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## Convergent solutions of nonlinear differential equations

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Equazioni differenziali. - Convergent solutions of nonlinear differential equations. Nota di David Lowell Lovelady, presentata ${ }^{(*)}$ dal Socio G. Sansone.

Riassunto. - Sono date condizioni sufficienti che assicurano che se $f$ è convergente allora ogni soluzione $v(t)$ dell'equazione

$$
v^{\prime}(t)=f(t)+\mathrm{F}(t, v(t))
$$

è convergente.
Questi risultati sono applicati per scegliere $\lim _{t \rightarrow \infty} v(t)$.
Soluzioni convergenti sono pure ottenute per l'equazione perturbata

$$
u^{\prime}(t)=f(t)+\mathrm{F}(t, u(t))+\mathrm{G}(t, u(t)) .
$$

## I. Introduction

Let $Y$ be a Banach space with norm $\mid$, and let $R+$ be the set of all nonnegative real numbers. We shall obtain herein conditions which ensure that every solution $v$ of

$$
\begin{equation*}
v^{\prime}(t)=f(t)+\mathrm{F}(t, v(t)) \tag{I}
\end{equation*}
$$

is convergent (i.e., $\lim _{t \rightarrow \infty} v(t)$ exists), where F is a continuous function from $\mathrm{R}^{+} \times \mathrm{Y}$ to Y and $f$ is a convergent continuous function from $\mathrm{R}^{+}$to Y . The hypotheses which we shall place on F will be such that global existence and uniqueness for (I) follows from both of [13] and [17]. Our results on (I) will be related to the results of [12], and, indeed, the results of [12] will play a part in our proofs.

In § III we will indicate how the results of § II relate to terminal value problems for (I). In particular we will show that if $z_{0}$ is in Y then there is $p_{0}$ in $Y$ such that $v(t) \rightarrow z_{0}$ if $f(t) \rightarrow p_{0}$.

We will also treat the perturbed equation

$$
\begin{equation*}
u^{\prime}(t)=f(t)+\mathrm{F}(t, u(t))+\mathrm{G}(t, u(t)) \tag{2}
\end{equation*}
$$

and obtain conditions which ensure the convergence of its solutions. The technique in (2) will be to cite asymptotic equivalence results from [II] which ensure that ( I ) and (2) have the same asymptotic behavior. Thus asymptotic conclusions for (I) can be transferred to (2). Since the proofs in [II] required that Y be finitedimensional, we will impose that restriction when studying (2).

The problem of determining when solutions of ordinary differential equations are convergent has been studied by several Authors, usually for
(*) Nella seduta del 10 febbraio 1973.
linear equations with "small" nonlinear perturbations. See, for example, A. Wintner [19], [20], [21], F. Brauer [1], [2], T. G. Hallam [4], [5], Hallam, G. Ladas, and V. Lakshmikantham [7], Hallam and Lakshmikantham [8], Hallam and J. W. Heidel [6], and J. D. Mamedov [15]. Our techniques will be the use of differential inequalities of Lakshmikantham and S. Leela [9] and the notion of logarithmic derivative developed by T. Ważewski [18] and S. M. Lozinskii [I4] and most recently employed by R. H. Martin, Jr. and the present Author [16], [13], [io], [II], [12].

## II. Convergent solutions

Let $\varphi$ be a continuous real-valued function on $\mathrm{R}^{+}$. We shall need the following conditions for our theorems.
$\left(C_{I}\right)$ : If $(t, x, y)$ is in $\mathrm{R}^{+} \times \mathrm{Y} \times \mathrm{Y}$ and $c$ is a positive number then

$$
|x-y-c[\mathrm{~F}(t, x)-\mathrm{F}(t, y)]| \geq[\mathrm{I}-c \varphi(t)]|x-y|
$$

(C2): There is a number M such that

$$
\int_{0}^{t} \exp \left[\int_{s}^{t} \varphi(r) \mathrm{d} r\right] \mathrm{d} s \leq \mathrm{M}
$$

whenever $t$ is in $\mathrm{R}^{+}$.
$\left.{ }^{( } C_{3}\right)$ : If $x$ is in Y then $\lim _{t \rightarrow \infty} \mathrm{~F}(t, x)$ exists, and if K is a compact subset of Y . then this convergence is uniform for $x$ in K .

Theorem i. Let $f$ be a convergent continuous function from $\mathrm{R}^{+}$to Y , and suppose that each of $\left(C_{I}\right),\left(C_{2}\right)$, and $\left(C_{3}\right)$ is true. Then there is a member $z$ of Y such that if $v$ is a continuously differentiable function satisfying ( I ) on $\mathrm{R}^{+}$then

$$
\lim _{t \rightarrow \infty} v(t)=z
$$

It should be noted that in Theorem I the existence of $\lim _{t \rightarrow \infty} v(t)$ is part of the conclusion, not hypothesis. The theorem can be thought of as saying that every solution of ( I ) is convergent and all solutions converge to the same point. It is known that ( $C I$ ) implies that if $x$ is in Y then there is exactly one continuously differentiable function $v$ from $\mathrm{R}^{+}$to Y such that $v(0)=x$ and such that ( I ) is true whenever $t$ is in $\mathrm{R}^{+}$. This result was obtained independently by N. Pavel [ ${ }^{7} 7$ ] and by R. H. Martin, Jr. and the present Author [13]. Before proving Theorem I , we need the following lemma. Note that if (C2) holds then M is necessarily positive.

Lemma. Suppose that (C2) is true, and let $m=1 / \mathrm{M}$. Then

$$
\liminf _{t \rightarrow \infty} \varphi(t) \leq-m
$$

Proof. It follows from [3, Lemma i, p. 68] that there is a number $k$ such that

$$
\exp \left[\int_{0}^{t} \varphi(s) \mathrm{d} s\right] \leq \exp (k-m t)
$$

whenever $t$ is in $\mathrm{R}^{+}$. Thus

$$
\int_{0}^{t} \varphi(s) \mathrm{d} s \leq k-m t
$$

whenever $t$ is in $\mathrm{R}^{+}$. Now, if $b$ is in $\mathrm{R}^{+}$and $\varepsilon$ is a positive number and $\varphi(t) \geq-m+\varepsilon$ whenever $t$ is in $[b, \infty)$, then

$$
\begin{aligned}
k-m t & \geq \int_{0}^{t} \varphi(s) \mathrm{d} s \\
& =\int_{0}^{b} \varphi(s) \mathrm{d} s+\int_{b}^{t} \varphi(s) \mathrm{d} s \\
& \geq \int_{0}^{b} \varphi(s) \mathrm{d} s+(-m+\varepsilon)(t-b)
\end{aligned}
$$

whenever $t$ is in $[b, \infty)$. This clearly cannot be, so the lemma is proved.
Proof of Theorem I. Let A from Y to Y be given by $\mathrm{A}(x)=\lim _{t \rightarrow \infty} \mathrm{~F}(t, x)$. Now, by ( $C_{3}$ ), A is continuous on compact subsets of Y and hence is continuous on Y. Also, if $(x, y)$ is in $\mathrm{Y} \times \mathrm{Y}$ and $c$ is a positive number,

$$
\begin{aligned}
|x-y-c[\mathrm{~A}(x)-\mathrm{A}(y)]| & =\lim _{t \rightarrow \infty}|x-y-c[\mathrm{~F}(t, x)-\mathrm{F}(t, y)]| \\
& \geq \limsup _{t \rightarrow \infty}[\mathrm{I}-c \varphi(t)]|x-y| \\
& \geq[\mathrm{I}+c m]|x-y|
\end{aligned}
$$

It now follows from [16] that if $p$ is in Y then there is exactly one member $z$ of Y such that $p+\mathrm{A}(z)=0$. Let $p=\lim _{t \rightarrow \infty} f(t)$ and find $z$ such that $p+\mathrm{A}(z)=\mathrm{o}$. Thus $\lim _{t \rightarrow \infty}|f(t)+\mathrm{F}(t, z)|=0$. It follows from the results cited in the proof of the lemma that

$$
\begin{equation*}
\lim _{t \rightarrow \infty} \exp \left[\int_{0}^{t} \varphi(s) \mathrm{d} s\right]=\mathrm{o} \tag{3}
\end{equation*}
$$

and now an easy computation shows that

$$
\begin{equation*}
\lim _{t \rightarrow \infty} \int_{0}^{t}|f(s)+\mathrm{F}(x, z)| \exp \left[\int_{s}^{t} \varphi(r) \mathrm{d} r\right] \mathrm{d} s=0 \tag{4}
\end{equation*}
$$

Now [12] says that (3) and (4) imply the conclusion of the theorem, and we are through.

## III. TERMINAL VALUE PROBLEMS

It is clear in Theorem 1 that $z$ depends on $f$, or, more specifically, on $\lim _{t \rightarrow \infty} f(t)$. This brings up the question of controlling (I) with chosen forcing functions, in order to reach a desired terminal value.

TheOrem 2. Let each of $(C I),(C 2)$, and $\left(C_{3}\right)$ be true, and let $z_{0}$ be in Y. Then there is a member $p_{0}$ of Y such that, if $f$ is a continuous function from $\mathrm{R}^{+}$to Y and $p_{0}=\lim _{t \rightarrow \infty} f(t)$, then every solution $v$ of ( I ) satisfies

$$
z_{0}=\lim _{t \rightarrow \infty} v(t)
$$

Theorem 2 is clear from the construction in the proof of Theorem 1 , and we shall not include a proof here.

## IV. Stability of CONVERGENT SOLUTIONS

From this point forward we shall assume that $Y$ is finitedimensional. Let $G$ be a continuous function from $R^{+} \times Y$ to $Y$, and let $\omega$ be a continuous function from $\mathrm{R}^{+} \times \mathrm{R}^{+}$to $\mathrm{R}^{+}$. We shall need the following conditions.
(C4): If $(t, x)$ is in $\mathrm{R}^{+} \times \mathrm{Y}$ then $|\mathrm{G}(t, x)| \leq \omega(t,|x|)$.
$(C 5)$ : If $c$ is in $\mathrm{R}^{+}$then $\lim _{t \rightarrow \infty} \omega(t, c)=0$.
(C6): If $(r, s, t)$ is in $\mathrm{R}^{+} \times \mathrm{R}^{+} \times \mathrm{R}^{+}$and $s \leq t$ then $\omega(r, s) \leq \omega(r, t)$.
THEOREM 3. Suppose that each of (CI), (C2), (C4), (C5), and (C6) is true and that $f$ is a continuous function from $\mathrm{R}^{+}$to Y . Then ( I ) and (2) are asymptotically equivalent in the sense that each of (i) and (ii) is true.
(i): If $v$ is a bounded solution of $(\mathrm{I})$ on $\mathrm{R}^{+}$then there is a member $b$ of $\mathrm{R}^{+}$and a solution $u$ of $(2)$ on $[b, \infty)$ such that

$$
\begin{equation*}
\lim _{t \rightarrow \infty}|v(t)-u(t)|=0 \tag{5}
\end{equation*}
$$

(ii): If $b$ is in $\mathrm{R}^{+}$and $u$ is a bounded solution of (2) on $[b, \infty)$ then there is a solution $r$ of $(\mathrm{I})$ on $[b, \infty)$ such that (5) is true.

Theorem 4. Suppose that, in addition to the hypotheses of Theorem 3, $\left(C_{3}\right)$ is true and $f$ is convergent. Then there is a member $b$ of $\mathrm{R}^{+}$such that there exists a convergent solution of (2) on $[b, \infty)$. Furthermore, if $b$ is in $\mathrm{R}^{+}$and $u$ is a bounded solution of (2) on $[b, \infty)$ then $u$ is convergent.

Theorem 3 follows easily from arguments so similar to the proof of [in, Theorem] that we shall not include them here. Theorem 4 follows directly from Theorems 1 and 3. Note that, in Theorem 4, all bounded (and hence convergent) solutions of (2) have the same limit, since (5) is true and we know from Theorem i that all solutions of ( I ) have the same limit.

The condition on the dimension of Y was imposed so as to permit the proof ideas of [II] to carry over to Theorem 3. The proof of [II, Theorem] involved applying the Schauder-Tychonoff theorem, in the form of [3, p. 9], to sets of Y -valued functions, and this requires Y to be finitedimensional.

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