

---

ATTI ACCADEMIA NAZIONALE DEI LINCEI  
CLASSE SCIENZE FISICHE MATEMATICHE NATURALI  
**RENDICONTI**

---

GIOVANNI PROUSE

**On a non—linear mixed problem for the  
Navier-Stokes equations. Nota II**

*Atti della Accademia Nazionale dei Lincei. Classe di Scienze Fisiche,  
Matematiche e Naturali. Rendiconti, Serie 8, Vol. **48** (1970), n.3, p. 293–296.  
Accademia Nazionale dei Lincei*

<[http://www.bdim.eu/item?id=RLINA\\_1970\\_8\\_48\\_3\\_293\\_0](http://www.bdim.eu/item?id=RLINA_1970_8_48_3_293_0)>

L'utilizzo e la stampa di questo documento digitale è consentito liberamente per motivi di ricerca e studio. Non è consentito l'utilizzo dello stesso per motivi commerciali. Tutte le copie di questo documento devono riportare questo avvertimento.

Atti della Accademia Nazionale dei Lincei. Classe di Scienze Fisiche, Matematiche e Naturali. Rendiconti, Accademia Nazionale dei Lincei, 1970.

RENDICONTI  
DELLE SEDUTE  
DELLA ACCADEMIA NAZIONALE DEI LINCEI

**Classe di Scienze fisiche, matematiche e naturali**

*Seduta del 14 marzo 1970*

*Presiede il Presidente BENIAMINO SEGRE*

**SEZIONE I**

**(Matematica, meccanica, astronomia, geodesia e geofisica)**

**Analisi matematica.** — *On a non-linear mixed problem for the Navier-Stokes equations.* Nota III di GIOVANNI PROUSE<sup>(\*)</sup>, presentata<sup>(\*\*)</sup> dal Corrisp. L. AMERIO.

**RIASSUNTO.** — Si dimostra un teorema di unicità della soluzione del problema posto nella Nota I.

4. Let us prove the following uniqueness theorem.

*Let  $\vec{u}(t), \vec{v}(t)$  be two solutions on  $0^{\perp} T$  of the Navier-Stokes system (in the sense indicated at § 3), corresponding to the same initial and boundary conditions. Then  $\vec{u}(t) \equiv \vec{v}(t)$ .*

We observe, first of all, that, setting  $\vec{w}(t) = \vec{u}(t) - \vec{v}(t)$ , the function  $\vec{w}(t)$  satisfies, by (3.15), the equation

$$(4.1) \quad \begin{aligned} & \int_0^T \left\{ -(\vec{w}(t), \vec{h}'(t))_{V_0} + \mu (\vec{w}(t), \vec{h}(t))_{V_1} + b(\vec{u}(t), \vec{u}(t), \vec{h}(t)) - \right. \\ & \left. - b(\vec{v}(t), \vec{v}(t), \vec{h}(t)) \right\} dt = \\ & = \int_0^T \int_0^k \left\{ \left( -\frac{1}{2} u_1^2(0, x_2, t) + \frac{1}{2} v_1^2(0, x_2, t) \right) h_1(0, x_2, t) + \right. \\ & \left. + \left( \frac{1}{2} u_1^2(l, x_2, t) - \frac{1}{2} v_1^2(l, x_2, t) \right) h_1(l, x_2, t) \right\} dx_2 dt = \end{aligned}$$

(\*) Istituto Matematico del Politecnico di Milano.

Lavoro eseguito nell'ambito dell'attività del Contratto di Ricerca « Equazioni Funzionali » del Comitato per la Matematica del C.N.R.

(\*\*) Nella seduta del 13 dicembre 1969.

$$\begin{aligned}
& - \int_0^T \int_0^l \{ \beta_1(x_1, t) (|u_2(x_1, 0, t)| u_2(x_1, 0, t) - |v_2(x_1, 0, t)| v_2(x_1, 0, t)) h_2(x_1, 0, t) + \\
& + \beta_2(x_1, t) (|u_2(x_1, k, t)| u_2(x_1, k, t) - |v_2(x_1, k, t)| v_2(x_1, k, t)) h_2(x_1, k, t) \} dx_1 dt.
\end{aligned}$$

Repeating the procedure followed to prove (3.37), it can be shown that, if  $\vec{u}(t)$  is a solution on  $0 \rightarrow T$ , then  $\vec{u}'(t) \in L^{4/3}(0 \rightarrow T; V_{\sigma-1})$  (see also Baiocchi [8], Lions [11])<sup>(1)</sup>. By a theorem of Strauss [12] we obtain therefore, setting in (4.1)  $\vec{h}(t) = \vec{w}(t)$  and bearing in mind that  $\vec{w}(0) = 0$ ,

$$\begin{aligned}
(4.2) \quad & \frac{1}{2} \|\vec{w}(t)\|_{V_0}^2 + \mu \int_0^t \|\vec{w}(\eta)\|_{V_1}^2 d\eta + \int_0^t (b(\vec{u}(\eta), \vec{u}(\eta), \vec{w}(\eta)) - \\
& - b(\vec{v}(\eta), \vec{v}(\eta), \vec{w}(\eta))) d\eta = \\
& = \int_0^t \int_0^k \frac{1}{2} \{ (-u_1^2(0, x_2, \eta) + v_1^2(0, x_2, \eta)) w_1(0, x_2, \eta) + \\
& + (u_1^2(l, x_2, \eta) - v_1^2(l, x_2, \eta)) w_1(l, x_2, \eta) \} dx_2 d\eta - \\
& - \int_0^t \int_0^k \{ \beta_1(x_1, \eta) (|u_2(x_1, 0, \eta)| u_2(x_1, 0, \eta) - |v_2(x_1, 0, \eta)| v_2(x_1, 0, \eta)) w_2(x_1, 0, \eta) + \\
& + \beta_2(x_1, \eta) (|u_2(x_1, k, \eta)| u_2(x_1, k, \eta) - |v_2(x_1, k, \eta)| v_2(x_1, k, \eta)) w_2(x_1, k, \eta) \} dx_1 d\eta.
\end{aligned}$$

Observe that the last integral on the right hand side of (4.2) is, by the assumptions made,  $\geq 0$ . Hence

$$\begin{aligned}
(4.3) \quad & \|\vec{w}(t)\|_{V_0}^2 + 2\mu \int_0^t \|\vec{w}(\eta)\|_{V_1}^2 d\eta \leq 2 \int_0^t |b(\vec{u}(\eta), \vec{u}(\eta), \vec{w}(\eta)) - \\
& - b(\vec{v}(\eta), \vec{v}(\eta), \vec{w}(\eta))| d\eta + \\
& + \int_0^t \int_0^k \{ |u_1(0, x_2, \eta) + v_1(0, x_2, \eta)| w_1^2(0, x_2, \eta) + \\
& + |u_1(l, x_2, \eta) + v_1(l, x_2, \eta)| w_1^2(l, x_2, \eta) \} dx_2 d\eta.
\end{aligned}$$

On the other hand,

$$(4.4) \quad |b(\vec{u}, \vec{u}, \vec{w}) - b(\vec{v}, \vec{v}, \vec{w})| \leq |b(\vec{w}, \vec{v}, \vec{w})| + |b(\vec{u}, \vec{w}, \vec{w})|$$

(1) Per tutte le citazioni bibliografiche vedi Nota I, questi «Rendiconti», vol. XLVIII, fasc. 1, p. 26 (1970).

and, by an inequality of Ladyzenskaja,

$$(4.5) \quad |b(\vec{w}, \vec{v}, \vec{w})| \leq \|w\|_{L^4(\Omega)} \|\vec{v}\|_{H^1(\Omega)} \|\vec{w}\|_{L^4(\Omega)} \leq \sqrt{2} \|\vec{v}\|_{H^1(\Omega)} \|\vec{w}\|_{L^2(\Omega)} \|\vec{w}\|_{H^1(\Omega)} \leq \\ \leq \frac{\mu}{4} \|\vec{w}\|_{V_1}^2 + c_\mu \|\vec{v}\|_{V_1}^2 \|\vec{w}\|_{V_0}^2.$$

Analogously, we have

$$(4.6) \quad |b(\vec{u}, \vec{w}, \vec{w})| \leq \|\vec{u}\|_{L^4(\Omega)} \|\vec{w}\|_{H^1(\Omega)} \|\vec{w}\|_{L^4(\Omega)} \leq \sqrt{2} \|\vec{u}\|_{L^4(\Omega)} \|\vec{w}\|_{H^1(\Omega)}^{3/2} \|\vec{w}\|_{L^2(\Omega)}^{1/2} \leq \\ \leq \frac{\mu}{4} \|\vec{w}\|_{V_1}^2 + c'_\mu \|\vec{u}\|_{L^4(\Omega)}^4 \|\vec{w}\|_{V_0}^2 \leq \frac{\mu}{4} \|\vec{w}\|_{V_1}^2 + c''_\mu \|\vec{u}\|_{V_0}^2 \|\vec{u}\|_{V_1}^2 \|\vec{w}\|_{V_0}^2.$$

Moreover, by the usual embedding theorems, bearing in mind that  $\vec{u}(t), \vec{v}(t)$  are  $V_\sigma$ -bounded, we obtain, since  $\sigma > 0$ ,

$$(4.7) \quad \int_0^k \{ |u_1(0, x_2, t) + v_1(0, x_2, t)| w_1^2(0, x_2, t) + \\ + |u_1(l, x_2, t) + v_1(l, x_2, t)| w_1^2(l, x_2, t) \} dx_2 \leq \\ \leq (\|\gamma_0 \vec{u}(t)\|_{L^2(\Gamma)} + \|\gamma_0 \vec{v}(t)\|_{L^2(\Gamma)}) \|\gamma_0 \vec{w}(t)\|_{L^4(\Gamma)}^2 \leq \\ \leq c_1 (\|\vec{u}(t)\|_{H^{(1+\sigma)/2}(\Omega)} + \|\vec{v}(t)\|_{H^{(1+\sigma)/2}(\Omega)}) \|\vec{w}(t)\|_{H^{3/4}(\Omega)} \leq \\ \leq c_2 (\|\vec{u}(t)\|_{V_\sigma}^{1/2} \|\vec{u}(t)\|_{V_1}^{1/2} + \|\vec{v}(t)\|_{V_\sigma}^{1/2} \|\vec{v}(t)\|_{V_1}^{1/2}) \|\vec{w}(t)\|_{V_0}^{1/2} \|\vec{w}(t)\|_{V_1}^{3/2} \leq \\ \leq c_3 (\|\vec{u}(t)\|_{V_1}^{1/2} + \|\vec{v}(t)\|_{V_1}^{1/2}) \|\vec{w}(t)\|_{V_0}^{1/2} \|\vec{w}(t)\|_{V_1}^{3/2} \leq \\ \leq c_3 (\|\vec{u}(t)\|_{V_1}^{1/2} + \|\vec{v}(t)\|_{V_1}^{1/2}) \left[ \frac{\mu}{c_3} (\|\vec{u}(t)\|_{V_1}^{1/2} + \|\vec{v}(t)\|_{V_1}^{1/2})^{-1} \|\vec{w}(t)\|_{V_1}^2 + \right. \\ \left. + \frac{c_3^3}{\mu^3} (\|\vec{u}(t)\|_{V_1}^{1/2} + \|\vec{v}(t)\|_{V_1}^{1/2})^3 \|\vec{w}(t)\|_{V_0}^2 \right] \leq \\ \leq \mu \|\vec{w}(t)\|_{V_1}^2 + c_4 (\|\vec{u}(t)\|_{V_1}^2 + \|\vec{v}(t)\|_{V_1}^2) \|\vec{w}(t)\|_{V_0}^2.$$

Hence, by (4.4), (4.5), (4.6), (4.7),

$$(4.8) \quad 2 |b(\vec{u}(t), \vec{u}(t), \vec{w}(t)) - b(\vec{v}(t), \vec{v}(t), \vec{w}(t))| + \\ + \int_0^k \{ |u_1(0, x_2, t) + v_1(0, x_2, t)| w_1^2(0, x_2, t) + \\ + |u_1(l, x_2, t) + v_1(l, x_2, t)| w_1^2(l, x_2, t) \} dx_2 \leq \\ \leq 2\mu \|\vec{w}(t)\|_{V_1}^2 + c_5 (\|\vec{u}(t)\|_{V_1}^2 + \|\vec{v}(t)\|_{V_1}^2) \|\vec{w}(t)\|_{V_0}^2.$$

Since  $\vec{u}(t), \vec{v}(t) \in L^2(\Omega \cap T; V_1)$ , we have

$$(4.9) \quad \|\vec{u}(t)\|_{V_1}^2 + \|\vec{v}(t)\|_{V_1}^2 = \chi(t) \in L^1(\Omega \cap T).$$

Introducing (4.8), (4.9) into (4.3) we obtain

$$\|\vec{w}(t)\|_{V_0}^2 \leq c_5 \int_0^t \chi(\eta) \|\vec{w}(\eta)\|_{V_0}^2 d\eta,$$

from which follows that  $\|\vec{w}(t)\|_{V_0} = 0$ .

The theorem is therefore proved.

5. By a similar procedure to that followed in the preceding paragraphs it is possible to give existence and uniqueness theorems for the solutions of problems which are slightly different from the one so far considered.

We can in this way prove a uniqueness and existence (in the small) theorem of the solution satisfying the initial condition (3.1) and the boundary conditions (3.4), (3.5), (3.6) and

$$(5.1) \quad \begin{aligned} p(0, x_2, t) &= \alpha_1(x_2, t) \\ p(l, x_2, t) &= \alpha_2(x_2, t) \end{aligned}$$

or

$$(5.2) \quad \begin{aligned} u_1(0, x_2, t) &= \alpha_1(x_2, t) \\ u_1(l, x_2, t) &= \alpha_2(x_2, t). \end{aligned}$$

It is, in other words, possible to assign on the initial and final sections the values of the pressure or of the velocity.

If, instead of system (1.1), we consider the linearized Navier-Stokes system

$$(5.3) \quad \begin{cases} \frac{\partial u_j}{\partial t} - \mu \Delta u_j + \frac{\partial p}{\partial x_j} = f_j & (j = 1, 2) \\ \sum_{k=1}^2 \frac{\partial u_k}{\partial x_k} = 0, \end{cases}$$

then the existence and uniqueness of a solution satisfying the initial condition (3.1) and the boundary conditions (3.4), (3.5), (3.6), (5.1) or (3.4), (3.5), (3.6), (5.2) can be proved in the large, that is on the whole interval  $\Omega \cap T$ .

Observe, finally, that, if we consider the linearized system, conditions (3.4), (3.5) may be substituted by the following, more general, ones

$$(5.4) \quad \begin{aligned} p(x_1, 0, t) &= -\beta_1(x_1, t) \rho_1(u_2(x_1, 0, t)), \\ p(x_1, k, t) &= \beta_2(x_1, t) \rho_2(u_2(x_1, k, t)), \end{aligned}$$

where  $\rho_i(\xi)$  ( $i = 1, 2$ ) are continuous functions of  $\xi \in -\infty \rightarrow \infty$ , non-decreasing, with  $\rho_i(0) = 0$  and such that

$$v_1 |\xi|^\sigma \leq \xi \rho_i(\xi) \leq v_2 |\xi|^\sigma,$$

$v_1$  and  $v_2$  being positive constants and  $\sigma \geq 1$ .