
ATTI ACCADEMIA NAZIONALE DEI LINCEI
CLASSE SCIENZE FISICHE MATEMATICHE NATURALI
RENDICONTI

ADI BEN-ISRAEL, MICHAEL J. L. KIRBY

**A Characterization of Equilibrium Points of
Bimatrix Games**

*Atti della Accademia Nazionale dei Lincei. Classe di Scienze Fisiche,
Matematiche e Naturali. Rendiconti, Serie 8, Vol. **46** (1969), n.4, p. 402–407.*

Accademia Nazionale dei Lincei

<http://www.bdim.eu/item?id=RLINA_1969_8_46_4_402_0>

L'utilizzo e la stampa di questo documento digitale è consentito liberamente per motivi di ricerca e studio. Non è consentito l'utilizzo dello stesso per motivi commerciali. Tutte le copie di questo documento devono riportare questo avvertimento.

Ricerca operativa. — *A Characterization of Equilibrium Points of Bimatrix Games.* Nota di ADI BEN-ISRAEL e MICHAEL J. L. KIRBY, presentata dal Socio B. SEGRE.

RIASSUNTO. — I punti di equilibrio dei giochi bimatriziali vengono qui caratterizzati da certe sottomatrici della matrice di retribuzione.

NOTATIONS AND PRELIMINARIES. — We denote by:

\mathbb{R}^n = the n -dimensional real vector space,

$\mathbb{R}_+^n = \{x \in \mathbb{R}^n : x \geq 0\}$ the nonnegative orthant in \mathbb{R}^n ,

e = the vector whose components are all 1 and whose dimension is to be determined by the context,

$M = \{1, 2, \dots, m\}$,

$N = \{1, 2, \dots, n\}$.

For any subsets $I \subset M$, $J \subset N$, let

$$\bar{I} = \{i : i \in M, i \notin I\}, \quad \bar{J} = \{j : j \in N, j \notin J\}.$$

For any $m \times n$ real matrix

$$A = (a_{ij}) \quad i \in M, j \in N,$$

define the submatrix

$$A(I/J) = (a_{ij}) \quad i \in I, j \in J.$$

For any vector $x = (x_i) \in \mathbb{R}^m$, define the subvector

$$x(I) = (x_i), \quad i \in I.$$

For any subspace L of \mathbb{R}^n , P_L denotes the perpendicular projection on L .

For any $m \times n$ real matrix A denote by

$R(A)$ the range space of A ,

$N(A)$ the null space of A ,

A^T the transpose of A ,

A^+ the generalized inverse of A , [8].

We recall from [2] that

$$x = A^+ b + N(A)$$

is the general solution of

$$Ax = b$$

whenever solvable; also

$$A^{+T} = A^{T+} \quad \text{and} \quad AA^+ = P_{R(A)}.$$

(*) Nella seduta del 19 aprile 1969.

A *bimatrix game* is a two person game defined by two $m \times n$ matrices $A = (a_{ij})$, $B = (b_{ij})$ so that if player I chooses $i \in M$ and player II chooses $j \in N$ then the payoffs are a_{ij} to player I and b_{ij} to player II. Without loss of generality the matrices A , B can be taken to be positive matrices, [5]. A point $(x, y) \in R^{m+n}$ is an *equilibrium point* of the bimatrix game (A, B) if and only if (x, y) satisfies

$$(1a) \quad x \in R_+^m, \quad e^T x = 1,$$

$$(1b) \quad y \in R_+^n, \quad e^T y = 1,$$

$$(2a) \quad B^T x \leq (x^T B y) e,$$

$$(2b) \quad A y \leq (x^T A y) e.$$

Equilibrium points of bimatrix games, whose existence was first proved by Nash [7], were further studied in [3], [4], [5] and [6].

(1) and (2) imply the following complementary slackness conditions

$$(3a) \quad x^T [Ay - (x^T A y) e] = 0,$$

$$(3b) \quad y^T [B^T x - (x^T B y) e] = 0.$$

RESULTS. – Equilibrium points of a bimatrix game are characterized in the following

THEOREM:

Assumptions: Let A, B be positive $m \times n$ matrices and let $x \in R_+^m$, $y \in R_+^n$.

Conclusions: (x, y) is an equilibrium point for the bimatrix game (A, B) if and only if there are sets $I \subset M$, $J \subset N$ for which the following 8 conditions are satisfied.

$$(4) \quad e = A(I/J)u \quad \text{for some } u \geqq 0,$$

$$(5) \quad e = B(I/J)^T v \quad \text{for some } v \geqq 0,$$

$$(6) \quad x(\bar{I}) = 0,$$

$$(7) \quad y(\bar{J}) = 0,$$

$$(8) \quad x(I) = B(I/J)^{T+} e \left[\frac{1 - e^T w}{e^T B(I/J)^+ e} \right] + w, \quad \text{for some } w \in N(B(I/J)^T),$$

$$(9) \quad y(J) = A(I/J)^+ e \left[\frac{1 - e^T z}{e^T A(I/J)^+ e} \right] + z, \quad \text{for some } z \in N(A(I/J)),$$

$$(10) \quad B(I/N)^T x(I) \leqq \left[\frac{1 - e^T w}{e^T B(I/J)^+ e} \right] e,$$

$$(11) \quad A(M/J) y(J) \leqq \left[\frac{1 - e^T z}{e^T A(I/J)^+ e} \right] e.$$

Proof. - I. *If:*

First we show that for the z defined by (9), $e^T z \neq 1$. For if $e^T z = 1$, then (11) implies that $y(J) = 0$ (since A is positive), so by (9) $z = 0$ contradicting $e^T z = 1$.

Now we show that y , satisfying (7) and (9), is a probability vector:

$$\begin{aligned} e^T y &= e^T y(J) && \text{by (7)} \\ &= 1 && \text{by (9).} \end{aligned}$$

Hence

(1 b) is satisfied.

(1 a) is similarly proved.

To prove (2 b) we calculate

$$\begin{aligned} (12) \quad x^T A y &= x(I)^T A(I/J) y(J) && \text{by (6), (7)} \\ &= x(I)^T A(I/J) A(I/J)^+ e \left[\frac{I - e^T z}{e^T A(I/J)^+ e} \right] + x(I)^T A(I/J) z && \text{by (9)} \\ &= x(I)^T e \left[\frac{I - e^T z}{e^T A(I/J)^+ e} \right] && \text{since } z \in N(A(I/J)), \text{ (4) and} \\ &&& A(I/J) A(I/J)^+ = P_{R(A(I/J))} \\ &= \frac{I - e^T z}{e^T A(I/J)^+ e} && \text{by (1 a) and (6)} \end{aligned}$$

(2 b) follows now from (11) and (12)

(2 a) is similarly proved.

2. *Only if:*

Let (x, y) be an equilibrium point and define

$$(13) \quad I = \left\{ i : \sum_{j=1}^n a_{ij} y_j = x^T A y \right\}$$

$$(14) \quad J = \left\{ j : \sum_{i=1}^m b_{ij} x_i = x^T B y \right\}.$$

Both I, J are nonempty since I empty implies that

$$Ay < (x^T A y) e$$

which implies by using (1 a) that

$$x^T A y < x^T A y, \quad \text{a contradiction.}$$

(6) and (7) follow from (2) (3) and the definitions (13) (14).

Using (7) and (13) we get

$$(15) \quad A(I/J) y(J) = (x^T A y) e$$

which proves (4) since $y(J) \geq 0$, $x^T A y > 0$. (5) is similarly proved. The general solution of (15) is

$$(16) \quad y(z) = A(I/J)^+ e (x^T A y) + z, \quad \text{for some } z \in N(A(I/J)).$$

But

$$\begin{aligned} I &= e^T y \\ &= e^T y(J), \quad \text{by (7)} \\ &= e^T A(I/J)^+ e (x^T A y) + e^T z. \end{aligned}$$

In general, $A(I/J)$ positive does not imply that $e^T A(I/J)^+ e \neq 0$. For example

$$A(I/J) = \begin{pmatrix} 3 & 1 \\ 4 & 2 \end{pmatrix}, \quad A(I/J)^+ = \frac{1}{2} \begin{pmatrix} 2 & -1 \\ -4 & 3 \end{pmatrix}.$$

Since a positive constant may be added to all elements of A and B without changing the equilibrium points, it can thus be assumed without loss of generality that

$$e^T A(I/J)^+ e \neq 0, \quad \text{by (16)}$$

so

$$x^T A y = \frac{I - e^T z}{e^T A(I/J)^+ e}$$

which when inserted in (16) and (26) gives (9) and (11) respectively. (8) and (10) are similarly proved. *Q.E.D.*

Remarks.

1. An important special class of bimatrix games are 2-person 0-sum games, in which case

$$(17) \quad B = -A.$$

Then $e^T w = 0$ in (8) and $e^T z = 0$ in (9), since in this case

$$\begin{aligned} e &\in R(A(I/J)) \quad \text{by (7)}, \\ e &\in R(A(I/J)^T) \quad \text{by (5) and (17)}, \\ w &\in N(A(I/J)^T) \quad \text{by (8) and (17)}, \\ z &\in N(A(I/J)) \quad \text{by (9)}. \end{aligned}$$

We use here the fact that for any matrix A , $R(A)$ and $N(A^T)$ are orthogonal subspaces.

For 2-person 0-sum games the theorem of [1] is thus a corollary of our theorem. In particular, the value of the game is then $\frac{1}{e^T A(I/J)^+ e}$.

2. In general $e^T w$ and $e^T z$ are not zero, as shown by the following example. Let

$$A = \begin{pmatrix} 1 & 2 \\ \frac{1}{2} & \frac{1}{2} \end{pmatrix} \quad B = \begin{pmatrix} 1 & 1 \\ \frac{1}{2} & \frac{1}{2} \end{pmatrix}$$

then $(x, y) = \left(\begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} \alpha \\ 1-\alpha \end{pmatrix} \right)$ is an equilibrium point for all $0 \leq \alpha \leq 1$. For $0 < \alpha < 1$ (13) and (14) give

$$I = \{1\} \quad , \quad J = \{1, 2\}$$

and the submatrices $A(I/J)$, $B(I/J)$ are

$$A(I/J) = (1 \ 2) \quad , \quad B(I/J) = (1 \ 1)$$

with

$$A(I/J)^+ = \frac{1}{5} \begin{pmatrix} 1 \\ 2 \end{pmatrix} \quad , \quad B(I/J)^+ = \frac{1}{2} \begin{pmatrix} 1 \\ 1 \end{pmatrix}.$$

Now z defined by (9) is of the form

$$z = \begin{pmatrix} 2\beta \\ -\beta \end{pmatrix} \text{ for some real } \beta, \text{ since } z \in N(A(I/J)).$$

But (9) gives:

$$\begin{aligned} y(J) &= \begin{pmatrix} \alpha \\ 1-\alpha \end{pmatrix} = A(I/J)^+ e \left[\frac{1-e^T z}{e^T A(I/J)^+ e} \right] + z \\ &= \frac{1}{5} \begin{pmatrix} 1 \\ 2 \end{pmatrix} \frac{1-\beta}{\left(\frac{3}{5}\right)} + \begin{pmatrix} 2\beta \\ -\beta \end{pmatrix} \\ &= \begin{pmatrix} \frac{1}{3} + \frac{5}{3}\beta \\ \frac{2}{3} - \frac{5}{3}\beta \end{pmatrix}, \end{aligned}$$

so that $\beta = \frac{3}{5}\alpha - \frac{1}{5}$, and $\beta \neq 0$ if $\alpha \neq \frac{1}{3}$ in which case $e^T z = \beta \neq 0$. In this example, however, $w = 0$ since

$$N(B(I/J)^T) = \{0\}.$$

The payoffs to the players at the equilibrium point $\left(\begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} \alpha \\ 1-\alpha \end{pmatrix} \right)$ are thus

$$x^T A(I/J) y = \frac{1-e^T z}{e^T A(I/J)^+ e} = 2 - \alpha \quad , \quad x^T B(I/J) y = \frac{1-e^T w}{e^T B(I/J)^+ e} = 1$$

to players I and II respectively.

For $\alpha = 0$ or 1 the set J is $\{2\}$ or $\{1\}$ respectively. This illustrates the nonuniqueness of the equilibrium points and the nonuniqueness of the corresponding payoffs to each player.

3. Any equilibrium point (x, y) corresponds, via the conditions (4)–(11), to two index sets $I \subset M$ and $J \subset N$. The corresponding submatrices $A(I/J)$ and $B(I/J)$, which are the essential parts of the payoff matrices A and B at the given equilibrium point, satisfy (4) and (5) (among other conditions). This fact may be used in excluding certain submatrices from consideration as possible optimal $A(I/J)$ or $B(I/J)$. For instance, in the above example, mixed strategies are excluded for player I since the matrix.

$$A = \begin{pmatrix} 1 & 2 \\ 1 & 1 \\ \frac{1}{2} & \frac{1}{2} \end{pmatrix}$$

does not satisfy (4).

4. Extreme equilibrium points, e.g. [6], may be characterized in the same way that basic optimal strategies were characterized in [9] and in corollaries 1 and 2 of [1].

Acknowledgement: Part of the research was undertaken for the U. S. Army Research Office—Durham, Contract No. Da-31-124-ARO-D-322, and for the National Science Foundation, Project GP 7550 at Northwestern University in Evanston, Illinois.

REFERENCES.

- [1] BEN-ISRAEL, A., *On optimal solutions of 2-person o-sum games*, « Rend. Acc. Lincei », ser. VIII, Vol. XLIV, fasc. 4, 274–278 (1968).
- [2] BEN-ISRAEL, A. and A. CHARNE, *Contributions to the theory of generalized inverses*, « J. Soc. Indust. Appl. Math. », II, nr. 3, 667–699 (1963).
- [3] KUHN, H. W., *An algorithm for equilibrium points in bimatrix games*, « Proc. Nat. Acad. Sci U.S.A. », 47, 1657–1662 (1961).
- [4] LEMKE, C. E., *Bimatrix equilibrium points and mathematical programming*, « Management Sci. » II, 681–689 (1965).
- [5] LEMKE, C. E., and J. T. HOWSON, Jr., *Equilibrium points of bimatrix games*, « J. Soc. Indust. Appl. Math. » 12, nr. 2, 413–423 (1964).
- [6] MANGASARIAN, O. L., *Equilibrium points of bimatrix games*, « J. Soc. Indust. Appl. Math. » 12, nr. 4, 778–780 (1964).
- [7] NASH, J. F., *Noncooperative games*, « Ann. Math. » 54, 286–295 (1951).
- [8] PENROSE, R., *A generalized inverse for matrices*, « Proc. Cambridge Philos. Soc. » 51, 406–413 (1955).
- [9] SHAPLEY, L. S. and R. N. SNOW, *Basic solutions of discrete games* pp. 27–35 in « Contributions to the Theory of Games » Vol. I (edited by H. W. Kuhn and A. W. Tucker) Princeton University Press, Princeton, N. J. 1950.