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## Classe Scienze Fisiche Matematiche Naturali Rendiconti

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# On holornorphically subprojective Kählerian manifolds, II 

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Geometria differenziale. - On holomorphically subprojective Kählerian manifolds, II. Nota di Seifchi Yamaguchi e Tyuzi Adati, presentata (*) dal Socio B. Segre.

RIASSUNTO. - La nozione di varietà olomorficamente sottoproiettiva è stata introdotta dagli Autori in un altro lavoro [6]. Qui si definiscono e studiano quelle fra tali varietà che risultano kähleriane di $\mathrm{I}^{a}$ o di $2^{a}$ specie.

## i. Introduction

An $n$-dimensional affinely connected manifold $\mathrm{A}_{n}$ is said to be subprojective if there exists a coordinate system such that every geodesic is given with respect to this system by $n-2$ homogeneous linear equations and one further equation that need not be linear.

The present authors have introduced in a previous paper [6] the notion of holomorphically subprojective Kählerian manifold as follows. Let us consider an $n$ complex dimensional Kählerian manifold $M$. If there exists a complex coordinate system such that every holomorphically planar curve is given with respect to this system by $n-2$ homogeneous linear equations and one further equation that need not be linear, then M is called a holomorphicaliy subprojective Kählerian manifold.

In this paper, we investigate the differential geometric properties of the holomorphically subprojective Kählerian manifolds of the first and second kind. In § 2 we shall recall the identities and theorems in a Kählerian manifold with vanishing Bochner curvature tensor and, in §3, we give a short summary of holomorphically subprojective Kählerian manifolds which are necessary for what follows. Moreover the holomorphically subprojective Kählerian manifolds of the first and second kind are defined. The holomorphically subprojective Kählerian manifold of the first kind is studied in §4.

## 2. Kählerian manifolds with vanishing Bochner curvature tensor

Let us consider a $2 n$ real dimensional Kählerian manifold $M$ with complex structure J and Riemannian metric $g$ which satisfy the following relations

$$
\begin{gathered}
\mathrm{J}_{j}^{r} \mathrm{~J}_{r}{ }^{\boldsymbol{1}}=-\delta_{j}{ }^{\mathbf{i}}, \quad g_{j i}=\mathrm{J}_{j}^{r} \mathrm{~J}_{i}{ }^{s} g_{r s} \quad, \quad \nabla_{j} \mathrm{~J}_{i}^{h}=\mathrm{o}, \\
(h, i, j, \cdots, r, s, t, \cdots=\mathrm{I}, 2,3, \cdots, 2 n)
\end{gathered}
$$

$\nabla$ being the operator of covariant derivation with respect to the Riemannian connection defined by $g$. Denote by $\mathrm{R}_{k j i}{ }^{h}, \mathrm{R}_{k j}$ and R the Riemannian curvature tensor, the Ricci tensor and the scalar curvature respectively.
(*) Nella seduta del io aprile 1976.

The tensor field defined by

$$
\begin{gather*}
\mathrm{K}_{k j i}^{h}=\mathrm{R}_{k j i}^{h}+\left(\mathrm{L}_{k i} \delta_{j}^{h}-\mathrm{L}_{j i} \delta_{k}^{h}+g_{k i} \mathrm{~L}_{j}^{h}-g_{j i} \mathrm{~L}_{k}^{h}\right.  \tag{2.1}\\
\left.+\mathrm{M}_{k i} \mathrm{~J}_{j}^{h}-\mathrm{M}_{j i} \mathrm{~J}_{k}^{h}+\mathrm{J}_{k i} \mathrm{M}_{j}^{h}-\mathrm{J}_{j i} \mathrm{M}_{k}^{h}+2 \mathrm{M}_{k j} \mathrm{~J}_{i}^{h}+2 \mathrm{~J}_{k j} \mathrm{M}_{i}^{h}\right) /[2(n+2)]
\end{gather*}
$$

is called the Bochner curvature tensor, where we have put

$$
\begin{equation*}
\mathrm{L}_{j i}=\mathrm{R}_{j i}-\mathrm{R} g_{j i} /[4(n+\mathrm{I})] \mathrm{M}_{j i}=\mathrm{J}_{j}{ }^{r} \mathrm{~L}_{r i} . \tag{2.2}
\end{equation*}
$$

In a Kählerian manifold $M$ with vanishing Bochenr curvature tensor, the following equation

$$
\begin{gather*}
4(n+\mathrm{I}) \nabla_{k} \mathrm{R}_{j i}=g_{k i} \nabla_{i} \mathrm{R}+g_{k j} \nabla_{j} \mathrm{R}+2 g_{j i} \nabla_{k} \mathrm{R}  \tag{2.3}\\
-\mathrm{J}_{k j} \mathrm{~J}_{i}^{r} \nabla_{r} \mathrm{R}-\mathrm{J}_{k i} \mathrm{~J}_{j}^{r} \nabla_{r} \mathrm{R}
\end{gather*}
$$

has been obtained by M. Matsumoto [3]. Furthermore M. Matsumoto and S. Tanno [4] have proved

Theorem A. If a Kählerian manifold M with vanishing Bochner curvature tensor has constant scalar curvature, then M is one of the following manifolds:
(I) M is a manifold of constant holomorphic sectional curvature.
(2) M is a locally product manifold of two manifolds of constant holomorphic sectional curvature $\mathrm{H}(\geqq \mathrm{o})$ and -H .

## 3. Holomorphically subprojective Kählerian manifolds

Now, in what follows, we always agree to adopt the following convention: (ij) (resp. [ij]) for indices $i$ and $j$ means the symmetric (resp. shew-symmetric) part with respect to indices $i$ and $j$, for example

$$
u_{(i j)}=u_{i j}+u_{j i} \quad\left(\text { resp. } u_{[i j]}=u_{i j}-u_{j i}\right) .
$$

As for a holomorphically subprojective Kählerian manifold, we have obtained the following in [6]:

Theorem B. In order that a $2 n(n \geqq 3)$ real dimensional Kählerian manifold be holomorphically subprojective, it is necessary and sufficient that there exists a local real coordinate system $\left(x^{i}\right)$ such that the Christoffel symbol of M may take the form

$$
\begin{gather*}
\left\{\begin{array}{c}
h \\
i j
\end{array}\right\}=\rho_{(i} \delta_{j)}^{h}+\stackrel{\rho}{\rho}_{(i} \mathrm{J}_{j)}^{h}+f_{j i} x^{h}-f_{j r} \mathrm{~J}_{i}^{r} \hat{x}^{h},  \tag{3.I}\\
f_{[j i]}=0 \quad, \quad f_{r[j} \mathrm{J}_{i]}^{r}=0, \tag{3.2}
\end{gather*}
$$

where $\rho_{i}$ and $f_{j i}$ are covariant vector and tensor fields respectively, and we have put $\check{x}^{h}=\mathrm{J}_{r}^{h} x^{r}$ and $\stackrel{\rightharpoonup}{\rho}_{h}=-\mathrm{J}_{h}{ }^{r} \rho_{r}$.

Now we put

$$
Q_{k j i}=\partial_{[k} f_{j] i}+x^{r} f_{r[k} f_{j] i}-\ddot{x}^{r} f_{r[k} f_{j] s} \mathrm{~J}_{i}^{s}, \quad \partial_{k} f_{j i}=\frac{\partial f_{j i}}{\partial x^{k}},
$$

$$
\begin{gather*}
\lambda|x|^{2}=\mathrm{Q}_{k r}^{r} x^{k}, \varepsilon|x|^{4}=\mathrm{Q}_{k j i} \stackrel{x}{ }^{k} x^{j} \stackrel{x}{x}^{i},|x|^{2}=g_{j i} x^{j} x^{i},  \tag{3.4}\\
\mathrm{H}_{j i}=\partial_{i} \rho_{j}-\rho_{i} \rho_{j}+\tilde{\rho}_{i} \tilde{\rho}_{j}+\mathrm{F}_{j i}, \quad \mathrm{~F}_{j i}=-\left(k+\rho_{r} x^{r}\right) f_{j i}+\rho_{r} \check{x}^{r} f_{j s} J_{i}^{s},  \tag{3.5}\\
a|x|^{2}=\mathrm{H}_{j i} x^{j} x^{i} . \tag{3.6}
\end{gather*}
$$

As for these quantities, the following relations have been introduced in [6]:

$$
\begin{equation*}
\partial_{j} \rho_{i}=\partial_{i} \rho_{j}, \tag{3.7}
\end{equation*}
$$

$$
\begin{align*}
& 2(n-\mathrm{I})|x|^{2} \mathrm{Q}_{k j i}+(\lambda+\varepsilon)|x|^{2}\left(\mathrm{~J}_{i[k} \dot{x}_{j]}+2 \stackrel{x}{x}_{i} \mathrm{~J}_{j k}\right.  \tag{3.10}\\
& \left.\quad+g_{i[k} x_{j]}\right)+2\{2 \lambda+(n+\mathrm{I}) \varepsilon\} \ddot{x}_{i} \ddot{x}_{[j} x_{k]}=\mathrm{o}
\end{align*}
$$

(3.I I) $\quad \mathrm{R}_{k j i h}=\left\{a+\frac{\lambda+\varepsilon}{2(n-\mathrm{I})}|x|^{2}\right\}\left(g_{i[k} g_{j] h}-\mathrm{J}_{i[k} \mathrm{J}_{j] h}+2 \mathrm{~J}_{k j} \mathrm{~J}_{i h}\right)$

$$
\begin{gathered}
-\frac{\lambda+\varepsilon}{2(n-\mathrm{I})}\left[\left(\mathrm{J}_{i[k} \stackrel{\rightharpoonup}{x}_{j]}+2 \mathrm{~J}_{j k} \stackrel{\rightharpoonup}{x}_{i}-g_{i[j} x_{k]}\right) x_{h}-\left(\mathrm{J}_{i[k} x_{j]}+2 \mathrm{~J}_{j k} x_{i}\right.\right. \\
\left.\left.+g_{i[j} \stackrel{\rightharpoonup}{x}_{k]}\right) \stackrel{x}{x}_{h}+x_{i}\left(x_{[k} g_{i] h}-\tilde{x}_{[k} \mathrm{J}_{j] h}\right)+\stackrel{x}{x}_{i}\left(\tilde{x}_{[k} g_{j] h}+x_{[k} \mathrm{J}_{j] h}\right)-2 \mathrm{~J}_{j h} \stackrel{x}{x}_{[k} x_{j]}\right] \\
-\frac{2 \lambda+(n+\mathrm{I}) \varepsilon}{(n-\mathrm{I})|x|^{2}} x_{[k} \tilde{x}_{j]} \tilde{x}_{[i} x_{h]} .
\end{gathered}
$$

Next we give the identities of holomorphically subprojective Kählerian manifolds which are necessary for what follows.

From (3.II) we can find

$$
\begin{equation*}
\mathrm{R}_{k h}=-\left\{2(n+\mathrm{I}) a+\frac{n(\lambda+\varepsilon)|x|^{2}}{n-\mathrm{I}}\right\} g_{k h}+\frac{n \lambda+\varepsilon}{n-\mathrm{I}}\left(x_{k} x_{h}+\tilde{x}_{k} \tilde{x}_{h}\right) \tag{3.12}
\end{equation*}
$$

$$
\begin{equation*}
\mathrm{R}=-4 n(n+\mathrm{I}) a-2\{n \lambda+(n+\mathrm{I}) \varepsilon\}|x|^{2} \tag{3.13}
\end{equation*}
$$

from which, with the aid of these, it follows from (2.2) that

$$
\begin{gather*}
\mathrm{L}_{k h}=-\left\{(n+2) a+\frac{n(n+3) \lambda+(n+\mathrm{I})^{2} \varepsilon}{2(n-\mathrm{I})(n-\mathrm{I})}|x|^{2}\right\} g_{k h}  \tag{3.14}\\
+\frac{n \lambda+\varepsilon}{n-\mathrm{I}}\left(x_{k} x_{h}+\tilde{x}_{k} \check{x}_{h}\right) .
\end{gather*}
$$

Making use of (3.1), we have
(3.15) $\quad \nabla_{j} x_{i}=\left(\mathrm{I}+\rho_{r} x^{r}\right) g_{j i}-\rho_{r} \check{x}^{r} \mathrm{~J}_{j i}+\left(\rho_{j}+f_{j r} x^{r}\right) x_{i}+\left(\tilde{\rho}_{j}+f_{j r} \tilde{x}^{r}\right) \tilde{x}_{i}$, or, equivalently
$(3.15)^{\prime} \quad \nabla_{j} \dot{x}_{i}=\left(\mathrm{I}+\rho_{r} x^{r}\right) \mathrm{J}_{j i}+\rho_{r} \stackrel{\rightharpoonup}{x}^{r} g_{j i}+\left(\rho_{j}+f_{j r} x^{r}\right) \ddot{x}_{i}-\left(\tilde{\rho}_{j}-f_{j r} \stackrel{x}{x}^{r}\right) x_{i}$.
Also, (3.5) and (3.9) yield the following

$$
\begin{gather*}
\nabla_{j} \rho_{i}=-\rho_{j} \rho_{i}+\stackrel{\rightharpoonup}{\rho}_{j} \rho_{i}+f_{j i}+\left[\left\{2(n-\mathrm{I}) a+(\lambda+\varepsilon)|x|^{2}\right\} g_{j i}\right.  \tag{3.16}\\
\left.-(\lambda+\varepsilon)\left(x_{j} x_{i}+\vec{x}_{j} \tilde{x}_{i}\right)\right] /[2(n-\mathrm{I})]
\end{gather*}
$$

by virtue of (3.1).
We try to express the curvature tensor of a holomorphically subprojective Kählerian manifold M by means of the Ricci tensor.

We set $\mathrm{M}^{\prime}=\{\mathrm{P} \in \mathrm{M}: n \lambda+\varepsilon=\mathrm{o}$ at P$\}$. Then in $\mathrm{M}-\mathrm{M}^{\prime}$ the following relation is obtained by straightforward computations:

$$
\begin{equation*}
\mathrm{R}_{k j i h}=(\mathrm{A}+2 \mathrm{BD} / \mathrm{E})\left(g_{k[i} g_{i] h}-\mathrm{J}_{k[i} \mathrm{J}_{j] h}+2 \mathrm{~J}_{k j} \mathrm{~J}_{i h}\right) \tag{3.17}
\end{equation*}
$$

$$
-\mathrm{B}\left(g_{k[i} \mathrm{R}_{j] h}+\mathrm{R}_{k[i} g_{j] h}+\mathrm{J}_{k[i} \mathrm{S}_{j] h}+\mathrm{S}_{k[i} \mathrm{J}_{j] h}+2 \mathrm{~J}_{k j} \mathrm{~S}_{i h}+2 \mathrm{~S}_{k j} \mathrm{~J}_{i h}\right) / \mathrm{E}
$$

$$
+\mathrm{C}\left[\mathrm{~S}_{k j} \mathrm{~S}_{i h}-\mathrm{D}\left(\mathrm{~S}_{k j} \mathrm{~J}_{i h}+\mathrm{J}_{k j} \mathrm{~S}_{i h}\right)+\mathrm{D}^{2} \mathrm{~J}_{k j} \mathrm{~J}_{i h}\right] / \mathrm{E}^{2}
$$

where we put

$$
\begin{gathered}
\mathrm{S}_{k j}=\mathrm{J}_{k}^{r} \mathrm{R}_{r j} \quad, \quad \mathrm{~A}=a+\frac{(\lambda+\varepsilon)|x|^{2}}{2(n-\mathrm{I})} \quad, \quad \mathrm{B}=\frac{\lambda+\varepsilon}{2(n-\mathrm{I})}, \\
\mathrm{C}=\frac{2 \lambda+(n+\mathrm{I}) \varepsilon}{(n-\mathrm{I})|x|^{2}}, \mathrm{D}=-\left\{2(n+\mathrm{I}) a+2 n \mathrm{~B}|x|^{2}\right\}, \mathrm{E}=\frac{n \lambda+\varepsilon}{n-\mathrm{I}} .
\end{gathered}
$$

Thus we have
Theorem 3.I. In $\mathrm{M}-\mathrm{M}^{\prime}$, the curvature tensor of the holomorphically subprojective Mählerian manifold M has the form (3.17).

In order to get further results on holomorphically subprojective Kählerian manifolds, we consider the holomorphically subprojective Kählerian manifolds specified by the functions $\lambda$ and $\varepsilon$.

In the following we shall call a holomorphically subprojective Kählerian manifold with

$$
2 \lambda+(n+1) \varepsilon=0 \quad(\text { resp. } n \lambda+\varepsilon=0)
$$

holomorphically subprojective Kählerian manifold of the first (resp. second) for brevity, we denore by $\mathrm{M}_{1}$ (resp. $\mathrm{M}_{2}$ ) the first (resp. second) kind.

In [6] we have derived the following
Theorem C. $\mathrm{M}_{1}(n \geqq 3)$ is a Kählerian manifold with vanishing Bochner curvature tensor which has the Ricci tensor of the form

$$
\begin{equation*}
\mathrm{R}_{j i}=-\left\{2(n+1) a-n \varepsilon|x|^{2} / 2\right\} g_{j i}-(n+2) \varepsilon\left(x_{j} x_{i}+\tilde{x}_{j} \tilde{x}_{i}\right) / 2 \tag{3.18}
\end{equation*}
$$

As for $\mathrm{M}_{2}$, from (3.12) we have
THEOREM 3.2. In order that a $2 n(n \geqq 3)$ dimensional holomorphically subprojective Kählerian manifold M be $\mathrm{M}_{2}$, it is recessary and sufficient that M is an Einstein manifold.

## 4. Holomorphicallx subprojective Kählerian manifolds OF THE FIRST KIND

In the first place, let us seek the necessary and sufficient condition that a holomorphically subprojective Kählerian manifold $M$ be $M_{1}$.

Let us derive the following
-Theorem 4.I. In order that a $2 n(n \geqq 3)$ dimensional holomorphically subprojective Kählerian manifold M be the holomorphically subprojective Kählerian manifold of the first kind, it is necessary and sufficient that M has a vanishing Bochner curvature tensor.

Proof. Transvecting (2.1) with $\tilde{x}^{k} x^{j} x^{i} \tilde{x}_{h}$ and according to our assumption, that is, $\mathrm{K}_{k j i}^{h}=\mathrm{o}$, it follows that

$$
\begin{equation*}
\mathrm{R}_{k i j h} \tilde{x}^{k} x^{j} x^{i} \tilde{x}^{h}-4|x|^{2} \mathrm{~L}_{k j} x^{k} x^{j} /(n+2)=0 \tag{4.1}
\end{equation*}
$$

By contraction (3.II) with $\tilde{x}^{k} x^{j} x^{i} \tilde{x}^{h}$, we get

$$
\mathrm{R}_{k j i h} \tilde{x}^{k} x^{j} x^{i} \tilde{x}^{h}=-\left(4 a+|x|^{2}\right)|x|^{4}
$$

and in the same way we obtain from (3.14)

$$
\mathrm{L}_{k j}^{\prime} x^{k} x^{j}=-(n+2) a|x|^{2}+\frac{n \lambda-(n+1) \varepsilon}{2(n+1)}|x|^{4}
$$

Consequently we can see that (4.I) denotes $2 \lambda+(n+1) \varepsilon=0$ by means of these. This concludes the proof.

ThEOREM 4.2. $\mathrm{M}_{1}(n \geqq 3)$ is a Kählerian manifold with vanishing Bochner curvature tensor which has the Ricci tensor of the form

$$
\begin{equation*}
\mathrm{R}_{k j}=\alpha g_{k j}+\beta\left(\sigma_{k} \sigma_{j}+\tilde{\sigma}_{k} \tilde{\sigma}_{j}\right), \tag{4.2}
\end{equation*}
$$

27.     - RENDICONTI 1976, vol. LX, fasc. 4.
where $\sigma_{i}$ is a gradient vector, and $\alpha$ and $\beta$ are functions such that

$$
\begin{equation*}
\alpha=-2(n+1) a-n|\sigma|^{2} \beta /(n+2) . \tag{4.3}
\end{equation*}
$$

Proof. For some functions $x$ and $\mu$ we set

$$
\begin{equation*}
\sigma_{i}=x x_{i}-\mu \tilde{x}_{i} \tag{4.4}
\end{equation*}
$$

which yields that

$$
x_{i}=\frac{x \sigma_{i}+\mu \tilde{\sigma}_{i}}{x^{2}+\mu^{2}}, \quad \tilde{x}_{i}=\frac{\varkappa \stackrel{\sigma}{\sigma}_{i}-\mu \sigma_{i}}{x^{2}+\mu^{2}}, \quad|x|^{2}=\frac{|\sigma|^{2}}{x^{2}+\mu^{2}},
$$

and substituting these into (3.18), it follows that

$$
\mathrm{R}_{j i}=-\left\{2(n+\mathrm{I}) a-\frac{n \varepsilon|\sigma|^{2}}{2\left(\chi^{2}+\mu^{2}\right)}\right\} g_{j i}-\frac{(n+2) \varepsilon}{2\left(\chi^{2}+\mu^{2}\right)}\left(\sigma_{j} \sigma_{i}+\ddot{\sigma}_{j} \ddot{\sigma}_{i}\right),
$$

or, equivalently,

$$
\mathrm{R}_{i j}=\alpha g_{j i}+\beta\left(\sigma_{j} \sigma_{i}+\dot{\sigma}_{j} \dot{\sigma}_{i}\right),
$$

where we have put $\beta=-(n+2) \varepsilon / 2\left(\chi^{2}+\mu^{2}\right)$ and $\alpha$ is given by (4.3): In what follows, we show that the covariant vector $\sigma_{i}$ is gradient. In order to try this, we differentiate (4.4) covariantly. Then

$$
\nabla_{j} \sigma_{i}=x_{j} x_{i}+x \nabla_{j} x_{i}-\mu_{j} \tilde{x}_{i}-\mu \nabla_{j} \tilde{x}_{i},
$$

which means that

$$
\nabla_{[j} \sigma_{i]}=x_{[j} x_{i]}+x \nabla_{[j} x_{i]}-\mu_{[j} \tilde{x}_{j]}-\mu \nabla_{[j} \tilde{x}_{i]},
$$

where we have put $x_{i}=\nabla_{i} x$ and $\mu_{i}=\nabla_{i} \mu$. With the aid of (3.15) and (3.15)', the equation above can be rewritten as follows:

$$
\begin{align*}
\nabla_{[j} \sigma_{i]} & =x_{[j} x_{i]}-\mu_{[j} \tilde{x}_{i]}-2\left\{x \rho_{r} \tilde{x}^{r}+\mu\left(\mathrm{I}+\rho_{r} x^{r}\right)\right\} \mathrm{J}_{j i}  \tag{4.5}\\
& +\left\{\kappa\left(\rho_{[j}+x^{r} f_{r[j}\right)+\mu\left(\stackrel{\rho}{\rho}_{[j}-\tilde{x}^{r} f_{r[j}\right)\right\} x_{i]} \\
& +\left\{x\left(\stackrel{\rho}{\rho}_{[j}-\tilde{x}^{r} f_{r[j}\right)-\mu\left(\rho_{[j}+x^{r} f_{r[j)}\right)\right\} \tilde{x}_{i]} .
\end{align*}
$$

Hereafter we may take $x$ and $\mu$ such that

$$
\begin{equation*}
x \omega=\mathrm{I}+\rho_{r} x^{r} \quad, \quad \mu \omega=-\rho_{r} \tilde{x}^{r} \tag{4.6}
\end{equation*}
$$

for certain function $\omega$, because of $x$ and $\mu$ are any functions. Differentiating (4.6) covariantly and recalting (3.15), (3.15)', (3.16), (4.4) and (4.6), equation (4.5) can be reduced to

$$
\nabla_{[j} \sigma_{i]}=\sigma_{i}\left[2\left(\rho_{j}+f_{j r} x^{r}\right)-\partial_{j} \log \omega\right]-\sigma_{j}\left[2\left(\rho_{i}+f_{i r} x^{r}\right)-\partial_{i} \log \omega\right]
$$

and therefore we have $d \sigma$ if there exists a function $\omega$ such that $\partial_{j} \log \omega=$ $2\left(\rho_{j}+f_{j r} x^{r}\right)$. In fact, there exists such a function $\omega$. Let us prove this fact. Contracting $h$ and $i$ in (3.1), it follows that

$$
\partial_{j} \log \sqrt{\bar{g}}=2(n+1) \rho_{j}+2 f_{j r} x^{r}
$$

where $\mathfrak{g}=\operatorname{det}\left(g_{j k}\right)$. Since our discussions are local, by virtue of (3.7) we can know that there exists a function $\rho$ such that $\rho_{i}=\partial_{i} \rho$. So if we choose a function $\omega$ such that $\omega=\exp \left(\log \left\lvert\, \frac{1}{g}-2 n \rho\right.\right)$, then we find $\partial_{i} \log \omega=2\left(\rho_{i}+f_{i r} x^{r}\right)$, which means that the proof is completed.

Let us prove the following
THEOREM 4.3. In order that a $2 n(n \geqq 3)$ dimensional holomorphically subprojective Kählerian manifold M be a manifold of constant holomorphic sectional curvature, it is necessary and sufficient that M is of the first and of the second kind at the same time.

Proof. If M is $\mathrm{M}_{1}$ and $\mathrm{M}_{2}$, then we have $\lambda=\varepsilon=\mathrm{o}$. Thus by making use of the Corollary in [6], we can see that M is a manifold of constant holomorphic sectional curvature. Conversely, we assume that M be a manifold of constant holomorphic sectional curvature. Then M has a vanishing Bochner curvature tensor and M is an Einstein manifold. Therefore by virtue of Theorem 3.2 and $4 . \mathrm{I}$, we find that M is $\mathrm{M}_{1}$ and $\mathrm{M}_{2}$ at the same time.

In the next place, we try to show the following
Theorem 4.4. The holomorphically subprojective Kählerian manifold of the first kind with $\mathrm{I}+\rho_{r} \mathrm{x}^{r}=\mathrm{o}$ and $\rho_{r} \tilde{x}^{r}=\mathrm{o}$ is one of following manifolds:
(I) M is a manifold of constant holomorphic sectional curvature.
(2) M is a locally product manifold of two manifolds of constant holomorphic sectional curvature $\mathrm{H}(\geqq 0)$ and -H .

Proof. By assumption we have

$$
\begin{gather*}
\mathrm{I}+\rho_{r} x^{r}=\mathrm{o}  \tag{4.7}\\
\rho_{r} \tilde{x}^{r}=\mathrm{o} \tag{4.8}
\end{gather*}
$$

We differentiate (4.7) covariantly and take account (3.15), (3.16), (4.7) and (4.8). Then we get $a=0$ and hence equation (3.18) can be rewritten as follows:

$$
\begin{equation*}
\mathrm{R}_{j i}=\varepsilon\left[n|x|^{2} g_{j i}-(n+2)\left(x_{j} x_{i}+\tilde{x}_{j} \tilde{x}_{i}\right)\right] / 2 \tag{4.9}
\end{equation*}
$$

which implies that

$$
\begin{equation*}
\mathrm{R}=(n+\mathrm{I})(n-\mathrm{I})|x|^{2} \varepsilon \tag{4.io}
\end{equation*}
$$

and differentiating (4.9) and (4.10) covariantly and recalling (3.15), (3.15)', (4.7) and (4.8), we have

$$
\begin{gather*}
\nabla_{k} \mathrm{R}_{j i}=\alpha_{k}\left[n|x|^{2} g_{j i}-(n+2)\left(x_{j} x_{i}+\tilde{x}_{j} \tilde{x}_{i}\right)\right],  \tag{4.II}\\
\nabla_{k} \mathrm{R}=2(n+\mathrm{I})(n-2)|x|^{2} \alpha_{k}
\end{gather*}
$$

where we have put

$$
\alpha_{k}=\nabla_{k} \varepsilon / 2+\varepsilon\left(\rho_{k}+f_{k r} x^{r}\right) .
$$

Since our manifold has a vanishing Bochner curvature tensor by Theorem 4.3 , we may use equation (2.3). By substitution of (4.11) and (4.12) into (2.3), we obtain

$$
\begin{gathered}
2 \alpha_{k}\left[n|x|^{2} g_{j i}-(n+2)\left(x_{j} x_{i}+\tilde{x}_{j} \tilde{x}_{i}\right)\right] \\
=(n-2)|x|^{2}\left(\alpha_{j} g_{k i}+\alpha_{i} g_{k j}+2 \alpha_{k} g_{j i}+\mathrm{J}_{k j} \tilde{\alpha}_{i}+\mathrm{J}_{k i} \widetilde{\alpha}_{j}\right),
\end{gathered}
$$

from which we have by transvection with $x^{j} x^{i}$

$$
\begin{equation*}
n|x|^{2} \alpha_{k}=-(n-2)\left(\alpha_{r} x^{r} x_{k}+\alpha_{r} \tilde{x}^{r} \tilde{x}_{k}\right) \tag{4.13}
\end{equation*}
$$

Furthermore, contracting this with $x^{k}$ and $\tilde{x}^{k}$ respecvtiely, we can see that $\alpha_{r} x^{r}=\alpha_{r} \tilde{x}^{r}=\mathrm{o}$. Therefore from (4.13) we have $\alpha_{k}=\mathrm{o}$ together with these, which means that the scalar curvature R is constant. At last, the proof is completed by Theorem A.

Summing up the above discussions we can state the following
THEOREM 4.5. A $2 n(n \geqq 3)$ dimensional holomorphically subprojective Kählerian manifold of the first kind has the following properties (I)~(III):
(I) The manifold is a Kählerian manifold with vanishing Bochner curvature tensor which has the Ricci tensor of the form

$$
\mathrm{R}_{j k}=\alpha g_{j k}+\beta\left(\sigma_{j} \sigma_{k}+\stackrel{\rightharpoonup}{\sigma}_{j} \stackrel{\rightharpoonup}{\sigma}_{k}\right),
$$

where $\sigma_{i}$ is a gradient vector, and $\alpha$ and $\beta$ are some functions.
(II) The vector $x^{h}$ in (3.1) is contravariant analytic, that is, $x^{h}$ satisfies

$$
\mathscr{L}_{x} \mathrm{~J}_{i}^{h}=\mathrm{o},
$$

or, equivalently

$$
\nabla_{j} x_{i}=\mathrm{J}_{j}^{r} \mathrm{~J}_{i}^{s} \nabla_{r} x_{s},
$$

where $\mathscr{L}_{x}$ denotes the operator of Lie derivation with respect to $x^{h}$.
(III) There exist a gradient vector $\rho_{i}$ and a symmetric tensor $f_{j k}$ such that for some functions $\Phi$ and $\varphi$.

$$
f_{r[j} \mathrm{J}_{i]}^{r}=\mathrm{o}
$$

and

$$
\nabla_{j} \rho_{i}=-\rho_{j} \rho_{i}+\stackrel{\rightharpoonup}{\rho}_{j} \stackrel{\rightharpoonup}{\rho}_{i}+f_{j i}+\Phi g_{j i}+\varphi\left(\sigma_{j} \sigma_{i}+\stackrel{\rightharpoonup}{\sigma}_{j} \tilde{\sigma}_{i}\right) .
$$

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