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**Convergence of solutions of perturbed non-linear  
differential equations**

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**Equazioni differenziali ordinarie.** — *Convergence of solutions of perturbed non-linear differential equations.* Nota di B. S. LALLI e R. S. RAMBALLY, presentata (\*) dal Socio G. SANSONE.

**RIASSUNTO.** — Si studiano i sistemi  $y' = f(t, y)$ ,  $y' = f(t, y) + g(t, y)$  e si trovano condizioni sufficienti per la convergenza delle soluzioni di tali sistemi. I risultati ottenuti generalizzano quelli di un altro Autore.

1. We shall consider the following systems of differential equations:

$$(1) \quad x' = f(t, x)$$

$$(2) \quad y' = f(t, y) + g(t, y),$$

where  $x, y, f$  and  $g$  are  $n$ -vectors. We assume that  $f$  and  $g$  are continuous from  $\mathbb{R}_+ \times \mathbb{R}^n$  to  $\mathbb{R}^n$  and that the Jacobian matrix  $f_x$  is continuous on  $\mathbb{R}_+ \times \mathbb{R}^n$ . Our main purpose is to generalize some of Hallam's results [1] through the use of his own techniques.

We denote by  $x(t, t_0, x_0)$  the solution of (1) passing through  $(t_0, x_0) \in \mathbb{R}_+ \times \mathbb{R}^n$ . Recall that the variational system of (1) associated with the solution  $x(t, t_0, x_0)$  is the system

$$(3) \quad z' = f_x(t, x(t, t_0, x_0))z.$$

We usually denote by  $\Phi(t, t_0, x_0)$  the fundamental matrix of (3) such that  $\Phi(t_0, t_0, x_0) = I$ , the identity matrix. The non-linear variation of parameters formula, of which much use is made, can be written as

$$(4) \quad \begin{aligned} y(t, t_0, y_0) &= x(t, t_0, y_0) \\ &+ \int_{t_0}^t \Phi(t, s, y(s, t_0, y_0))g(s, y(s, t_0, y_0))ds. \end{aligned}$$

2. Avramescu [2] introduced the following definitions concerning the convergent behavior of systems of differential equations:

(i) Equation (1) is *convergent* if  $\lim_{t \rightarrow \infty} x(t, t_0, x_0) = \lambda(t_0, x_0)$  is defined for each  $(t_0, x_0) \in \mathbb{R}_+ \times \mathbb{R}^n$ .

(ii) Equation (1) is *equi-convergent* if it is convergent and for each  $\epsilon > 0$ ,  $\alpha > 0$ ,  $t_0 \geq 0$ , there exists a function  $T = T(t_0, \alpha, \epsilon)$  such that  $\|x(t, t_0, x_0) - \lambda(t_0, x_0)\| < \epsilon$  whenever  $t > t_0 + T$  and  $\|x_0\| \leq \alpha$ . Note that

(\*) Nella seduta del 16 giugno 1972.

the symbol  $\|\cdot\|$  denotes some convenient norm on  $R^n$  and a corresponding matrix norm.

(iii) Equation (1) is *equi-uniformly convergent* if it is equi-convergent and the  $T$  in the above definition is independent of  $t_0$ .

(iv) Equation (1) is called *coalescent* if it is convergent and if  $\lambda(0, x_0)$  is a constant.

The above definitions are also applicable on a subset  $D$  of  $R_+ \times R^n$ . The following terminology will also be used in the sequel.

(v) Equation (1) is *equi-uniformly convergent in variation* if for each  $\epsilon > 0$  and each  $\alpha > 0$  there exist a scalar function  $T = T(\alpha, \epsilon)$  and a matrix function  $L = L(t_0, x_0)$ , which is continuous on  $R_+ \times R^n$  and bounded on  $R_+$ , such that

$$\|\Phi(t, t_0, x_0) - L(t_0, x_0)\| < \epsilon$$

whenever  $t > t_0 + T$ ,  $\|x_0\| \leq \alpha$ ,  $t_0 \in R_+$ .

**THEOREM I.** Suppose that equation (1) is convergent and equi-uniformly convergent in variation. For each  $\alpha > 0$ , let  $\omega_\alpha(t, \|y\|)$  be such that

$$(5) \quad \|g(t, y)\| \leq \omega_\alpha(t, \|y\|) \quad \text{whenever } \|y\| \leq \alpha,$$

where  $\omega_\alpha(t, r)$  is a continuous, monotone, non-decreasing function in  $r$  for each fixed  $t$  such that

$$(6) \quad \int_c^\infty \omega_\alpha(t, c) dt < \infty, \quad 0 \leq c \leq \alpha.$$

Then for any initial position  $y_0$ , there exists a  $J = J(y_0)$  such that if  $t_0 \geq J$  the solution  $y(t, t_0, y_0)$  of (2) is convergent.

*Proof.* Brauer [3] has shown that if (1) is equi-uniformly convergent in variation, then it is uniformly stable in variation. Thus, for each  $\alpha > 0$  there exists  $M = M(\alpha)$  such that  $\|x_0\| \leq \alpha$  implies that

$$\|\Phi(t, t_0, x_0)\| \leq M(\alpha), \quad t \geq t_0 \geq 0.$$

Let  $y_0$  be given and consider the solution  $x(t, t_0, y_0)$ . Since (1) is convergent, there exists a constant  $B$  such that

$$\|x(t, t_0, y_0)\| \leq B \quad \text{for } t \geq t_0.$$

Let  $J$  be large enough so that

$$(7) \quad \int_J^\infty \omega_{2B}(t, 2B) dt < \frac{B}{M(2B)} \quad (\text{i.e. let } \alpha \text{ in hypothesis be } 2B).$$

We claim that for  $t \geq t_0 \geq J$ ,  $\|y(t, t_0, y_0)\| < 2B$ .

If this is not so, then consider the first  $t$ -value, call it  $t_1$ , such that  $\|\gamma(t_1, t_0, y_0)\| = 2B$ . Then using (4), (5) and (7), we obtain the following inequalities.

$$2B = \|\gamma(t_1, t_0, y_0)\| \leq \|x(t_1, t_0, y_0)\| + \int_{t_0}^{t_1} \|\Phi(t_1, s, y(s, t_0, y_0))\| \cdot$$

$$\cdot \|g(s, y(s, t_0, y_0))\| ds \leq B + M(2B) \int_{t_0}^{t_1} \omega_{2B}(s, 2B) ds < 2B.$$

Hence our claim is justified. [Note that on  $[t_0, t_1]$ ,  $\|\gamma(t, t_0, y_0)\| \leq 2B$  so that  $\|\Phi(t, s, y(s, t_0, y_0))\| \leq M(2B)$  on this interval].

In order to show the convergence of  $y(t, t_0, y_0)$  we show

$$(8) \quad \begin{aligned} & \lim_{t \rightarrow \infty} \int_{t_0}^t \Phi(t, s, y(s, t_0, y_0)) g(s, y(s, t_0, y_0)) ds \\ &= \int_{t_0}^{\infty} L(s, y(s, t_0, y_0)) g(s, y(s, t_0, y_0)) ds. \end{aligned}$$

[Note that the last integral is well defined since  $L(s, y(s)) \leq \Phi(t, s, y(s, t_0, y_0))$  so that

$$\begin{aligned} & \int_{t_0}^{\infty} L(s, y(s, t_0, y_0)) g(s, y(s, t_0, y_0)) ds \\ & \leq \int_{t_0}^{\infty} \Phi(t, s, y(s, t_0, y_0)) g(s, y(s, t_0, y_0)) ds. \end{aligned}$$

Thus this last integral is majorized by the integral

$$\int_{t_0}^{\infty} M(2B) \omega_{2B}(s, 2B) ds].$$

Now let  $\epsilon > 0$  be given. Let  $T_0$  be large enough so that

$$(9) \quad \int_{T_0}^{\infty} \omega_{2B}(s, 2B) ds < \frac{\epsilon}{3M(2B)}.$$

Since (1) is equi-uniformly convergent in variation, there exists  $T_1, T_1 \geq T_0$  such that if  $t \geq T_1$ , then

$$(10) \quad \|\Phi(t, s, y(s, t_0, y_0)) - L(s, y(s, t_0, y_0))\| < \frac{\epsilon}{3T_0 K}$$

where  $K = \max \|g(t, y)\|$  over

$$\|y\| \leq 2B, \quad t_0 \leq t \leq T_0.$$

Then for  $t \geq T_1$  we have, using (9) and (10)

$$\begin{aligned}
 (11) \quad & \left\| \int_{t_0}^t \Phi(t, s, y(s, t_0, y_0)) g(s, y(s, t_0, y_0)) ds \right. \\
 & \left. - \int_{t_0}^{\infty} L(s, y(s, t_0, y_0)) g(s, y(s, t_0, y_0)) ds \right\| \\
 & \leq \int_{t_0}^{T_0} \|\Phi(t, s, y(s, t_0, y_0)) - L(s, y(s, t_0, y_0))\| \|g(s, y(s, t_0, y_0))\| ds \\
 & + \int_{T_0}^{\infty} \|\Phi(t, s, y(s, t_0, y_0)) g(s, y(s, t_0, y_0))\| ds \\
 & + \int_{T_0}^{\infty} \|L(s, y(s, t_0, y_0)) g(s, y(s, t_0, y_0))\| ds \\
 & \leq \frac{\varepsilon}{3T_0 K} K(T_0 - t_0) + 2 \int_{T_0}^{\infty} M(2B) \omega_{2B}(s, 2B) ds \\
 & < \frac{\varepsilon}{3} + 2 \left( \frac{\varepsilon}{3} \right) = \varepsilon.
 \end{aligned}$$

Thus

$$\begin{aligned}
 & \lim_{t \rightarrow \infty} \int_{t_0}^t \Phi(t, s, y(s, t_0, y_0)) g(s, y(s, t_0, y_0)) ds \\
 & = \int_{t_0}^{\infty} L(s, y(s, t_0, y_0)) g(s, y(s, t_0, y_0)) ds.
 \end{aligned}$$

Let  $\lambda_y(t_0, y_0)$  and  $\lambda_x(t_0, y_0)$  be the limits  $\lim_{t \rightarrow \infty} y(t, t_0, y_0)$  and  $\lim_{t \rightarrow \infty} x(t, t_0, y_0)$  respectively. Now

$$y(t, t_0, y_0) = x(t, t_0, y_0) + \int_{t_0}^t \Phi(t, s, y(s, t_0, y_0)) g(s, y(s, t_0, y_0)) ds.$$

Thus

$$\lambda_y(t_0, y_0) = \lambda_x(t_0, y_0) + \lim_{t \rightarrow \infty} \int_{t_0}^t \Phi(t, s, y(s, t_0, y_0)) g(s, y(s, t_0, y_0)) ds.$$

Using (8) we get

$$(12) \quad \lambda_y(t_0, y_0) = \lambda_x(t_0, y_0) + \int_{t_0}^{\infty} L(s, y(s, t_0, y_0)) g(s, y(s, t_0, y_0)) ds.$$

Hence  $y(t, t_0, y_0)$  is convergent and the theorem is proved.

We now consider a fixed  $y_0 \in \mathbb{R}^n$ . Let  $J_0(y_0)$  be the infimum of all those  $J(y_0)$  for which Theorem 1 is satisfied. Let  $D = \{(t, y) \mid y \in \mathbb{R}^n, t > J_0(y_0)\}$ . In the next two theorems, we consider convergence on this set  $D$ .

**THEOREM 2.** *Assume that equation (1) is equi-convergent and equi-uniformly convergent in variation. Assume that (5) and (6) hold. Then equation (2) is equi-convergent on D.*

*Proof.* We first note that all hypotheses of Theorem 1 are satisfied and so all equations in its proof are applicable here. In particular, we shall make use of equation (12).

Since equation (1) is equi-convergent, we have, for  $(t_0, y_0) \in D$  with  $\|y_0\| \leq \alpha$ ,  $B = B(\alpha)$  such that  $\|y(t, t_0, y_0)\| \leq B$ . Using equations (4) and (12), we obtain

$$(13) \quad \begin{aligned} y(t, t_0, y_0) - \lambda_y(t_0, y_0) &= x(t, t_0, y_0) - \lambda_x(t_0, y_0) \\ &\quad + \int_{t_0}^t \Phi(t, s, y(s, t_0, y_0)) g(s, y(s, t_0, y_0)) ds \\ &\quad - \int_{t_0}^{\infty} L(s, y(s, t_0, y_0)) g(s, y(s, t_0, y_0)) ds. \end{aligned}$$

Exactly as was done in Theorem 1, we can find  $T_1$  such that for  $t \geq T_1$  we have

$$\begin{aligned} &\left\| \int_{t_0}^t \Phi(t, s, y(s, t_0, y_0)) g(s, y(s, t_0, y_0)) ds \right. \\ &\quad \left. - \int_{t_0}^{\infty} L(s, y(s, t_0, y_0)) g(s, y(s, t_0, y_0)) ds \right\| \\ &< \frac{\varepsilon}{2} \end{aligned}$$

for any  $\varepsilon > 0$ . By the equi-convergence of equation (1) we can also find  $T_2$  such that

$$\|x(t, t_0, y_0) - \lambda_x(t_0, y_0)\| < \frac{\varepsilon}{2}, \quad t \geq T_2.$$

Let  $t > \max\{T_1, T_2\}$ . For any such  $t$ , (13) gives

$$\|y(t, t_0, y_0) - \lambda_y(t_0, y_0)\| < \varepsilon.$$

This gives us the equi-convergence of equation (2) on  $D$ .

By a very similar argument we can obtain:

**THEOREM 3.** Assume that equation (1) is equi-uniformly convergent and equi-uniformly convergent in variation. Assume that equations (5) and (6) are satisfied. Then equation (2) is equi-uniformly convergent on D.

Finally we give a condition for convergent solutions of (2) to be coalescent.

**THEOREM 4.** Assume that equation (1) is coalescent to  $x_\infty$  and that

$$\|g(t, y)\| \leq \omega_\alpha(t, \|y\|), \quad \text{any } \alpha > 0, \quad \|y\| \leq \alpha$$

where  $\omega_\alpha(t, r)$  is a continuous, non-decreasing function in  $r$  for each fixed  $t$ . Also suppose that for each  $\alpha > 0$  there exists a continuous function  $\eta_\alpha : \mathbb{R}_+ \times \mathbb{R}_+ \rightarrow \mathbb{R}_+$  such that

$$\|\Phi(t, t_0, x_0)\| \leq \eta_\alpha(t, t_0) \quad \text{for } t \geq t_0 \geq 0, \quad \|x_0\| \leq \alpha.$$

Suppose

$$\lim_t \int_0^t \eta_\alpha(t, s) \omega_\alpha(s, c) ds = 0, \quad 0 \leq c \leq \alpha.$$

Then all solutions of (2) coalesce to  $x_\infty$ .

*Proof.* Since equation (1) is coalescent, it is convergent. Let  $y(t, t_0, y_0)$  be a convergent solution of (2). Then

$$\lambda_y(t_0, y_0) = \lambda_x(t_0, y_0) + \lim_t \int_{t_0}^t \Phi(t, s, y(s, t_0, y_0)) g(s, y(s, t_0, y_0)) ds.$$

By convergence of  $y(t, t_0, y_0)$ , there exists a constant  $B > 0$  such that  $\|y(t, t_0, y_0)\| \leq B$ ,  $t \geq t_0$ . From the hypotheses on  $\Phi$  and  $g$ , we obtain

$$\begin{aligned} & \left\| \int_{t_0}^t \Phi(t, s, y(s, t_0, y_0)) g(s, y(s, t_0, y_0)) ds \right\| \\ & \leq \int_0^t \eta_B(t, s) \omega_B(s, B) ds. \end{aligned}$$

Thus

$$\lambda_y(t_0, y_0) = \lambda_x(t_0, y_0).$$

Hence equation (2) is coalescent to  $x_\infty$ .

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