#### ATTI ACCADEMIA NAZIONALE DEI LINCEI

#### CLASSE SCIENZE FISICHE MATEMATICHE NATURALI

## RENDICONTI

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# A fixed point theorem based on the use of an auxiliary functional

Atti della Accademia Nazionale dei Lincei. Classe di Scienze Fisiche, Matematiche e Naturali. Rendiconti, Serie 8, Vol. **56** (1974), n.2, p. 175–179. Accademia Nazionale dei Lincei

<http://www.bdim.eu/item?id=RLINA\_1974\_8\_56\_2\_175\_0>

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**Equazioni funzionali.** — A fixed point theorem based on the use of an auxiliary functional (\*). Nota di Christian Fabry, presentata (\*\*) dal Socio G. Sansone.

RIASSUNTO. — Si presentano teoremi di punti fissi per funzioni non necessariamente continue definite su spazi topologici compatti o su sottoinsiemi debolmente compatti di spazi vettoriali topologici. I risultati generalizzano teoremi ottenuti da W. A. Kirk per applicazioni nonespansive.

I. The aim of this Note is to present a fixed point theorem which provides a generalization for the following results of W. A. Kirk [1, 2].

Theorem 1. Suppose X is a nonempty, weakly compact, convex subset of a Banach space E, and suppose that X has normal structure. Then, for every nonexpansive mapping  $T: X \to X$ , there is a point x in X such that x = Tx.

Theorem 2. Suppose X is a nonempty, weakly compact subset of a Banach space E. If  $T: X \to X$  is a nonexpansive mapping which has diminishing orbital diameters, then there is a point x in X such that x = Tx.

Let us recall that a mapping  $T: X \to X$  is nonexpansive if  $||Tx - Ty|| \le \le ||x - y||$  for all x, y in X and that it has diminishing orbital diameters if, for each  $x \in X$ , x = Tx,

$$\delta\left(\mathbf{Q}\left(x\right)\right)<\infty\qquad\text{and}\quad\lim_{n\to\infty}\delta\left(\mathbf{Q}\left(\mathbf{T}^{n}x\right)\right)<\delta\left(\mathbf{Q}\left(x\right)\right)$$

where  $\delta(Q(x))$  is the diameter of the set  $Q(x) = \{T^n x; n = 0, 1, 2, \dots\}$ . On the other hand, a bounded convex subset X in a Banach space E is said to have normal structure if, for every convex subset H of X which contains more than one point, there is a point  $x \in H$  which is nondiametral, that is, for which

$$\sup \{ \|x - y\| : y \in H \} < \delta(H) = \sup \{ \|x - y\| : x, y \in H \}.$$

2. Our first result provides a fixed point existence criterion in the general framework of a compact topological space X; it involves the use of a function  $\psi: X \times X \to \mathbf{R}$  (with adequate continuity and boundedness properties) such that  $\psi(Tx, Ty) \leq \psi(x, y)$ . Other fixed point theorems based on the use of an auxiliary functional have been given by M. Furi and A. Vi-

<sup>(\*)</sup> Lavoro eseguito durante un soggiorno dell'Autore presso l'Istituto di Matematica Applicata. Facoltà d'Ingegneria. Università di Firenze.

<sup>(\*\*)</sup> Nella seduta del 9 febbraio 1974.

gnoli [3] and by J. H. George, V. M. Sehgal and R. F. Smithson [4] (see also J. W. Thomas [5]); the main difference with the present approach is that the auxiliary functional was defined on X rather than on the product  $X \times X$ .

Theorem 3. Let X be a nonempty compact topological space and let  $T: X \to X$  (not necessarily continuous). Let us assume that a function  $\psi: X \times X \to \mathbf{R}$  exists such that

- (i)  $(\forall x \in X)$ ,  $\psi(x, \cdot)$  is lower semi-continuous (l.s.c., in short),
- (ii)  $(\forall y \in X)$ ,  $\psi(\cdot, y)$  is 1.s.c.,
- (iii)  $(\forall x \in X) (\forall y \in X)$ , the set  $\{\psi(x, T^n y); n = 0, 1, 2, \cdots\}$  is bounded in **R**,
- (iv)  $(\forall y \in X)$ , the function  $Q(\cdot, y) = \limsup_{n \to \infty} \psi(\cdot, T^n y)$  is 1.s.c.,
- (v)  $(\forall x \in X) (\forall y \in X), \psi (Tx, Ty) \leq \psi (x, y),$
- (vi)  $(\forall H \subset X : H \text{ closed}, T(H) \subset H, H \text{ containing more than one point})$   $(\exists x \in H, y \in H), \limsup_{n \to \infty} \psi(x, T^n y) < \sup \{\psi(x, y) : x \in H, y \in H\}.$

Then there is a point  $x \in X$  such that x = Tx.

- *Proof.* I) Let  $\Phi$  be the family of closed and nonempty subsets H of X such that  $T(H) \subset H$  (invariant sets). The family  $\Phi$  is nonempty, since  $X \in \Phi$ , and can obviously be (partially) ordered by inclusion. It then results from the compactness of X and from Zorn's lemma that  $\Phi$  contains a minimal element, say K.
- 2) For  $y \in X$ , let  $K_0(y) = \{x \in K : Q(x,y) = \inf_{u \in K} Q(u,y)\}$ ; as  $Q(\cdot,y)$  is l.s.c., the set  $K_0(y)$  is nonempty and closed. Moreover, it is invariant since  $Q(Tx,y) \leq Q(x,y)$  for  $x \in X$ ,  $y \in X$ . By the minimality of K, it then results that,  $\forall y \in X$ ,  $K_0(y) = K$  and that Q(x,y) is independent of  $x \in K$ . Let us then introduce the function  $r: X \to \mathbf{R}$  defined by r(y) = Q(x,y), x being any element of K.
  - 3) Let  $r_0 = \inf \{r(y) : y \in K\}$ ; it is clear that

$$(\forall \epsilon > 0) (\exists y \in K) (\forall x \in K) (\exists N \ge 0) (\forall n \ge N), \psi(x, T^n y) \le r_0 + \epsilon.$$

The set  $S(x, \varepsilon) = \{y \in K : \psi(x, y) \le r_0 + \varepsilon\}$  is nonempty and closed; as K is compact and as the family  $\{S(x, \varepsilon) : x \in K, \varepsilon > 0\}$  has the finite intersection property, the intersection  $S = \bigcap_{\varepsilon > 0} \bigcap_{x \in K} S(x, \varepsilon)$  is nonempty and closed.

4) It will be shown now that  $T(S) \subset S$  which will imply, by the minimality of K, that S = K. Indeed,  $\forall x \in K$ ,  $\forall y \in S$ , the following relations hold:

$$\psi\left(\mathrm{T}x\,,\,\mathrm{T}y\right)\leq\psi\left(x\,,\,y\right)\leq r_{0}$$

and, therefore,  $\sup \{\psi(x, Ty) : x \in T(K)\} \le r_0$ , for all  $y \in S$ . But, the closure  $\operatorname{cl} T(K)$  of T(K) is invariant because  $T(K) \subset \operatorname{cl} T(K) \subset K$ , which implies that  $\operatorname{cl} T(K) = K$ . As  $\psi(\cdot, y)$  is l.s.c., it then follows that  $\sup \{\psi(x, Ty) : x \in K\} \le r_0$  or that  $Ty \in S$ , for all  $y \in S$ .

5) For all  $x \in K$ ,  $y \in K$ , the following relation then holds:

$$\psi(x,y) \leq r_0 = \inf \left\{ \limsup_{n \to \infty} \psi(x, T^n y) : x, y \in K \right\};$$

this relation, together with hypothesis (vi), shows that K must consist of a single point.

3. A similar result can be given when X is a weakly compact subset of a locally convex topological vector space (LCTVS) E. In that case, it is possible, as shown by the following lemma, to make appropriate hypotheses about the function  $\psi(\cdot,y):X\to\mathbf{R}$  in order to get the required properties of semi-continuity for the function  $Q(\cdot,y)=\limsup_{n\to\infty}\psi(\cdot,T^ny)$ . Let us recall that a function  $\psi:E\to\mathbf{R}$  is called quasi-convex if the sets  $P(r)=\{y\in E:\psi(y)\leq r\},\ r\in\mathbf{R},\ \text{are convex}.$ 

LEMMA. Let E be a locally convex topological vector space. If a family  $\{\psi_n: n=0, 1, 2, \cdots\}$  of real quasi-convex functions defined on E is bounded at each point of E and is equicontinuous, then the function  $Q: E \to \mathbf{R}: x \to 0$  limsup  $\psi_n(x)$  is quasi-convex and l.s.c., and thus weakly l.s.c.

*Proof.* It must be shown that the sets  $P(r) = \{x \in E : Q(x) \le r\}$ ,  $r \in \mathbb{R}$ , are convex and closed, and thus weakly closed.

I) Let us prove first that,  $\forall r \in \mathbf{R}$ , the set P(r) is closed. Let  $x \in \operatorname{cl} P(r)$ ; the equicontinuity of  $\{\psi_n : n = 0, 1, 2, \cdots\}$  implies that

$$(\forall \varepsilon > 0) (\exists u \in P(r)) (\forall n \ge 0), |\psi_n(x) - \psi_n(u)| \le \varepsilon/2.$$

On the other hand, it results from the definition of O that

$$(\forall \varepsilon > 0) (\forall u \in E) (\exists N \ge 0) (\forall n \ge N), \psi_n(u) - Q(u) \le \varepsilon/2.$$

Therefore, it is clear that

$$(\forall \varepsilon > 0) (\exists N' \ge 0) (\forall n \ge N'), \ \psi_n(x) \le r + \varepsilon,$$

which shows that  $Q(x) \le r$  and that P(r) is closed.

2) Let  $x_1$ ,  $x_2 \in P(r)$  and let us show that any point x belonging to the segment  $[x_1, x_2]$  is also in P(r). By hypothesis,  $Q(x_i) \le r$  for i = 1, 2 and, therefore,

$$(\forall \varepsilon > 0) (\exists N_i \ge 0) (\forall n \ge N_i), \psi_n(x_i) \le r + \varepsilon,$$
  $(i = 1, 2);$ 

taking  $N = max\left\{N_1\,,\,N_2\right\}$  and using the quasi-convexity of  $\psi,$  one obtains

$$(\forall \epsilon > \mathrm{o}) \, (\exists \mathrm{N} \geq \mathrm{o}) \, (\forall n \geq \mathrm{N})$$
 ,  $\psi_n(x) \leq r + \epsilon$ 

or  $Q(x) \le r$  for  $x \in [x_1, x_2]$ .

We are now able to state our main result. In the theorem, X is a weakly compact subset of a LCTVS E and  $\Phi$  denotes the family of nonempty invariant subsets of X which are intersections of X with closed convex subsets of E.

Theorem 4. Let X be a nonempty weakly compact subset of a LCTVS E and let  $T: X \to X$  (not necessarily continuous). Let us assume that a function  $\psi: E \times E \to \mathbf{R}$  exists such that

- (i)  $(\forall x \in X), \psi(x, \cdot)$  is quasi-convex and (strongly) l.s.c. on E,
- (ii)  $(\forall y \in X)$ ,  $\psi(\cdot, y)$  is quasi-convex on E,
- (iii) the family of functions  $\{\psi(\cdot, y) : y \in X\}$  is (strongly) equicontinuous on E,
- (iv)  $(\forall x \in E) (\forall y \in X)$ , the set  $\{ \psi(x, T^n y) : n = 0, 1, 2, \cdots \}$  is bounded in **R**.
- (v)  $(\forall x \in X) (\forall y \in X), \psi(Tx, Ty) \leq \psi(x, y),$
- (vi)  $(\forall K \in \Phi, K \text{ containing more than one point}) (\exists x \in K, y \in K),$   $\limsup_{n \to \infty} \psi(x, T^n y) < \sup \{ \psi(x, y) : x, y \in K \}.$

Then, there is a point  $x \in X$  such that x = Tx.

*Proof.* The proof follows very closely that of Theorem 3 and will be given only in its broad lines; the notation will be similar to that of Theorem 3.

- I) It is clear that  $\Phi$  has a minimal element K, a set  $H \in \Phi$  being closed for the topology induced on X by the weak topology of E.
- 2) For  $y \in X$ , let again  $K_0(y) = \{x \in K : Q(x,y) = \inf_{\substack{u \in K \\ u \in K}} Q(u,y)\}$ ; as  $Q(\cdot,y)$  is l.s.c. and quasi-convex (lemma), the set  $K_0(y)$  is nonempty and is the intersection of X with a closed convex subset of E. Moreover,  $K_0(y)$  is invariant, and therefore  $K_0(y) = K$ . As in theorem 3, a function  $r: X \to \mathbf{R}$  can be introduced by the definition r(y) = Q(x,y), x being any element of K.
- 3) If  $r_0 = \inf \{r(y) : y \in K\}$ , the sets  $S(x, \varepsilon) = \{y \in K : \psi(x, y) \le \le r_0 + \varepsilon\}$  where  $x \in K$ ,  $\varepsilon > 0$  are nonempty and are intersections of X with closed convex subsets of E. The same will be true for  $S = \bigcap S(x, \varepsilon)$ .
- 4) It can be shown that S is invariant and thus that S = K. Indeed, it is clear that  $\sup \{\psi(x,Ty): x \in T(K)\} \le r_0$ . But, the intersection of K with the convex closure  $\operatorname{cocl} T(K)$  of T(K) is invariant; it then results that  $K = K \cap \operatorname{cocl} T(K)$  and that  $\sup \{\psi(x,Ty): x \in K\} \le r_0$ .
  - 5) The conclusion then follows as in Theorem 3.

In fact, the function  $\psi$  need not be defined on the whole product  $E \times E$ , but only on cocl  $X \times \operatorname{cocl} X$ , the hypotheses being then modified accordingly. On the other hand, it can be seen that, when E is a Banach space and  $\psi$  is defined by  $\psi(x,y) = \|x-y\|$ , Theorems I and 2 are special cases of Theorem 4, as hypothesis (vi) may be replaced by either one of the following two conditions:

(vi') 
$$(\forall K \in \Phi, K \text{ containing more than one point}) (\exists x \in K),$$
  
 $\sup \{ \psi(x, y) : y \in K \} < \sup \{ \psi(x, y) : x, y \in K \},$ 

$$\begin{array}{ll} (\mathrm{vi''}) & (\forall x \in \mathbf{X} \;,\, x = Tx) \;, \\ & \underset{N \to \infty}{\lim} \; \left[ \sup \left\{ \psi(\mathbf{T}^m x \;,\, \mathbf{T}^n x) : m \;,\, n \geq \mathbf{N} \right\} \right] < \\ & < \sup \left\{ \psi\left(\mathbf{T}^m x \;,\, \mathbf{T}^n x\right) : m \;,\, n \geq \mathbf{o} \right\}. \end{array}$$

Indeed, the first condition obviously implies (vi) whereas the second one implies that, for any invariant subset K of X, either K contains a fixed point or there exists  $x \in K$ ,  $N \ge 0$  such that

$$\sup \{ \psi(\mathbf{T}^{N}x, \mathbf{T}^{n}x) : n \geq \mathbf{N} \} = \sup \{ \psi(\mathbf{T}^{m}x, \mathbf{T}^{n}x) : m, n \geq \mathbf{N} \} <$$

$$< \sup \{ \psi(x, y) : x, y \in \mathbf{K} \}.$$

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