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An a priori bound for the Cauchy problem in Banach space

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Analisi matematica. — *An a priori bound for the Cauchy problem in Banach space.* Nota di ADA ARDITO e PAOLO RICCIARDI (*) presentata (**) dal Corrisp. G. STAMPACCHIA.

RIASSUNTO. — Si dà un nuovo metodo basato su funzioni di Liapunov per ottenere maggiorazioni a priori per equazioni differenziali in spazi di Banach.

1. INTRODUCTION

Let Ω be an open subset of the Banach space X and let $\partial\Omega$ denote its boundary and $\bar{\Omega}$ its closure. By $\|x\|$ we denote the norm of $x \in X$. Let $A: D_A \subset X \rightarrow X$ be a linear operator which is the generator of a strongly continuous semigroup e^{tA} and let $f: [0, T] \times \Omega \rightarrow X$ be a continuous ⁽¹⁾ mapping $(t, x) \rightarrow f(t, x)$.

We consider the problems

$$(1.1) \quad \begin{cases} u' = Au + f(t, u) \\ u(0) = u_0 \end{cases}$$

$$(1.2) \quad u(t) = e^{tA} u_0 + \int_0^t e^{(t-s)A} f(s, u(s)) \, ds.$$

A function u of class C^1 , such that $u(t) \in D_A$, $\forall t \geq 0$ and $t \rightarrow Au(t)$ is continuous, and satisfying (1.1) is said to be a classical solution of (1.1). A solution of (1.2) is said to be a mild solution of (1.1). It is well known (see T. Kato [7]) that if $u_0 \in D_A$ and f is of class C^1 then every mild solution is classical.

In addition if f is locally Lipschitz one has local existence; to have global existence it is sufficient to have a priori estimates. Such a priori estimates are obtained if $-f(t, \cdot)$ is accretive for each t (see e.g., F. Browder [1], T. Kato [7]) or if there is some principle of conservation of energy (see e.g., I. E. Segal [12], T. Kato [7]). Another case in which a priori bounds can be established is when $f(t, \cdot) \in K_B(X)$ ⁽²⁾ (see M. Iannelli [5]). In this case one demonstrates that if u is a solution of (1.2) then $t \rightarrow \|u(t)\|$ is decreasing.

In this work we have replaced the norm with Liapunov function which decreases along the solutions and we establish a generalization of the results of M. Iannelli [6]. At the end we will give examples that generalize equations of T. Carleman.

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(1) It is sufficient to require only that $f(t, \cdot)$ be integrable.

(2) $\|x\| \leq \|x - \alpha f(t, x)\| \quad \forall \alpha > 0 \quad \forall t$.

2. A THEOREM OF GLOBAL EXISTENCE

DEFINITION 2.1. *One says that the problem (1.1) or (1.2) has an a priori bound if for each solution*

$$(2.1) \quad u: [0, \alpha[\rightarrow \Omega \quad \alpha \leq T$$

the set

$$(2.2) \quad \mathcal{O} = \{u(t) : t \in [0, \alpha[\}$$

is bounded and is bounded a positive distance away from $\partial\Omega$.

THEOREM 2.2. *If the problem (1.1) is such that:*

- (i) *there exists an a priori bound;*
- (ii) *there exists a local solution for every $u_0 \in \Omega$;*
- (iii) *$f(t, u)$ is bounded (that is, maps bounded sets into bounded sets)*

then there exists a global solution of (1.1).

Proof. By Zorn's lemma and (ii) there exists a function

$$(2.3) \quad u: [0, \alpha[\rightarrow \Omega$$

which is a maximal solution of (1.1). From (i) we have that $\mathcal{O}$ defined in (2.2) is bounded and from (iii) there exists $M \in \mathbf{R}^+$ such that

$$(2.4) \quad \|f(t, x)\| \leq M \quad \forall (t, x) \in [0, \alpha[\times \mathcal{O}.$$

By (2.4) results that exists the Lebesgue integral

$$(2.5) \quad \int_0^\alpha e^{(\alpha-s)A} f(s, u(s)) \, ds.$$

Then for each $t \in [0, \alpha[$ one has

$$(2.6) \quad \left\| e^{\alpha A} u_0 + \int_0^\alpha e^{(\alpha-s)A} f(s, u(s)) \, ds - e^{tA} u_0 - \int_0^t e^{(t-s)A} f(s, u(s)) \, ds \right\| \leq \|e^{\alpha A} u_0 - e^{tA} u_0\| + \left\| \int_t^\alpha e^{(\alpha-s)A} f(s, u(s)) \, ds \right\| + \left\| \int_0^t [e^{(\alpha-s)A} f(s, u(s)) - e^{(t-s)A} f(s, u(s))] \, ds \right\|.$$

Therefore

$$(2.7) \quad \lim_{t \rightarrow \alpha} u(t) = u(\alpha).$$

On the other hand by (i) $u(\alpha) \in \Omega$. It follows by the maximality of $u(t)$ that $\alpha = T$.

3. A PRIORI BOUNDS (CLASSICAL SOLUTIONS)

LEMMA 3.1. *Let $I \subset \mathbf{R}$, $V(t, x)$ a mapping of $I \times \Omega \rightarrow \mathbf{R}$ and $u(t)$ a mapping of $I \rightarrow \Omega$. If*

- (i) *$V(t, x)$ is locally Lipschitz in $x \in \Omega$, uniformly in t on each bounded interval $J \subset I$;*
- (ii) *$\frac{\partial}{\partial t} V(t, x)$ exists and is continuous in (t, x) ;*
- (iii) *$u(t)$ is absolutely continuous on each bounded interval $J \subset I$;*
- (iv) ⁽³⁾ *$u(t)$ is differentiable a.e.*

Then

(α) *$V(t, u(t))$ is differentiable a.e.*

(β) ⁽⁴⁾ *$d/dt V(t, u(t)) = \frac{\partial}{\partial t} V(t, u(t)) + D_u^- V(t, u(t)) u'(t)$ a.e.*

Proof. Fix $t \in J$ and from the hypothesis it is possible to find an interval I_τ and two constants M_J and K_J such that for each $\varepsilon > 0$ there exists a $\delta_\varepsilon > 0$ such that for each finite system of intervals $[\alpha_k, \beta_k]$ ($k = 1, \dots, n$) contained in I_τ such that $\sum_{k=1}^n (\beta_k - \alpha_k) < \delta_\varepsilon$ one has

$$(3.1) \quad \sum_{k=1}^n |V(\beta_k, u(\beta_k)) - V(\alpha_k, u(\alpha_k))| < \varepsilon.$$

In fact

$$(3.2) \quad \sum_{k=1}^n |V(\beta_k, u(\beta_k)) - V(\alpha_k, u(\alpha_k))| \leq \sum_{k=1}^n K_J \|u(\beta_k) - u(\alpha_k)\| + \\ + \left| \frac{\partial}{\partial t} V(\xi_k, u(\alpha_k)) \right| |\beta_k - \alpha_k| \leq \sum_{k=1}^n K_J \|u(\beta_k) - u(\alpha_k)\| + M_J |\beta_k - \alpha_k| \quad (5) \\ \alpha_k < \xi_k < \beta_k.$$

It will suffice therefore to choose $\delta_\varepsilon \leq \min \left(\delta_{\varepsilon'}, \frac{\varepsilon - K_J \varepsilon}{M_J} \right)$ where $\delta_{\varepsilon'}$ is relative to the absolute continuity of $u(t)$ in J . Therefore (α) is established.

With regard to (β) for the points where $V(t, u(t))$ is differentiable one has

$$(3.3) \quad d/dt V(t, u(t)) = \lim_{h \rightarrow 0} 1/h [V(t+h, u(t+h)) - V(t, u(t))] = \\ = \lim_{h \rightarrow 0} 1/h [V(t, u(t) + hu'(t)) - V(t, u(t))] + \\ + \lim_{h \rightarrow 0} 1/h [V(t, u(t+h)) - V(t, u(t) + hu'(t))] + \\ + \lim_{h \rightarrow 0} 1/h [V(t+h, u(t+h)) - V(t, u(t+h))].$$

(3) If X is reflexive then (iii) $\Rightarrow$ (iv).

(4) $D_u^- V(t, u(t)) u'(t) = \overline{\lim}_{h \rightarrow 0} 1/h [V(t, u(t) + hu'(t)) - V(t, u(t))].$

(5) Since $\alpha_k, \beta_k \in \bar{J} \subset I$, one has by (ii) that there exists a constant M_J such that $\left| \frac{\partial}{\partial t} V(\xi_k, u(\alpha_k)) \right| \leq M_J.$

It follows from (ii)

$$(3.4) \quad \lim_{h \rightarrow 0} \frac{1}{h} [V(t+h, u(t+h)) - V(t, u(t+h))] =$$

$$\lim_{h \rightarrow 0} \frac{1}{h} \frac{\partial}{\partial t} V(\xi, u(t+h)) h = \frac{\partial}{\partial t} V(t, u(t)) \quad t+h < \xi < t$$

and from (i)

$$(3.5) \quad \lim_{h \rightarrow 0} \left| \frac{1}{h} [V(t, u(t+h)) - V(t, u(t) - hu'(t))] \right| \leq$$

$$\lim_{h \rightarrow 0} \frac{1}{h} \|K_J\| \|u(t+h) - u(t) - hu'(t)\| = 0.$$

Therefore we have (β).

THEOREM 3.2. *If there exists a mapping $V(t, x)$, $V: [0, T] \times \Omega \rightarrow \mathbf{R}$, satisfying the hypotheses (i) and (ii) of Lemma 3.1. such that*

$$(iii) \quad \frac{\partial}{\partial t} V(t, x) + D_x^- V(t, x) f(t, x) \leq 0$$

(iv) ⁽⁶⁾ u_0 is such that the set

$$(3.6) \quad K_{u_0} = \bigcup_{t \in [0, T]} \{x / V(t, x) \leq V(0, u_0)\}$$

is bounded and bounded a positive distance away from $\partial\Omega$ then there exists an a priori bound for the classical solutions of (1.1).

Proof. Let $u(t), u: [0, \alpha[\rightarrow \Omega$, be a classical solution of (1.1). Then $u(t)$ satisfies the hypothesis (iii) and (iv) of Lemma 3.1. Therefore from (iii) one obtains

$$(3.7) \quad d/dt V(t, u(t)) \leq 0 \quad \text{a.e.}$$

It follows that for each $t \in [0, \alpha[$

$$(3.8) \quad V(t, u(t)) \leq V(0, u_0).$$

Therefore $\mathcal{O}$ defined in 2 (2.2), is contained in K_{u_0} , and the conclusion follows.

LEMMA 3.3. ⁽⁷⁾ *Let $u_0 \in D_A \cap \Omega$. If*

(i) $f(t, u)$ has partial derivatives with respect to t and u and these partial derivatives are continuous in (t, u) .

If the (1.1) has a mild solution then this solution is classical.

If in addition

(ii) $\frac{\partial}{\partial t} f(t, u)$ is bounded.

then there exists a local solution.

(6) If $\Omega = X$ then this condition can be replaced by the following.

$$(iv)' \quad \lim_{\|x\| \rightarrow +\infty} V(t, x) > V(0, u) \quad \text{uniformly in } t \text{ in } [0, T].$$

(7) See T. Kato [7].

COROLLARY 3.4. *Under the hypothesis of Lemma 3.3. and Theorem 3.2. If*

(i) *$f(t, u)$ is bounded*

there is a global classical solution of (1.1).

Proof. The results is obvious from Theorem 2.2. observing that by Lemma 3.3. $u(\alpha) \in D_A \cap \Omega$.

4. A PRIORI BOUNDS (MILD SOLUTIONS)

THEOREM 4.1. *Suppose there exists a sequence $\{f_n\}$, $f_n: [0, T] \times \Omega \rightarrow X$, of mappings verifying the hypotheses of Lemma 3.3., of Corollary 3.4. and such that.*

(i) *$\{f_n\}$ is equi-Lipschitz continuous on bounded subsets of Ω uniformly in $t \in [0, T]$;*

(ii) *$\lim_n f_n(t, x) = f(t, x)$ for each fixed (t, x) .*

Suppose in addition there exists a mapping $V(t, x)$, $V: [0, T] \times \Omega \rightarrow \mathbf{R}$ satisfying the hypothesis (i) and (ii) of Lemma 3.1. and

(iii) *$\forall n$, $\frac{\partial}{\partial t} V(t, x) + D_x^- V(t, x) (Ax + f_n(t, x)) \leq 0$*

(iv)₁ *$K_{u_0} = \bigcup_{t \in [0, T]} \{x/V(t, x) \leq V(0, u_0)\}$ is bounded and bounded a positive distance away from $\partial\Omega$*

(iv)₂ *$D_A \cap K_{u_0}$ is dense in K_{u_0} .*

Then there is an a priori bound for (1.2).

Before proving Theorem 4.1. we first state the following Lemma whose proof is obvious.

LEMMA 4.2. *If (iv)₁ and (iv)₂ hold then for each $u_{0_n} \in D_A \cap K_{u_0}$ the set $K_{u_{0_n}} = \bigcup_{t \in [0, T]} \{x/V(t, x) \geq V(0, u_{0_n})\}$ is contained in K_{u_0} .*

Proof of 4.1. Since by (iv)₂, $D_A \cap K_{u_0}$ is dense in K_{u_0} , there exists a sequence $\{u_{0_n}\} \subset D_A \cap K_{u_0}$ that converges to u_0 . We consider the problem

$$u_n(t) = u_{0_n} + \int_0^t e^{(t-s)A} f_n(s, u_n(s)) ds.$$

By Lemma 4.2. and by (iii) above it follows that there is a global classical solution for, each n .

Let $u(t)$, $u: [0, \alpha] \rightarrow \Omega$ be a local solution of (1.2). Then $\forall t \in [0, \alpha[$

$$\begin{aligned} (4.1) \quad \|u_n(t) - u(t)\| &\leq \|e^{tA} u_{0_n} - e^{tA} u_0\| + \\ &+ \left\| \int_0^t e^{(t-s)A} f_n(s, u_n(s)) - e^{(t-s)A} f_n(s, u(s)) ds \right\| + \\ &+ \left\| \int_0^t [e^{(t-s)A} f_n(s, u(s)) - e^{(t-s)A} f(s, u(s))] ds \right\|. \end{aligned}$$

By the continuity of e^{tA} for each fixed t we have

$$(4.2) \quad \lim_{n \rightarrow \infty} \|e^{tA} u_{0_n} - e^{tA} u_0\| = 0$$

and by the boundedness of f_n and the Theorem of dominated convergence we have

$$(4.3) \quad \lim_{n \rightarrow \infty} \left\| \int_0^t [e^{(t-s)A} f_n(s, u(s)) - e^{(t-s)A} f(s, u(s))] ds \right\| = 0.$$

Therefore it follows that

$$(4.4) \quad \|u_n(t) - u(t)\| \leq \varepsilon_n + \left\| \int_0^t e^{(t-s)A} [f_n(s, u(s)) - f(s, u(s))] ds \right\|.$$

By (i) and the Theorem of Hille-Yosida there exists a constant c such that

$$(4.5) \quad \|u_n(t) - u(t)\| \leq \varepsilon_n + c \int_0^t \|u_n(s) - u(s)\| ds.$$

By Gronwall's Lemma

$$(4.6) \quad \|u_n(t) - u(t)\| \leq \varepsilon_n e^{ct}.$$

Therefore $\lim_n u_n(t) = u(t) \quad \forall t \in [0, \alpha]$. By (iii)

$$(4.7) \quad V(t, u_n(t)) \leq V(0, u_{0_n})$$

and one has, passing to the limit

$$(4.8) \quad V(t, u(t)) \leq V(0, u_0) \quad \forall t \in [0, \alpha]$$

from which the conclusion follows by (iv)₁.

5. APPLICATIONS

Example 5.1. We consider the second order equation

$$(5.1) \quad \begin{cases} \ddot{u} + f(u) = 0 \\ \dot{u}(0) = u_1 \quad u(0) = u_0. \end{cases}$$

If there exists a mapping $F(x)$, $F: X \rightarrow \mathbf{R}$ such that

- (i) $F(x)$ is locally Lipschitz;
- (ii) $\{x_n\} \subset X$ is such that $\lim_{n \rightarrow \infty} \|x_n\| = +\infty$ then $\lim_n F(x_n) \geq 0$

(iii) ⁽⁸⁾ for each $y' \in \partial \|y\|$

$$(5.2) \quad \langle y, F'(x) \rangle = \|y\| \langle f(x), y' \rangle.$$

Then there exists a mapping $V(x, y)$, $V: X \oplus X \rightarrow \mathbf{R}$ that verifies the hypothesis of Theorem 3.2.

Proof. We observe that for each $x' \in \partial \|\dot{u}(t)\|$ one has

$$(5.3) \quad \langle \ddot{u}(t), x' \rangle + \langle f(u), x' \rangle = 0.$$

By (iii) it follows that

$$(5.4) \quad \|\dot{u}(t)\| \langle \ddot{u}(t), x' \rangle + \langle \dot{u}(t), F'(u(t)) \rangle = 0.$$

By a result of T. Kato and by the chain rule one has

$$(5.5) \quad \langle \ddot{u}(t), x' \rangle = d/dt \|\dot{u}(t)\| \quad \text{a.e.}; \quad \langle \dot{u}(t), F'(u(t)) \rangle = d/dt F(u(t)).$$

Then

$$(5.6) \quad d/dt (1/2 \|\dot{u}(t)\|^2 + F(u(t))) = 0.$$

One may then choose

$$(5.7) \quad V(x, y) = 1/2 \|y\|^2 + F(x).$$

Example 5.2. We consider the system

$$(5.8) \quad \begin{cases} u = -\frac{\partial}{\partial x} u + \tau_1(u, v) \\ v = -\frac{\partial}{\partial y} u + \tau_2(u, v) \\ u(0) = u_0(x, y) \quad v(0) = v_0(x, y). \end{cases} \quad t \in [0, T]$$

Let $X = C(0, L) \oplus C[0, L]$, $L \in \mathbf{R}^+$, $(u, v) \in X$, $\|(u, v)\| = \|u\| + \|v\|$, $\|u\| = \sup_{(x, y) \in [0, L]^2} |u(x, y)|$. Let A be the operator given by

$$A: D_A \subset X \rightarrow X, \quad A(u, v) = \left(-\frac{\partial}{\partial x} u, -\frac{\partial}{\partial y} v \right)$$

$$D_A = \left\{ (u, v) \in X, \left(-\frac{\partial}{\partial x} u, -\frac{\partial}{\partial y} v \right) \in X \text{ and } u(0, y) = v(x, 0) = 0 \right\}.$$

Let $f: X \rightarrow X$ be given by $f(u, v) = (\tau_1(u, v), \tau_2(u, v))$. Then (5.8) may be written, setting $w = (u, v)$, as

$$(5.9) \quad \begin{cases} \dot{w} = Aw + f(w) \\ w(0) = w_0. \end{cases}$$

(8) If $X = H$ is a Hilbert space, (iii) implies that $F(x)$ is an anti-derivative of $f(x)$. In fact identifying H with H' in the usual way with the Theorem of Riesz, it follows that $F'(x)$ is a mapping of H to H such that $F'(u(t)) = f(u(t))$. In the particular case that $X = \mathbf{R}$, set $x = (x_1, \dots, x_n)$ and $f(x) = (f_1(x), \dots, f_n(x))$ and by (iii) we may write

$$\sum_{i=1}^n \frac{\partial F(x)}{\partial x_i} y_i = \sum_{i=1}^n f_i(x) y_i.$$

If f verifies the hypothesis of Lemma 3.3. and if $w_0 \in D_A$, then (5.8) admits a classical local solution. If in addition (i) $\exists p, q \geq 1, \tau' \in \partial \|u\|, \xi' \in \partial \|v\|$ such that

$$p \|u\|^{p-1} \langle \tau_1(u, v), \tau' \rangle + q \|v\|^{q-1} \langle \tau_2(u, v), \xi' \rangle \leq 0$$

then there exists a mapping $V: X \rightarrow \mathbf{R}$ which assures the existence of an a priori bound for each $w_0 \in D_A$.

In fact one may choose

$$(5.10) \quad V(u, v) = \|u\|^p + \|v\|^q.$$

It follows that

$$(a) \quad \lim_{\|u\|, \|v\| \rightarrow \infty} V(u, v) = +\infty$$

$$(b) \quad D_w^- V(w) A w = p \|u\|^{p-1} D_s \|u\| \left(-\frac{\partial}{\partial x} u \right) + q \|v\|^{q-1} D_s \|v\| \left(-\frac{\partial}{\partial y} v \right) = \\ = p \|u\|^{p-1} \inf_{\tau' \in \partial \|u\|} \left\langle -\frac{\partial}{\partial x} u, \tau' \right\rangle + q \|v\|^{q-1} \inf_{\xi' \in \partial \|v\|} \left\langle -\frac{\partial}{\partial y} v, \xi' \right\rangle \leq 0 \quad (9)$$

$$(c) \quad D_w^- V(w) f(w) = p \|u\|^{p-1} D_s \|u\| \langle \tau_1(u, v) \rangle + q \|v\|^{q-1} D_s \|v\| \langle \tau_2(u, v) \rangle = \\ = p \|u\|^{p-1} \inf_{\tau' \in \partial \|u\|} \langle \tau_1(u, v), \tau' \rangle + q \|v\|^{q-1} \inf_{\xi' \in \partial \|v\|} \langle \tau_2(u, v), \xi' \rangle \leq 0.$$

We observe that if $f(w) = f \circ w$ where $f \in C(\mathbf{R}) \oplus C(\mathbf{R})$ then by (i) we may write

$$p |x|^{p-1} \operatorname{sgn} x \tau_1(x, \bar{y}) + q |y|^{q-1} \operatorname{sgn} y \tau_2(\bar{x}, y) \leq 0 \quad x > \bar{x}, y > \bar{y}.$$

For the problem e.g.

$$\begin{cases} u = -\frac{\partial}{\partial x} u - \frac{1}{4} u^3 - uv^2 \\ v = -\frac{\partial}{\partial y} u + u^6 - v^3 \end{cases}$$

one may choose $V: X \rightarrow \mathbf{R}, (u, v) \rightarrow V(u, v)$

$$V(u, v) = \|u\|^4 + \|v\|.$$

(9) We recall that $\partial \|u\|$ is the closed convex hull of the set

$$\{\tau' \in X', \tau' = \delta_{(x, y)^+} - \delta_{(x, y)^-}; (x, y)^+ \in M_0^+(u), (x, y)^- \in M_0^-(u)\}$$

where

$$M_0^+ = \{(x, y) \in \mathbf{R}^2, u(x, y) \geq 0, u(x, y) = \|u\|\}.$$

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