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H. O. TEJUMOLA

**A boundedness theorem for some non-linear  
differential equations of the fourth order**

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**Equazioni differenziali ordinarie.** — *A boundedness theorem for some non-linear differential equations of the fourth order.* Nota (\*) di H. O. TEJUMOLA, presentata dal Socio G. SANSONE.

RIASSUNTO. — L'Autore, con opportune ipotesi, dimostra un teorema sulla limitatezza delle soluzioni dell'equazione

$$x^{(iv)} + \varphi(\ddot{x})\ddot{x} + \psi(\dot{x}, \ddot{x}) + g(x, \dot{x}) + h(x) = \theta(t, x, \dot{x}, \ddot{x}, \ddot{\ddot{x}}).$$

1. This Note is sequel to an earlier one [2] in which the equation

$$(1.1) \quad x^{(iv)} + \varphi_1(\ddot{x})\ddot{x} + \varphi_2(\ddot{x}) + \varphi_3(\dot{x}) + a_4 x = p(t, x, \dot{x}, \ddot{x}, \ddot{\ddot{x}})$$

was studied, subject to certain generalized Routh-Hurwitz conditions on  $\varphi_1$ ,  $\varphi_2$  and  $\varphi_3$ . Our interest here is in the boundedness result ([2]; Theorem 2) which we extend to the much more general equations of the form

$$(1.2) \quad x^{(iv)} + \varphi(\ddot{x})\ddot{x} + \psi(\dot{x}, \ddot{x}) + g(x, \dot{x}) + h(x) = \theta(t, x, \dot{x}, \ddot{x}, \ddot{\ddot{x}}).$$

The functions  $\psi, g$  which correspond to  $\varphi_2, \varphi_3$  in (1.1) now depend also on  $\dot{x}$  and  $x$  respectively and the function  $h$ , corresponding to  $a_4 x$  in (1.1), is non-linear.

Assume here that the functions  $\varphi, \psi, g, h, \theta$  are continuous and that  $h'(x), \frac{\partial g}{\partial x}(x, y), \frac{\partial \psi}{\partial y}(y, z)$  exist and are continuous for all  $x, y$  and  $z$ . Let  $g_x(x, y) = \frac{\partial g}{\partial x}(x, y)$  and let  $g_y, \psi_y$  be similarly defined.

THEOREM. *Let*

$$(1.3) \quad \psi(y, 0) = g(x, 0) = 0, \quad h(x) \operatorname{sgn} x \rightarrow +\infty \quad \text{as } |x| \rightarrow \infty$$

*and suppose that*  $a_i (i = 1, 2, 3, 4), \delta_1, \delta_2, \Delta_0, \Delta_1, \Delta_2, A$  *are positive constants such that*

$$(1.4) \quad \varphi(z) \geq a_1 \quad \text{for all } z, \quad g(x, y)/y \geq a_3 \quad \text{for all } x \quad \text{and } y \neq 0$$

$$\text{and } 0 \leq a_4 - h'(x) \leq \varepsilon \Delta_2 a_1^2, \quad \text{for all } x, \quad \Delta_2 = a_2(a_1 + a_3 a_4^{-1});$$

$$(1.5) \quad \{a_1 a_2 - g_y(x, y)\} a_3 - a_1 \varphi(z) h'(x) \geq \Delta_0 \quad \text{for all } x, y \quad \text{and } z;$$

$$(1.6) \quad g_y(x, y) - \frac{g(x, y)}{y} \leq \delta_1 \quad \text{for } |y| \geq \Delta_1, \quad \delta_1 < 2 a_4 \Delta_0 / (a_1 a_3^2);$$

$$(1.7) \quad \frac{1}{z} \int_0^z \varphi(s) ds - \varphi(z) \leq \delta_2 \quad \text{for } z \neq 0, \quad \delta_2 < 2 \Delta_0 / (a_1 a_3^2);$$

(\*) Pervenuta all'Accademia il 27 luglio 1973.

$$(1.8) \quad 0 \leq \frac{\psi(y, z)}{z} - a_2 \leq \varepsilon_0 \frac{a_3^3}{a_4^2} \quad \text{for } z \neq 0;$$

$$(1.9) \quad g_x^2(x, y) \leq (\varepsilon - \varepsilon_0) a_1 \Delta_0, \quad \frac{1}{y} \int_0^y g_x(x, s) ds \leq \frac{(\varepsilon - \varepsilon_0) a_3}{4},$$

$$\left| \frac{1}{z} \int_0^z \psi_y(y, s) ds \right| \leq \frac{\Delta_0}{4 a_3}$$

for all  $x, y$  and  $z$ ;

$$(1.10) \quad |\theta(t, x, y, z, u)| \leq A \quad \text{for all } t, x, y, z \text{ and } u;$$

$$(1.11) \quad \varepsilon_0 < \varepsilon = \min \left[ \frac{a_4}{a_3}, \frac{1}{a_1}, \frac{\Delta_0}{16 a_1 a_3 \Delta_2}, \frac{a_1}{4 \Delta_2} \left( \frac{2 \Delta_0}{a_1^2 a_3^2} - \delta_2 \right), \right. \\ \left. \frac{a_3}{4 a_4 \Delta_2} \left( \frac{2 a_4 \Delta_0}{a_1 a_3^2} - \delta_1 \right) \right].$$

Then there exists a constant  $M_0$  which depends only on  $A, \varphi, \psi$ , and  $h$  such that every solution  $x(t)$  of (1.1) satisfies

$$|x(t)| \leq M_0, \quad |\dot{x}(t)| \leq M_0, \quad |\ddot{x}(t)| \leq M_0, \quad |\ddot{x}(t)| \leq M_0$$

for all sufficiently large  $t$ .

The condition (1.5) is a refinement of the corresponding one (1.4) of [2] which holds for all  $y \neq 0$ .

2. Let  $V = V(x, y, z, u)$  be the continuous function defined by

$$(2.1) \quad V = V_0 + V_1$$

where

$$(2.2) \quad 2 V_0 = 2 d_2 \int_0^x h(s) ds + (a_2 d_2 - a_4 d_1) y^2 + 2 \int_0^y g(x, s) ds \\ + 2 \int_0^z \{s \varphi(s) - d_2 s\} ds + d_1 u^2 + 2 d_1 \int_0^z \psi(y, s) ds + 2 y h(x) \\ + 2 d_1 z h(x) + 2 zu + 2 d_1 z g(x, y) + 2 d_2 y u + 2 d_2 y \int_0^z \varphi(s) ds \\ d_1 = \varepsilon + a_1^{-1}, \quad d_2 = \varepsilon + a_4 a_3^{-1},$$

and

$$(2.3) \quad V_1 = \left\{ (u + \Phi) \operatorname{sgn} x, \quad |x| \geq |u + \Phi| \right\}, \quad \Phi(z) = \int_0^z \varphi(s) ds.$$

For reasons which were outlined in [2], the theorem will follow once it is shown that

$$(2.4) \quad V(x, y, z, u) \rightarrow +\infty \quad \text{as} \quad x^2 + y^2 + z^2 + u^2 \rightarrow \infty$$

and that the limit

$$\dot{V}^+ = \limsup_{h \rightarrow +0} [V(x(t+h), y(t+h), z(t+h), u(t+h)) - V(x(t), y(t), z(t), u(t))]/h$$

exists, corresponding to any solution  $(x(t), y(t), z(t), u(t))$  of the equivalent system

$$(2.5) \quad \begin{aligned} \dot{x} &= y, \quad \dot{y} = z, \quad \dot{z} = u, \quad \dot{u} = -\varphi(z)u - \psi(y, z), \\ &\quad -g(x, y) - h(x) + \theta(t, x, y, z, u) \end{aligned}$$

(obtained from (1.2) by setting  $\dot{x} = y, \dot{y} = z, \dot{z} = u$ ), and satisfies

$$(2.6) \quad \dot{V}^+ \leq -1 \quad \text{provided} \quad x^2(t) + y^2(t) + z^2(t) + u^2(t) \geq M_1,$$

for some constant  $M_1 > 0$ .

3. First we verify (2.4). Assume that all the conditions of the theorem hold. Then, as in [1], the functions  $\varphi, g$  satisfy

$$(3.1) \quad \begin{aligned} d_1 - 1/\varphi(z) &\geq \varepsilon \quad \text{for all } z, \quad d_2 - a_4 y/g(x, y) \geq \varepsilon \quad \text{for } y \neq 0 \\ \text{and } a_2 - d_1 g_y(x, y) - d_2 \varphi(z) &\geq \frac{\Delta_0}{a_1 a_3} - \Delta_2 \varepsilon \quad \text{for all } y, z. \end{aligned}$$

Let  $\gamma$  be the function defined by

$$(3.2) \quad \gamma(x, y) = \begin{cases} g \frac{(x, y)}{y}, & y \neq 0 \\ g_y(x, 0), & y = 0. \end{cases}$$

Let  $z \neq 0$ . Then, in analogy with ([1]; pp. 141),  $V_0$  can be rearranged as follows:

$$(3.3) \quad \begin{aligned} 2V_0 &= \left\{ 2d_2 \int_0^x h(s) ds - \frac{h^2(x)}{\gamma} \right\} + \{a_2 d_2 - a_4 d_1 - d_2^2 \Phi(z)/z\} y^2 \\ &\quad + \left\{ 2 \int_0^y g(x, s) ds - yg(x, y) \right\} + \left\{ 2d_1 \int_0^z \psi(y, s) ds - d_2 - d_1^2 \gamma \right\} z^2 \\ &\quad + \left\{ 2 \int_0^z s\varphi(s) ds - z\Phi(z) \right\} + \{d_1 - z/\Phi(z)\} u^2 \\ &\quad + z/\Phi(z) [u + \Phi(z) + d_2 y\Phi(z)/z]^2 + \frac{1}{\gamma} [h(x) + y\gamma + d_1 z\gamma]^2. \end{aligned}$$

The first term in curly brackets clearly satisfies

$$(3.4) \quad 2d_2 \int_0^x h(s) ds - \frac{h^2(x)}{\gamma} \geq 2\varepsilon \int_0^x h(s) ds - \frac{h^2(0)}{a_3}.$$

As for the next two terms, note that

$$2 \int_0^y g(x, s) ds - yg(x, y) = \int_0^y \left( \frac{g(x, s)}{s} - g_y(x, s) \right) s ds, \quad y \neq 0$$

since

$$yg(x, y) = \int_0^y g(x, s) ds + \int_0^y sg_y(x, s) ds.$$

Furthermore

$$\left| 2 \int_0^y g(x, s) ds - yg(x, y) \right| \leq 3 \Delta_1^2 a_1 a_2 \quad \text{if } |y| \leq \Delta_1,$$

since  $|g(x, y)| \leq a_1 a_2 |y|$  for all  $x$  and  $y$ , the latter being a consequence of the fact that  $g$  satisfies (1.4) and (1.5). Since  $\delta_1 < \frac{2\Delta_0 a_4}{a_1 a_3^2}$ , the various arguments employed in estimating the term  $V_1$  in ([1]; pp. 141-142) can now be applied to the second and third terms in (3.3). Here, by considering the cases:  $|y| \leq \Delta_1$ ,  $|y| \geq \Delta_1$  separately, it will seen that

$$(3.5) \quad (a_2 d_2 - a_4 d_1 - d_2^2 \Phi(z)/z) y^2 + 2 \int_0^y g(x, s) ds - yg(x, y) \\ \geq M_2 y^2 - M_2 \Delta_1^2 - 3 \Delta_1^2 a_1 a_2$$

with

$$\varepsilon \leq \frac{1}{4} a_3 [2 \Delta_0 a_4 / (a_1 a_3^2) - \delta_1] / (a_4 \Delta_2),$$

where

$$M_2 = \left( \Delta_0 a_4 / (a_1 a_3^2) - \frac{1}{2} \delta_1 \right).$$

The fourth and fifth terms in (3.3) correspond to  $V_2$  ([1]; (3.10)). Since  $\psi(y, z)/z \geq a_2 (z \neq 0)$  and  $\varphi, g$  satisfy (3.1) the estimate for  $V_2$  in [1] holds here also. That is,

$$(3.6) \quad \left\{ 2 d_1 \int_0^z \psi(y, s) ds - d_2 - d_1^2 \gamma \right\} z^2 + 2 \int_0^z s \varphi(s) ds - z \Phi(z) \geq M_3 z^2$$

where  $M_3 = \frac{1}{2} [2 \Delta_0 / a_1^2 a_3 - \delta_2]$  and  $\varepsilon \leq \frac{1}{2} M_3 a_1 \Delta_2^{-1}$ . Lastly,

$$(3.7) \quad \{d_1 - z/\Phi(z)\} u^2 \geq \varepsilon u^2,$$

since  $\Phi(0) = 0$  implies that  $\Phi(z) = z\varphi(\tau z)$ , ( $0 \leq \tau \leq 1$ ), and  $\varphi$  satisfies (3.1). The estimates (3.4), (3.5), (3.6), (3.7) combined with (3.3) show that in the case  $z \neq 0$

$$(3.8) \quad 2 V_0 \geq 2 \varepsilon \int_0^x h(s) ds + M_2 y^2 + M_3 z^2 + \varepsilon u^2 - M_4$$

where  $M_4 = \frac{h^2(0)}{a_3} + M_2 \Delta_1^2 + 3 \Delta_1^2 a_1 a_2$ . In the case  $z = 0$ , it is a simple matter to show that  $V_0$  an estimate of the form (3.8) holds but with the term  $M_3 z^2$  absent.

To complete the verification of (2.4), observe now from (2.1) and (2.3) that

$$(3.9) \quad 2V \geq 2\varepsilon \int_0^x h(s) ds - |x| + M_2 y^2 + M_3 z^2 + \varepsilon u^2 - M_4,$$

since  $|V_1| \leq |x|$ . Now if  $x \geq 0$

$$2\varepsilon \int_0^x h(s) ds - |x| = 2\varepsilon \int_0^x \left\{ h(s) - \frac{1}{2} \varepsilon^{-1} \right\} ds$$

and the integral on the right tends to  $+\infty$  as  $|x| \rightarrow \infty$  since  $h(x) \operatorname{sgn} x \rightarrow +\infty$  as  $|x| \rightarrow \infty$ . The case  $x \leq 0$  can be handled similarly. Therefore

$$2\varepsilon \int_0^x h(s) ds - |x| \rightarrow +\infty \quad \text{as } |x| \rightarrow \infty,$$

and, in view of (3.9), (2.4) holds.

4. Next we verify (2.6). Let  $(x, y, z, u) \equiv (x(t), y(t), z(t), u(t))$  be any solution of (2.5). The existence of  $\dot{V}^+ = \dot{V}_0 + \dot{V}_1^+$  is not in question. As for the actual value of  $\dot{V}^+$ , a simple calculation will show that

$$(4.1) \quad \begin{aligned} \dot{V}_0 = & -U_1 y^2 - U_2 z^2 - U_3 u^2 - U_4 + d_1 \{h'(x) - a_4\} yz + \\ & + d_1 g_x(x, y) yz + (d_2 y + z + d_1 u) \theta(t, x, y, z, u) \end{aligned}$$

where

$$\begin{aligned} U_1 &= \left[ d_2 \frac{g(x, y)}{y} - h'(x) - \frac{1}{y} \int_0^y g_x(x, s) ds \right], \\ U_2 &= \left[ a_2 - d_1 g_y(x, y) - \Phi(z)/z - \frac{d_1}{z} \int_0^z \psi_y(y, s) ds \right], \\ U_3 &= d_1 \varphi(z) - 1, \\ U_4 &= z\psi(y, z) - a_2 z^2 + d_2 y (\psi(y, z) - a_2 z), \end{aligned}$$

and that

$$(4.2) \quad \dot{V}_1^+ = \begin{cases} -h(x) \operatorname{sgn} x - (\psi(y, z) + g(x, y) + \theta) \operatorname{sgn} x, & |x| \geq |u + \Phi| \\ y \operatorname{sgn}(u + \Phi), & |x| \leq |u + \Phi| \end{cases}.$$

Here both the co-efficients  $U_4$  and  $U_3$  can be estimated as in the corresponding case (3.5) of [2]. In fact the estimates there show that

$$U_4 \geq -\varepsilon_0 a_3 y^2 \quad \text{for all } y, z; \quad U_3 \geq \varepsilon a_1 \quad \text{for all } z.$$

The term  $U_1$  satisfies

$$U_1 \geq \varepsilon \frac{g(x, y)}{y} + (a_4 - h'(x)) - \frac{1}{y} \int_0^y g_x(x, s) ds$$

since  $d_2 = \varepsilon + a_4 a_3^{-1}$  and  $\frac{g(x, y)}{y} \geq a_3 (y \neq 0)$ . Hence

$$U_1 y^2 + U_4 \geq \left\{ \varepsilon' a_3 + (a_4 - h'(x)) - \frac{1}{y} \int_0^y g_x(x, s) ds \right\} y^2, \quad \varepsilon' = \varepsilon - \varepsilon_0.$$

Note now that

$$(a_4 - h'(x)) (y^2 - d_1 yz) \geq - (a_4 - h'(x)) \frac{d_1^2}{4} z^2$$

$$-\frac{\varepsilon'}{4} a_3 y^2 + d_1 g_x(x, y) yz \geq - \frac{d_1^2 z^2}{\varepsilon' a_3} g_x^2(x, y)$$

for all  $x, y$  and  $z$ . Therefore

$$U_1 y^2 + U_4 + d_1 (a_4 - h'(x)) yz + d_1 g_x(x, y) yz$$

$$\geq \frac{\varepsilon'}{4} a_3 y^2 - (a_4 - h'(x)) \frac{d_1^2}{4} z^2 - \frac{d_1^2}{\varepsilon' a_3} g_x^2(x, y) z^2$$

since  $\frac{1}{y} \int_0^y g_x(x, s) ds \leq \frac{\varepsilon' a_3}{4}$ ,  $\varepsilon' = \varepsilon - \varepsilon_0$ . Lastly the estimates for  $U_2$  in

([1]; pp. 144) show clearly that

$$U_2 \geq \left( \Delta_0 / a_1 a_3 - \Delta_2 \varepsilon - \frac{d_1}{z} \int_0^z \psi_y(y, s) ds \right),$$

so that, in view of (1.4) and (1.9),

$$\left\{ U_2 - (a_4 - h'(x)) \frac{d_1^2}{4} - \frac{d_1^2}{\varepsilon' a_3} g_x^2(x, y) \right\} > \Delta_0 / (8 a_1 a_3)$$

with  $\varepsilon < \Delta_0 / (16 a_1 a_3 \Delta_2)$ . The various estimates obtained for  $U_i$ ,  $i = 1, 2, 3, 4$  together with (4.1) imply that  $\dot{V}_0$  satisfies

$$(4.3) \quad \dot{V}_0 \leq -M_5 (y^2 + z^2 + u^2) + M_6 (|y| + |z| + |u|)$$

for some constants  $M_5 > 0$ ,  $M_6 > 0$ .

The expression for  $\dot{V}_1^+$  in (4.2) yields

$$\dot{V}_1^+ \leq \begin{cases} -h(x) \operatorname{sgn} x + M_7 (1 + |y| + |z|), & |x| \geq |u + \Phi| \\ |y|, & |x| \leq |u + \Phi| \end{cases}$$

for some constant  $M_7 > 0$ , since  $\psi$  and  $\theta$  satisfy (1.8) and (1.10) respectively. Thus, in view of (4.3), there are constants  $M_8 > 0$ ,  $M_9 > 0$  such that  $\dot{V}^+$  satisfies

$$(4.4) \quad \dot{V}^+ \leq -M_5 (y^2 + z^2 + u^2) - h(x) \operatorname{sgn} x + M_7 (1 + |y| + |z| + |u|)$$

or

$$(4.5) \quad \dot{V}^+ \leq -M_5(y^2 + z^2 + u^2) + M_8(|y| + |z| + |u|)$$

according as  $|x| \geq |u + \Phi|$  or  $|x| \leq |u + \Phi|$ .

The usual two-stage argument will now yield (2.6). Indeed since  $h$  is continuous and satisfies (1.3), there is a constant  $M_9 > 0$  such that  $h(x) \operatorname{sgn} x \geq -M_9$  for all  $x$ . Thus, it will be clear from either of the two estimates (4.4) and (4.5) that  $\dot{V}^+$  satisfies

$$(4.6) \quad \dot{V}^+ \leq -1 \quad \text{provided} \quad y^2 + z^2 + u^2 \geq M_{10},$$

for some constants  $M_{10} > 0$ . Suppose, however, that  $y^2 + z^2 + u^2 \leq M_{10}$  and let  $M_{11} = \max_{|u|, |z| \leq M_{10}} |u + \Phi|$ . Then  $|x| \geq M_{11}$  implies  $|x| > |u + \Phi|$  and so, in this case, the estimate (4.4) is applicable. Since  $y^2 + z^2 + u^2 \leq M_{10}$ , (4.4) implies the existence of a constant  $M_{12} \geq M_{11}$  such that

$$(4.7) \quad \dot{V}^+ \leq -1 \quad \text{if} \quad y^2 + z^2 + u^2 \leq M_{10} \quad \text{but} \quad |x| \geq M_{12}.$$

The two results (4.6) and (4.7) together verify (2.6).

*Remarks.* The extension of the present result to an equation (1.2) with  $\theta$  satisfying

$$|\theta(t, x, y, z, u)| \leq A + B(y^2 + z^2 + u^2)^{1/2}, \quad A > 0, B > 0$$

can be carried out as in [2]. In fact, all that is necessary is to increase each of the estimates (4.4) and (4.5) with a term not exceeding  $BM_{13}(y^2 + z^2 + u^2)^{1/2}$ ,  $M_{13} = \max(1, d_1, d_2)$ . However if the constant  $B$  is fixed so that  $B < M_5/(2M_{13})$  the whole of the estimates for  $\dot{V}^+$  will remain true.

## REFERENCES

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