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**Oscillations for forced second order nonlinear
differential equations**

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Equazioni differenziali ordinarie non lineari. — *Oscillations for forced second order nonlinear differential equations.* Nota (*) di VASILIOS A. STAIKOS e YIANNIS G. SFICAS, presentata dal Socio G. SANSONE.

RIASSUNTO. — Si danno risultati sul comportamento asintotico ed oscillatorio delle soluzioni di un'equazione differenziale perturbata della forma

$$[l(t)\psi(x)x']' + a(t)\varphi(x) = b(t)$$

o di forma più generale

$$[l(t)\psi(x)x']' + a(t)g(x, x') = b(t)$$

senza la restrizione $a \geq 0$. Questi risultati generalizzano e migliorano altri precedenti dovuti a Bobisud [2] e Kartsatos [3] che riguardano il caso speciale $\psi \equiv 1$, $l \equiv 1$, $b \equiv 0$.

In this paper we are concerned with the oscillatory and asymptotic behavior of solutions for differential equations of the form

$$(*) \quad [l(t)\psi(x)x']' + a(t)\varphi(x) = b(t)$$

where the nonnegativity of the function a is not assumed. As references to the subject we mention here the papers by Bhatia [1], Bobisud [2] and Kiguradze [4] in which the special case $\psi \equiv 1$ and $b \equiv 0$ is treated. Using the results obtained here for differential equations of the form (*), we derive, by comparison, other ones on oscillatory and asymptotic behavior of solutions for more general differential equations, namely for differential equations of the form

$$(**) \quad [l(t)\psi(x)x']' + f(t)g(x, x') = b(t)$$

All functions in (*) and (**) are supposed to be real-valued with domains

$$\mathfrak{D}(l) = \mathfrak{D}(a) = \mathfrak{D}(b) = \mathfrak{D}(f) = [t_0, \infty)$$

$$\mathfrak{D}(\psi) = \mathfrak{D}(\varphi) = \mathbf{R} \text{ and } \mathfrak{D}(g) = \mathbf{R}^2.$$

Moreover, ψ is nonnegative, l positive and such that

$$(I) \quad \int_{t_0}^{\infty} \frac{dt}{l(t)} = \infty.$$

Throughout the sequel, by "solution" of (*) or (**) we shall mean only solutions which are defined for all large t . Also, we shall consider the oscillatory character of the solutions in the usual sense, i.e., a solution is called *oscillatory* if and only if it has no last zero, otherwise it is called *nonoscillatory*.

(*) Pervenuta all'Accademia il 20 agosto 1973.

THEOREM I. Consider the differential equation (*) subject to the following conditions:

(i) the function φ is differentiable on $\mathbf{R} - \{0\}$ and for every $x \neq 0$,
 $x \varphi(x) > 0$ and $\varphi'(x) \geq 0$

(ii) the function ψ/φ is locally integrable on $(0, \infty)$ and $(-\infty, 0)$ and such that

$$\int_0^{\infty} \frac{\psi(x)}{\varphi(x)} dx < \infty \quad \text{and} \quad \int_{-\infty}^0 \frac{\psi(x)}{\varphi(x)} dx < \infty$$

(iii) for every $\mu > 0$,

$$\int_{t_0}^{\infty} [a(t) - \mu |b(t)|] \int_{t_0}^t \frac{ds}{l(s)} dt = \infty.$$

Then, every solution x of (*) is oscillatory or such that

$$\liminf_{t \rightarrow \infty} |x(t)| = 0.$$

Proof. Let x be a nonoscillatory solution of (*) with $c \equiv \liminf_{t \rightarrow \infty} |x(t)| \neq 0$.

Without loss of generality we can suppose that the domain of x is the whole half-line $[t_0, \infty)$ and that

$$|x(t)| > \frac{c}{2} \quad \text{for every } t \geq t_0.$$

Moreover, this solution can be supposed positive, since the substitution $u = -x$ transforms (*) into an equation of the same form satisfying the assumptions of the theorem.

For

$$(2) \quad z(t) = - \frac{l(t) \psi[x(t)] x'(t)}{\varphi[x(t)]} \int_{t_0}^t \frac{ds}{l(s)}$$

we have

$$\begin{aligned} z'(t) &= - \frac{[l(t) \psi[x(t)] x'(t)]' \varphi[x(t)] - l(t) \psi[x(t)] [x'(t)]^2 \varphi'[x(t)]}{\varphi^2[x(t)]} \int_{t_0}^t \frac{ds}{l(s)} - \\ &- \frac{l(t) \psi[x(t)] x'(t)}{\varphi[x(t)]} \frac{1}{l(t)} \geq - \frac{[l(t) \psi[x(t)] x'(t)]'}{\varphi[x(t)]} \int_{t_0}^t \frac{ds}{l(s)} - \frac{\psi[x(t)]}{\varphi[x(t)]} x'(t). \end{aligned}$$

Since

$$\begin{aligned} - \frac{[l(t) \psi[x(t)] x'(t)]'}{\varphi[x(t)]} &= a(t) - \frac{b(t)}{\varphi[x(t)]} \geq a(t) - \frac{|b(t)|}{\varphi[x(t)]} \geq \\ &\geq a(t) - \frac{1}{\varphi\left(\frac{c}{2}\right)} |b(t)| \end{aligned}$$

we obtain that for every $t \geq t_0$

$$z'(t) \geq [a(t) - \mu |b(t)|] \int_{t_0}^t \frac{ds}{l(s)} - \frac{\psi[x(t)]}{\varphi[x(t)]} x'(t)$$

where $\mu = \frac{1}{\varphi\left(\frac{c}{2}\right)}$. This inequality, by integration, gives

$$\begin{aligned} z(t) &\geq z(t_0) + \int_{t_0}^t [a(u) - \mu |b(u)|] \int_{t_0}^u \frac{ds}{l(s)} du - \int_{x(t_0)}^{x(t)} \frac{\psi(x)}{\varphi(x)} dx \geq \\ &\geq z(t_0) + \int_{t_0}^t [a(u) - \mu |b(u)|] \int_{t_0}^u \frac{ds}{l(s)} du - \int_{x(t_0)}^{\infty} \frac{\psi(x)}{\varphi(x)} dx \end{aligned}$$

from which, by (ii) and (iii), it follows that for some $t_1 > t_0$

$$z(t) \geq 1 \quad \text{for every } t \geq t_1.$$

Thus, by (2), for every $t \geq t_1$

$$(3) \quad \frac{\psi[x(t)]}{\varphi[x(t)]} x'(t) = - \frac{z(t)}{l(t) \int_{t_0}^t \frac{ds}{l(s)}} \leq - \frac{1}{l(t) \int_{t_0}^t \frac{ds}{l(s)}}$$

from which it is obvious that x' is negative on $[t_1, \infty)$ and consequently $\lim_{t \rightarrow \infty} x(t) = c$. Integrating, now, the inequality (3) from t_1 to t , we obtain that

$$(4) \quad \int_{x(t_1)}^{x(t)} \frac{\psi(x)}{\varphi(x)} dx \leq - \int_{t_1}^t \frac{du}{l(u) \int_{t_0}^u \frac{ds}{l(s)}} = - \left[\log \int_{t_0}^u \frac{ds}{l(s)} \right]_{t_1}^t.$$

Hence, by (1),

$$(5) \quad \int_c^{x(t_1)} \frac{\psi(x)}{\varphi(x)} dx = \infty$$

which contradicts (ii).

Remark. In particular for $\psi \equiv 1$, a function φ satisfying (i) and (ii) can be defined by

$$\varphi(x) = x^\alpha$$

where $\alpha > 1$, $\alpha = p/q$ and p, q are odd integers.

THEOREM 2. Consider the differential equation (*) with $b \equiv 0$, i.e. the equation

$$[l(t) \psi(x) x']' + a(t) \varphi(x) = 0.$$

Then, under the assumptions of Theorem 1, every solution of the differential equation under consideration is either oscillatory or tending monotonically to zero as $t \rightarrow \infty$. Moreover, under the additional assumption

$$(iv) \quad \int_{0+} \frac{\psi(x)}{\varphi(x)} dx < \infty \quad \text{and} \quad \int_{0-} \frac{\psi(x)}{\varphi(x)} dx < \infty$$

all solutions are oscillatory.

Proof. Let x be a nonoscillatory solution. This solution can be supposed again with domain $[t_0, \infty)$ and positive. Using the transformation (2) and following the same technique as in the proof of Theorem 1, we derive at first the inequality

$$z'(t) \geq a(t) \int_{t_0}^t \frac{ds}{l(s)} - \frac{\psi[x(t)]}{\varphi[x(t)]} x'(t) \quad , \quad t \geq t_0.$$

Then, by integration, we obtain (3) and consequently (4). Since, by (3), x' is negative on $[t_1, \infty)$, it follows that $\lim_{t \rightarrow \infty} x(t) = c \geq 0$ exists. Thus (4) gives (5), which contradicts (ii) for $c > 0$ and (iv) for $c = 0$.

Remark. The above theorem has been proved in the particular case $\psi \equiv 1$ and $l \equiv 1$ by Bobisud ([2] Theorems 1 and 2) under the additional condition

$$0 < \int_{t_0}^{\infty} a(t) dt \leq \infty.$$

THEOREM 3. Consider the differential equation (**) and the function φ subject to the conditions (i), (ii) and the following ones:

(v) the function g is continuous and such that for every $x \neq 0$ and y ,

$$xg(x, y) > 0$$

(vi) for every $\mu_1 > 0$ and $\mu_2 > 0$,

$$\int_{t_0}^{\infty} [\mu_1 f^+(t) - f^-(t) - \mu_2 |b(t)|] \int_{t_0}^t \frac{ds}{l(s)} dt = \infty$$

where

$$f^+(t) = \max \{f(t), 0\} \quad \text{and} \quad f^-(t) = \max \{-f(t), 0\},$$

(vii) $\mathcal{F}$ is a class of functions defined and differentiable for all large t , which possesses the property:

for every $x \in \mathcal{F}$ with $\liminf_{t \rightarrow \infty} |x(t)| \neq 0$, there exist positive constants

L, M (depending on x) such that

$$(6) \quad L \leq \frac{g[x(t), x'(t)]}{\varphi[x(t)]} \leq M$$

for all large t .

Then every solution x of $(^{**})$ which belongs to the function class $\mathcal{F}$ is oscillatory or such that

$$\liminf_{t \rightarrow \infty} |x(t)| = 0.$$

Proof. Let x be a nonoscillatory solution of $(^{**})$ with $x \in \mathcal{F}$ and $\liminf_{t \rightarrow \infty} |x(t)| \neq 0$. This solution can be supposed with domain $[t_0, \infty)$, positive and such that (6) is satisfied for all $t \geq t_0$.

If

$$a(t) = f(t) \frac{g[x(t), x'(t)]}{\varphi[x(t)]}$$

then the differential equation $(^*)$ has x as a solution. Since, by (6),

$$\begin{aligned} a(t) - \mu |b(t)| &= f(t) \frac{g[x(t), x'(t)]}{\varphi[x(t)]} - \mu |b(t)| \\ &= f^+(t) \frac{g[x(t), x'(t)]}{\varphi[x(t)]} - f^-(t) \frac{g[x(t), x'(t)]}{\varphi[x(t)]} - \mu |b(t)| \\ &\geq Lf^+(t) - Mf^-(t) - \mu |b(t)| \\ &= M[\mu_1 f^+(t) - f^-(t) - \mu_2 |b(t)|] \end{aligned}$$

where $\mu_1 = L/M$ and $\mu_2 = \mu/M$, we have that (iii) follows from (vi). Thus, by Theorem 1, x must be oscillatory or such that $\liminf_{t \rightarrow \infty} |x(t)| = 0$, a contradiction.

Remark. If in the above theorem $\mathcal{F}$ is the class of all bounded and differentiable functions for all large t , then, as conclusion, we have that every bounded solution x of $(^{**})$ is oscillatory or such that $\liminf_{t \rightarrow \infty} |x(t)| = 0$. Thus a result due to Kartsatos ([3] Theorem 1) follows from Theorem 3 in the particular case $\psi \equiv 1$, $l \equiv 1$ and $b \equiv 0$.

Applying the same technique used in the above theorem, it is obvious that we can obtain, by Theorem 2, the following theorems.

THEOREM 4. Consider the function φ and the differential equation $(^{**})$ with $b \equiv 0$, i.e. the equation

$$[l(t)\psi(x)x']' + f(t)g(x, x') = 0.$$

Then, under the conditions (i), (ii), (v), (vi) and

(vii)' $\mathcal{F}$ is a class of functions defined and differentiable for all large t , which possesses the property:

for every nonoscillatory $x \in \mathcal{F}$ with $\lim_{t \rightarrow \infty} x(t) \neq 0$, there exist positive constants L, M such that (6) is satisfied for all large t

every solution of the differential equation under consideration, which belongs to the function class $\mathcal{F}$ is oscillatory or tending to zero as $t \rightarrow \infty$.

THEOREM 5. Consider the function φ and the differential equation $(^{**})$ with $b \equiv 0$. Then, under the conditions (i), (ii), (iv), (v), (vi) and

(vii)' $\mathcal{F}$ is a class of functions defined and differentiable for all large t , which possesses the property:

for every nonoscillatory $x \in \mathcal{F}$, there exist positive constants L, M such that (6) is satisfied for all large t

all solutions of the differential equation under consideration, which belong to the function class $\mathcal{F}$ are oscillatory.

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