, Vol. 62 (1977), n.3, p. 321–324.*

Accademia Nazionale dei Lincei

<http://www.bdim.eu/item?id=RLINA_1977_8_62_3_321_0>

L'utilizzo e la stampa di questo documento digitale è consentito liberamente per motivi di ricerca e studio. Non è consentito l'utilizzo dello stesso per motivi commerciali. Tutte le copie di questo documento devono riportare questo avvertimento.

*Articolo digitalizzato nel quadro del programma
bdim (Biblioteca Digitale Italiana di Matematica)
SIMAI & UMI*

<http://www.bdim.eu/>

Equazioni differenziali ordinarie. — *Comparison theorems and integrability of nonoscillatory solutions of n -th order functional differential equations* (*). Nota di LU-SAN CHEN e CHEH-CHIH YEH, presentata (**) dal Socio G. SANSONE.

RIASSUNTO. — Si dimostrano tre teoremi sugli integrali di una equazione funzionale, differenziale, non lineare con argomento ritardato.

1. INTRODUCTION

The results of this note are inspired by two recent papers of Liu [2] and Rankin [4]. The method of these authors can be used to prove three theorems for general n -th order ($n \geq 2$) functional differential non-linear equation with retarded argument

$$(1) \quad L_n x(t) + [q(t)x(t)]' + p(t)f[x(g(t))] = h(t)$$

where the operators L_i are recursively defined by

$$L_0 x(t) = x(t) \quad , \quad L_i x(t) = \frac{1}{r_i(t)} \frac{d}{dt} L_{i-1} x(t), \quad i = 1, 2, \dots, n,$$

$$r_n(t) = 1.$$

It is assumed throughout this note that

$$(i) \quad r_i(t) \in C[R_+ \equiv [0, \infty), R_+ \setminus \{0\}],$$

$$\int_0^\infty r_i(t) dt = \infty, \quad i = 1, 2, \dots, n;$$

$$(ii) \quad p(t), q(t), g(t), h(t) \in C[R_+, R \equiv (-\infty, \infty)],$$

$$\lim_{t \rightarrow \infty} g(t) = \infty \quad \text{and} \quad q(t) \geq 0;$$

$$(iii) \quad f(y) \in C[R, R], yf(y) > 0 \quad \text{for} \quad y \neq 0.$$

A nontrivial solution of (1) which exists on $[\tau, \infty)$, for some fixed τ , is called *oscillatory* if it has arbitrary large zeros. Otherwise, it is said to be *nonoscillatory*.

(*) This research was supported by the National Science Council.

(**) Nella seduta del 12 marzo 1977.

2. INTEGRABILITY OF NONOSCILLATORY SOLUTIONS

THEOREM 1. Let the functions r_i, p, q, g, h and f satisfy (i)-(iii) and, in addition, suppose that

$$(C_1) \quad p(t) \geq M \text{ on } [\tau, \infty) \text{ for some constant } M > 0,$$

$$(C_2) \quad 0 \leq g'(t) \leq 1 \text{ on } [\tau, \infty),$$

$$(C_3) \quad \int_{\tau}^{\infty} |h(t)| dt < \infty,$$

$$(C_4) \quad \text{There exists a constant } K \text{ such that for } y \neq 0$$

$$\frac{f(y)}{y} \geq K.$$

Then every nonoscillatory solution of (1) on $[\tau, \infty)$ is integrable.

Proof. Let $x(t)$ be a nonoscillatory solution of (1) on $[\tau, \infty)$. Without loss of generality, we may assume that there is a $T_0 \geq \tau$ such that $x(t) > 0$ for $t \geq T_0$. From (ii) we see that there is a $T_1 \geq T_0$ such that $g(t) \geq T_0$ and $x(g(t)) > 0$ for $t \geq T_1$.

Integrating (1) from T_1 to $t \geq T_1$ and using conditions (C_1) -(C_4), we have

$$(2) \quad L_{n-1}x(t) - L_{n-1}x(T_1) + q(t)x(t) - q(T_1)x(T_1) + \\ + \int_{T_1}^t p(s)f[x(g(s))]ds \leq \int_{T_1}^t |h(s)|ds,$$

or

$$(3) \quad L_{n-1}x(t) - L_{n-1}x(T_1) - q(T_1)x(T_1) + MK \int_{T_1}^t x(g(s))ds \leq \int_{T_1}^t |h(s)|ds.$$

It follows from (C_3) that the left hand side of (3) remains bounded as $t \rightarrow \infty$. Suppose $\int_{T_1}^{\infty} x(g(s))ds = \infty$. Then $\lim_{t \rightarrow \infty} L_{n-1}x(t) = -\infty$. This and (i) imply that $\lim_{t \rightarrow \infty} x(t) = -\infty$, a contradiction. Therefore, we have

$$(4) \quad \int_{T_1}^{\infty} x(g(s))ds < \infty.$$

By (C₂) and change of variable, we get

$$(5) \quad \infty > \int_{T_1}^{\infty} x(g(s)) ds \geq \int_{T_1}^{\infty} g'(s) x(g(s)) ds = \int_{g(T_1)}^{\infty} x(t) dt.$$

Hence the proof is complete.

Remark 1. Taking $r_{n-1}(t) = r(t)^{-1}$, $r_i(t) \equiv 1$, $i = 1, 2, \dots, n-2$ and $f(x) \equiv x$, then Liu's result [2] is a special case of our theorem.

Remark 2. For the case $n = 2$, $r_1(t) \equiv 1$, $f(x) \equiv x$ and $q(t) \equiv 0$, the equation (1) is studied by Dahiya and Singh [1]. In the assumptions of our theorem, we do not require the condition $p(t)p''(t) \leq 2(p'(t))^2$ and the boundedness of the delay term $\tau(t) = t - g(t)$ which are assumed in [1].

3. COMPARISON THEOREMS

In this section, we compare the following two equations:

$$(5) \quad L_n x(t) + p(t)x(g(t)) = h(t),$$

$$(7) \quad L_n x(t) + p(t)x(g(t)) = 0.$$

A solution $x(t)$ of equation (6) (resp. 7) is termed *oscillatory* if it has an increasing sequence of zeros $\{t_n\}$ on $[\tau, \infty)$ such that $\lim_{n \rightarrow \infty} t_n = \infty$.

Equation (6) (resp. 7) is called *oscillatory* if all its solutions are oscillatory. Equation (6) (resp. 7) is called *nonoscillatory* if every solution is nonoscillatory.

THEOREM 2. *Assume that the equation (7) is oscillatory, then every pair of nonoscillatory solutions of equation (6) eventually has the same sign.*

Proof. Suppose $x(t)$ and $y(t)$ are nonoscillatory solutions of (6), then $W(t) = x(t) - y(t)$ is a solution of (7).

By hypothesis there exists an infinite sequence $\{t_n\}$ of zeros of $W(t)$. Hence $x(t_n) = y(t_n)$ for all n , implying that $x(t)$ and $y(t)$ have the same sign for large t .

Recently, Lovelady [3] proved the following theorem.

THEOREM 3. *If*

$$(8) \quad \int_0^{\infty} \omega_{n-1}(t) p(t) dt = \infty$$

where $\omega_i(t) \in C[R_+, R_+]$, $i = 1, 2, \dots, n-1$ are defined by

$$\omega_1(t) = \int_0^t r_1(s) ds, \quad \omega_k(t) = \int_0^t r_k(s) \omega_{k-1}(s) ds, \quad k = 2, 3, \dots, n-1.$$

then every bounded solution of the equation

$$(9) \quad L_n x(t) + (-1)^n p(t) x(g(t)) = 0, \quad (p(t) > 0)$$

is oscillatory.

From Theorems 2 and 3, we easily see that the following holds.

COROLLARY. *Let condition (8) hold. Then every pair of nonoscillatory bounded solutions of the equation*

$$(10) \quad L_n x(t) + (-1)^n p(t) x(g(t)) = h(t), \quad (p(t) > 0)$$

eventually has the same sign.

Remark 3. Taking $n = 2$, $r_1(t) = r(t)^{-1}$ and $g(t) \equiv t$, then Rankin's results [4, Theorem 9] is a special case of our result [Theorem 2].

REFERENCES

- [1] R. S. DAHIYA and B. SINGH (1975) - *Certain results on nonoscillatory and asymptotic nature of delay equations*, « Hiroshima Math. J. », 5, 7-15.
- [2] T. S. LIU (1976) - *Integrability of nonoscillatory solutions of a delay differential equations*, « Hiroshima Math. J. », 6, 293-295.
- [3] D. L. LOVELADY (1975) - *On the oscillatory behavior of bounded solution of higher order differential equations*, « J. Diff. Eqs. », 19, 167-175.
- [4] S. M. RANKIN (1976) - *Oscillation theorems for second order non-homogenous linear differential equations*, « J. Math. Anal. Appl. », 53, 550-553.