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**Further results on the Boundedness and the Stability
of certain fourth order differential equations**

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Equazioni differenziali. — *Further results on the Boundedness and the Stability of certain fourth order differential equations.* Nota di H. O. TEJUMOLA, presentata (*) dal Socio G. SANSONE.

RIASSUNTO. — Si dimostrano due Teoremi sulla limitatezza e stabilità delle soluzioni di una classe di equazioni differenziali non lineari del quarto ordine.

1. INTRODUCTION

Consider the fourth order differential equation

$$(1.1) \quad x^{(4)} + \varphi_1(\ddot{x})\ddot{x} + a_2\ddot{x} + \varphi_3(\dot{x}) + a_4x = p(t, x, \dot{x}, \ddot{x})$$

in which $a_2 > 0$, $a_4 > 0$ are constants and the functions φ_1 , φ_3 and p which depend only on the arguments displayed are such that $\varphi_1(z)$, $\varphi_1'(y)$, $p(t, x, y, z, u)$ are continuous for all x, y, z, u and t . In the case $p \equiv 0$ in (1.1), Ezeilo [1] showed that if $\varphi_3(0) = 0$ and there are constants $a_1 > 0$, $a_3 > 0$ such that

$$(1.2) \quad \varphi_3(y)/y \geq a_3 (y \neq 0) \quad \text{and} \quad \varphi_1(z) \geq a_1 \quad \text{for all } z,$$

$$(1.3) \quad \{a_1 a_2 - \varphi_3'(y)\} a_3 - a_1 a_4 \varphi_1(z) \geq \Delta_0 \quad (\text{arbitrary } y \text{ and } z)$$

for some constant $\Delta_0 > 0$,

$$(1.4) \quad \varphi_3'(y) - \varphi_3(y)/y \leq \delta_1 (y \neq 0),$$

where δ_1 is a constant such that $\delta_1 < 2 \Delta_0 a_4 a_1^{-1} a_3^{-2}$,

$$(1.5) \quad z^{-1} \int_0^z \varphi_1(s) ds - \varphi_1(z) \leq \delta_2 (z \neq 0),$$

where δ_2 is a constant such that $\delta_2 < 2 \Delta_0 a_1^{-2} a_3^{-1}$, then every solution $x(t)$ of (1.1) satisfies

$$(1.6) \quad x(t) \rightarrow 0, \quad \dot{x}(t) \rightarrow 0, \quad \ddot{x}(t) \rightarrow 0, \quad \ddot{\ddot{x}}(t) \rightarrow 0 \quad \text{as } t \rightarrow \infty.$$

The conditions (1.2) and (1.3) together with $a_i > 0$, $i = 1, 2, 3, 4$ are suitable generalizations of the Routh-Hurwitz conditions

$$a_i > 0 \quad (i = 1, 2, 3, 4), \quad (a_1 a_2 - a_3) a_3 - a_1^2 a_4 > 0$$

(*) Nella seduta dell'11 dicembre 1971.

for the asymptotic stability (in the large) of the trivial solution of the linear equation

$$x^{(4)} + a_1 \ddot{x} + a_1 \ddot{x} + a_3 \dot{x} + a_4 x = 0.$$

For the general case $p \not\equiv 0$, the present author [2] showed that if, in addition to the above conditions, p is a bounded function, then every solution of (1.1) is ultimately bounded.

The main object of the present note is to extend these results to equations of the form

$$(1.7) \quad x^{(4)} + \varphi_1(\ddot{x}) \ddot{x} + \varphi_2(\ddot{x}) + \varphi_3(\dot{x}) + a_4 x = p(t, x, \dot{x}, \ddot{x}, \ddot{x})$$

of which (1.1) is a special case corresponding to $\varphi_2(\ddot{x})$ linear in (1.7). We shall prove here

THEOREM 1. *Suppose, given the equation*

$$(1.8) \quad x^{(4)} + \varphi_1(\ddot{x}) \ddot{x} + \varphi_2(\ddot{x}) + \varphi_3(\dot{x}) + a_4 x = 0,$$

that

$$(i) \quad \varphi_2(0) = 0 = \varphi_3(0),$$

(ii) *there are constants $a_1 > 0$, $a_2 > 0$, $a_3 > 0$ such that each of (1.2), (1.3), (1.4), (1.5) and the following hold:*

$$(1.9) \quad 0 \leq (\varphi_2(z)/z - a_2) \leq \varepsilon_0 a_3^3/a_4^2 (z \neq 0),$$

where ε_0 is a positive constant such that

$$(1.10) \quad \varepsilon_0 < \varepsilon \leq \left[\frac{a_4}{a_3}, \frac{\Delta_0}{a_1 a_3 \Delta_1}, \frac{a_1}{4 \Delta_1} \left(\frac{2 \Delta_0}{a_1^2 a_3} - \delta_2 \right), \frac{a_3}{4 a_4 \Delta_1} \left(\frac{2 a_4 \Delta_0}{a_1 a_3^2} - \delta_1 \right) \right],$$

$\Delta_1 = a_1 a_2 + a_2 a_3 a_4^{-1}$. Then every solution $x(t)$ of (1.8) satisfies (1.6).

For the case $p \not\equiv 0$, we shall prove

THEOREM 2. *Let hypotheses (i) and (ii) of Theorem 1 hold and suppose further that*

$$(1.11) \quad |p(t, x, y, z, u)| \leq A < \infty$$

for all values of t, x, y, z and u . Then there exists a finite constant $D > 0$ whose magnitude depends only on φ_1, φ_2 and φ_3 as well as on $a_1, a_2, a_3, a_4, \delta_1, \delta_2, \Delta_0$ and A such that every solution $x(t)$ of (1.7) satisfies

$$(1.12) \quad |x(t)| \leq D, \quad |\dot{x}(t)| \leq D, \quad |\ddot{x}(t)| \leq D, \quad |\ddot{x}(t)| \leq D$$

for all $t \geq t_0$ ($0 < t_0 < \infty$).

A generalization of the Theorem will be given in § 5.

2. SOME PRELIMINARIES

A function $W_0(x, y, z, u)$. The main tool in the proofs of Theorems 1 and 2 is the differentiable function $W_0 = W_0(x, y, z, u)$ defined by

$$(2.1) \quad 2W_0 = a_4 d_2 x^2 + (a_2 d_2 - a_4 d_1) y^2 + 2 \int_0^y \varphi_3(\eta) d\eta + 2 \int_0^z \eta \varphi_1(\eta) d\eta \\ + 2 \int_0^z \{d_1 \varphi_2(\eta) - d_2 \eta\} d\eta + d_1 u^2 + 2 a_4 xy + 2 a_4 d_1 xz \\ + 2 d_1 z \varphi_3(y) + 2 d_2 yu + 2 zu + 2 d_2 y \int_0^z \varphi_1(\eta) d\eta$$

where

$$(2.2) \quad d_1 = \varepsilon + a_1^{-1}, \quad d_2 = \varepsilon + a_1^{-3} a_4,$$

$\varepsilon > 0$ being the constant in (1.10).

Notations. In what follows the capitals D, D_0, D_1, \dots denote finite positive constants whose magnitudes depend only on the functions $\varphi_1, \varphi_2, \varphi_3$ and p as well as on the constants $a_1, a_2, a_3, a_4, \delta_1, \delta_2, \Delta_0, \varepsilon_0$, and ε , but are independent of solutions of whatever differential equation under consideration. The D_i 's, $i = 0, 1, 2$ retain a fixed identity throughout, but the D 's without suffixes attached are not necessarily the same each time they occur.

3. PROOF OF THEOREM 1

The procedure here is the same as in [1] and we shall only sketch the outline. Consider, instead of (1.8), the equivalent system

$$(3.1) \quad \dot{x} = y, \quad \dot{y} = z, \quad \dot{z} = u, \quad \dot{u} = -\varphi_1(z)u - \varphi_2(z) - \varphi_3(y) - a_4 x$$

derived from it by setting $y = \dot{x}$, $z = \ddot{x}$ and $u = \dddot{x}$. The whole idea of the proof of the theorem is to show that W_0 is a Lyapunov function for the system (3.1). In fact, we shall verify that

LEMMA 1. *Subject to the conditions of Theorem 1:*

(i) $W_0(0, 0, 0, 0) = 0$ and there exist constants D_i , $i = 1, 2, 3, 4$ such that

$$(3.2) \quad W_0 \geq D_1 x^2 + D_2 y^2 + D_3 z^2 + D_4 u^2$$

for all x, y, z and u ;

(ii) the derivative $\dot{W}_0 \equiv \dot{W}_0(x(t), y(t), z(t), u(t))$ corresponding to any solution $(x(t), y(t), z(t), u(t))$ of (3.1) satisfies

$$(3.3) \quad \dot{W}_0 \leq -D_5 (y^2 + z^2 + u^2)$$

for some constant D_5 .

The usual Barbašin-type argument applied to (3.2) and (3.3) would then show that, for any solution $(x(t), y(t), z(t), u(t))$ of (3.1),

$$x(t) \rightarrow 0, \quad y(t) \rightarrow 0, \quad z(t) \rightarrow 0, \quad u(t) \rightarrow 0 \quad \text{as } t \rightarrow \infty,$$

which is (1.6).

Proof of Lemma 1. Since $\varphi_2(0) = 0$ and $\varphi_2(z)/z \geq a_2$ ($z \neq 0$), by (1.8), it is clear from (2.1) that

$$\begin{aligned} 2W_0 &\geq a_4 d_2 x^2 + (a_2 d_2 - a_4 d_1) y^2 + 2 \int_0^y \varphi_3(\eta) d\eta + 2 \int_0^z \eta \varphi_1(\eta) d\eta \\ &\quad + (a_2 d_1 - d_2) z^2 + d_1 u^2 + 2 a_4 xy + 2 a_4 d_1 xz + \\ &\quad + 2 d_1 z \varphi_3(y) + 2 d_2 yu + 2 zu + 2 d_2 y \int_0^z \varphi_1(\eta) d\eta \\ &\equiv 2\dot{W}_0^*. \end{aligned}$$

The function W_0^* is the same as the function V (3.1) of [1] except that here we have φ_1, φ_3 in place of f and g respectively and u in place of w . It will be seen from the various estimates arising in the course of the proof of [1; Lemma 1] that if ε is fixed by (1.10) then W_0^* , and hence W_0 , satisfies (3.2).

Turning now to (3.3), let $(x(t), y(t), z(t), u(t))$ be any solution of (3.1). By a straightforward differentiation from (2.1) we have that

$$(3.4) \quad \dot{W}_0 = -U_1 - U_2 - U_3 - U_4$$

where

$$(3.5) \quad \begin{aligned} U_1 &= d_2 y \varphi_3(y) - a_4 y^2, \quad U_2 = \{a_2 - d_1 \varphi_3'(y)\} z^2 - d_2 z \int_0^z \varphi_1(\eta) d\eta, \\ U_3 &= (d_1 \varphi_1(z) - 1) u^2, \quad U_4 = z \varphi_2(z) - a_2 z^2 + d_2 (y \varphi_2(z) - a_2 yz). \end{aligned}$$

By reasoning as in the proof of [1; Lemma 2], it can be shown from (1.2), (1.3) and (1.10) that

$$(3.6) \quad U_1 \geq a_3 \varepsilon y^2, \quad U_2 \geq \frac{1}{2} (\Delta_0/a_1 a_3) z^2, \quad U_3 \geq a_1 \varepsilon u^2.$$

Concerning the term U_4 , note that if $z \neq 0$,

$$\begin{aligned} U_4 &= (\varphi_2(z)/z - a_2) (z^2 + d_2 yz) \\ &\geq -(\varphi_2(z)/z - a_2) \frac{d_2^2}{4} y^2 \end{aligned}$$

by (1.9). Since $U_4 = 0$ when $z = 0$, U_4 satisfies

$$(3.7) \quad U_4 \geq -(\varphi_2(z)/z - a_2) \frac{d_2^2}{4} y^2$$

always. But by (2.2) and (1.9),

$$\frac{1}{4} d_2^2 (\varphi_2(z)/z - a_2) < \varepsilon_0 a_3;$$

therefore

$$(3.8) \quad U_1 + U_4 \geq (\varepsilon - \varepsilon_0) a_3 y^2.$$

On combining (3.8) and the estimates for U_2 and U_3 in (3.6) with (3.4), we get

$$\dot{W}_0 \leq -(\varepsilon - \varepsilon_0) a_3 y^2 - \frac{1}{2} (\Delta_0/a_1 a_3) z^2 - \varepsilon a_1 u^2,$$

which verifies (3.3). Theorem 1 now follows as was pointed out.

4. PROOF OF THEOREM 2

Here also we consider the differential system

$$(4.1) \quad \begin{aligned} \dot{x} &= y, & \dot{y} &= z, & \dot{z} &= u, \\ \dot{u} &= -\varphi_1(z)u - \varphi_2(z) - \varphi_3(y) - a_4 x + p(t, x, y, z, u), \end{aligned}$$

which is derived from (1.7) on setting $y = \dot{x}$, $z = \ddot{x}$ and $u = \ddot{\ddot{x}}$. Our procedure is the same as in the proof of the analogous result [2; Theorem 1], and we shall prove here that

LEMMA 2. *Assume that the conditions of Theorem 2 hold. Let $W_1 = W_1(x, u)$ be the continuous function defined by*

$$(4.2) \quad W_1 = \begin{cases} x \operatorname{sgn} u, & \text{if } |u| \geq |x| \\ u \operatorname{sgn} x, & \text{if } |u| \leq |x| \end{cases}$$

and set

$$(4.3) \quad W = W_0 + W_1,$$

where W_0 is the function (2.1). Then

$$(4.4) \quad W(x, y, z, u) \rightarrow +\infty \quad \text{as } x^2 + y^2 + z^2 + u^2 \rightarrow \infty,$$

and the limit

$$\begin{aligned} \dot{W}^+ &= \limsup_{h \rightarrow +0} \{ W(t+h), y(t+h), z(t+h), u(t+h) - \\ &\quad - W(x(t), y(t), z(t), u(t)) \} / h \end{aligned}$$

exists, corresponding to any solution $(x(t), y(t), z(t), u(t))$ of (4.1), and satisfies

$$(4.5) \quad \dot{W}^+ \leq -D_5 \quad \text{provided } x^2(t) + y^2(t) + z^2(t) + u^2(t) \geq D_6$$

for some constants D_5, D_6 .

As shown in [2; § 4], the two results (4.4) and (4.5) imply that

$$x^2(t) + y^2(t) + z^2(t) + u^2(t) \leq D, \quad t \geq t_0 \quad (0 < t_0 < \infty),$$

which is precisely (1.12).

Proof of Lemma 2. Clearly, from (4.2),

$$|W_1| \leq |u|$$

for all x and u , so that by (4.3) and (3.2)

$$W \geq D_1 x^2 + D_2 y^2 + D_3 z^2 + D_4 u^2 - |u|,$$

from which (4.4) follows.

Next we verify (4.5). Let $(x(t), y(t), z(t), u(t))$ be any solution of (4.1). Then

$$\dot{W}_1^+ = \limsup_{h \rightarrow +0} \{W_1(x(t+h), u(t+h)) - W_1(x(t), u(t))\}/h,$$

and a straightforward calculation from (4.2) and (4.1) gives that

$$\dot{W}_1^+ = \begin{cases} y \operatorname{sgn} u, & \text{if } |u| \geq |x| \\ -(\varphi_1(z)u + \varphi_2(z) + \varphi_3(y) + a_4 x - p) \operatorname{sgn} x, & \text{if } |u| \leq |x| \end{cases}.$$

Thus, by (1.9) and (1.11),

$$(4.6) \quad \dot{W}_1^+ \leq \begin{cases} |y|, & \text{if } |u| \geq |x| \\ -a_4 |x| + |\varphi_3(y)| + D_7(1 + |z| + |u|), & \text{if } |u| \leq |x| \end{cases},$$

where in obtaining (4.6) we also used the fact, arising from (1.3), that $\varphi_1(z) < a_2 a_3 a_4^{-1}$ for all z .

Observe now from (2.1) and (4.1) that

$$\dot{W}_0 = -U_1 - U_2 - U_3 - U_4 + (d_2 y + z + d_1 u) p(t, x, y, z, u)$$

U_1, U_2, U_3 and U_4 being as given in (3.5); therefore, by (1.11),

$$\dot{W}_0 \leq -U_1 - U_2 - U_3 - U_4 + D_8(|y| + |z| + |u|)$$

where $D_8 = \max(1, d_1, d_2)A$. From this, (3.6) and (4.6) it is clear that $\dot{W}^+ = \dot{W}_0 + \dot{W}_1^+$ necessarily satisfies

$$(4.7) \quad \dot{W}^+ \leq -U_1 - U_4 - \frac{1}{2}(\Delta_0/a_1 a_3)z^2 - a_1 \varepsilon u^2 + D_9(|y| + |z| + |u|)$$

if $|u| \geq |x|$, or

$$(4.8) \quad \begin{aligned} \dot{W}^+ &\leq -(U_1 - |\varphi_3(y)|) - U_4 - \frac{1}{2}(\Delta_0/a_1 a_3)z^2 - a_1 \varepsilon u^2 - a_4 |x| \\ &\quad + D_{10}(1 + |y| + |z| + |u|) \end{aligned}$$

if $|u| \leq |x|$.

First we show that there is a constant D_{11} such that

$$(4.9) \quad \dot{W}^+ \leq -1 \quad \text{whenever} \quad y^2 + z^2 + u^2 \geq D_{11}^2.$$

Indeed let $|y| > d_2^{-1}$. Then, by (3.5), (1.2) and (2.2)

$$\begin{aligned} U_1 - |\varphi_3(y)| &= (d_2 |y| - 1) |\varphi_3(y)| - a_4 y^2 \\ &\geq a_3 \varepsilon y^2 - a_3 |y|, \end{aligned}$$

so that, as in the verification of (3.8),

$$(U_1 - |\varphi_3(y)|) + U_4 \geq (\varepsilon - \varepsilon_0) a_3 y^2 - a_3 |y|.$$

On using this in (4.8) and noting that $U_1 + U_4$ in (4.7) satisfies (3.8), it will be clear from (4.7) and (4.8) that \dot{W}^+ , at least, satisfies

$$\dot{W}^+ \leq -D_{12} y^2 + D(|y| + 1)$$

for some constant D_{12} if $|y| > d_2^{-1}$. Thus, provided $|y| > d_2^{-1}$ is large enough, $|y| > D_{13}$ say,

$$(4.10) \quad \dot{W}^+ \leq -1 \quad \text{if} \quad |y| \geq D_{13} (> d_2^{-1}).$$

If, however, $|y| \leq d_2^{-1}$ it will be seen from (4.7), (4.8), (3.6) and (3.7) that

$$\dot{W}^+ \leq -\frac{1}{2} (\Delta_0/a_1 a_3) z^2 - a_1 \varepsilon u^2 + D(|z| + |u| + 1),$$

from which it follows that $\dot{W}^+ \leq -1$ when $|y| \leq d_2^{-1}$ provided $z^2 + u^2$ is large enough, say $z^2 + u^2 \geq D_{14}$. In other words,

$$(4.11) \quad \dot{W}^+ \leq -1 \quad \text{if} \quad y^2 + z^2 + u^2 \geq D_{12}^2 + D_{14}^2,$$

which is (4.9) with $D_{11}^2 = D_{12}^2 + D_{14}^2$.

Next, we verify that the estimate (4.11) still holds when $y^2 + z^2 + u^2 \leq D_{11}^2$ provided that $|x|$ is large enough. Assume here, to start with, that $|x| \geq D_{11}$. Then $|x| \geq |u|$ so that \dot{W}^+ satisfies (4.8). Since $y^2 + z^2 + u^2 \leq D_{11}^2$, it is clear here that

$$\begin{aligned} \dot{W}^+ &\leq -a_4 |x| + D_{15} \\ &\leq -1, \end{aligned}$$

provided $|x| \geq D_{11}$ is sufficiently large, say $|x| \geq D_{16} (\geq D_{11})$. Thus

$$(4.12) \quad \dot{W}^+ \leq -1 \quad \text{if} \quad y^2 + z^2 + u^2 \leq D_{11}^2 \quad \text{but} \quad |x| \geq D_{16}.$$

The result (4.12) combined with (4.11) clearly show that

$$\dot{W}^+ \leq -1 \quad \text{if} \quad x^2 + y^2 + z^2 + u^2 \geq D_{16}^2 + D_{11}^2,$$

which verifies (4.5).

Theorem 2 now follows as was pointed out.

5. A GENERALIZATION OF THEOREM 2

There is no difficulty in extending Theorem 2 to an equation (1.7) in which p satisfies

$$(5.1) \quad |p(t, x, y, z, u)| \leq A + B(y^2 + z^2 + u^2)^{1/2}$$

with $A > 0$ and $B > 0$ constants and B sufficiently small. Indeed the use of (5.1) instead of the condition (1.11) of Theorem 2 does not affect the work in § 4 appreciably. The main adjustments would occur in the two estimates (4.7) and (4.8) of \dot{W}^+ , each of which will now have to be augmented by a term not exceeding $BD_{17}(y^2 + z^2 + u^2)^{1/2}$, $D_{17} = 3^{1/2} \max(1, d_1, d_2)$. However, if B is fixed such that

$$B < \min \left[\frac{a_3 \varepsilon}{2 D_{17}}, \frac{\Delta_0}{4 a_1 a_3 D_{17}}, \frac{a_1 \varepsilon}{2 D_{17}} \right],$$

it will be seen, by using the arguments of § 4, that the two estimates (4.9) and (4.12) for \dot{W}^+ still hold valid under the condition (5.1).

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