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ATTI ACCADEMIA NAZIONALE DEI LINCEI  
CLASSE SCIENZE FISICHE MATEMATICHE NATURALI  
**RENDICONTI**

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**The projective transformation in a Finster space**

*Atti della Accademia Nazionale dei Lincei. Classe di Scienze Fisiche,*

*Matematiche e Naturali. Rendiconti, Serie 8, Vol. **43** (1967), n.6, p. 480–484.*

Accademia Nazionale dei Lincei

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**Geometria differenziale.** — *The projective transformation in a Finsler space.* Nota di H. D. PANDE, presentata<sup>(\*)</sup> dal Socio E. BOMPIANI.

**RIASSUNTO.** — Si considerano le trasformazioni proiettive (cioè che conservano le geodetiche) di uno spazio di Finsler, si studia il modo di alterarsi dei parametri di una congruenza per una tale trasformazione, e si dimostra che la connessione indotta su una varietà immersa in quello spazio subisce pure una trasformazione proiettiva.

### I. INTRODUCTION.

Let  $F_n$  be an  $n$ -dimensional Finsler space equipped with the positively homogeneous metric function  $F(x, \dot{x})$  of degree one in its directional arguments. The entities ([1], page 13, (3.1)).

$$(1.1) \quad g_{ij}(x, \dot{x}) \stackrel{\text{def}}{=} \frac{1}{2} \partial_i \partial_j F^2(x, \dot{x}) \quad (1), \quad (2)$$

form the covariant components of the metric tensor of  $F_n$ . They are symmetric directional arguments and

$$(1.2) \quad g^{ij}(x, \dot{x}) g_{jk}(x, \dot{x}) = \delta_k^i \begin{cases} 1 & \text{if } k = i \\ 0 & \text{if } k \neq i. \end{cases}$$

The covariant components of the unit vector along the direction of the element of support  $(x^i, \dot{x}^i)$  are given by ([1], page 69 (1.15'))

$$(1.3) \quad l_i(x, \dot{x}) = \partial_i F(x, \dot{x}).$$

The covariant derivative of a vector  $X^i(x, \dot{x})$ , depending on the element of support, with respect to  $\dot{x}^k$  in the sense of Cartan is given by [1], Chap. III

$$(1.4) \quad X_{|k}^i(x, \dot{x}) = (\partial_k X^i) - (\partial_j X^i) G_k^j + X^j \Gamma_{jk}^{*i},$$

where

$$(1.5)a \quad G_k^j(x, \dot{x}) \stackrel{\text{def}}{=} \partial_k G^i(x, \dot{x}),$$

$$(1.5)b \quad 2 G^i(x, \dot{x}) = \gamma_{jk}^i(x, \dot{x}) \dot{x}^j \dot{x}^k,$$

$\gamma_{jk}^i(x, \dot{x})$  being the Christoffel symbols of second kind ([1], page 59, (27) and (23)) and  $\Gamma_{jk}^{*i}(x, \dot{x})$  are the Cartan connection coefficients symmetrical

(\*) Nella seduta del 9 dicembre 1967.

(1)  $\partial_i = \partial/\partial x^i$  and  $\dot{\partial}_i = \partial/\partial \dot{x}^i$ ; Latin indices run from 1 to  $n$ .

(2) Numbers in brackets refer to the references at the end of the paper.

in their lower indices and homogeneous of degree zero in their directional arguments. We have ([1], Ch. III)

$$(1.6) \quad G_{jk}^i(x, \dot{x}) x^j = \Gamma_{jk}^{*i}(x, \dot{x}) \dot{x}^j = G_k^i(x, \dot{x}),$$

where  $G_{jk}^i(x, \dot{x}) \stackrel{\text{def}}{=} \partial_k G_j^i(x, \dot{x})$ .

Let  $\lambda_{(a)} \{a = 1, 2, \dots, n\}$  be the unit tangents of  $n$ -congruences of an orthogonal enneple. The subscript ' $a$ ' in the parenthesis simply distinguishes one congruence from the other. The covariant and contravariant components of  $\lambda_{(a)}$  will respectively be denoted by  $\lambda_{(a)}^i$  and  $\lambda_{(a)i}$ . Since  $n$ -congruences are mutually orthogonal, we have [2]

$$(1.7) \quad g_{ij}(x, \dot{x}) \lambda_{(a)}^i \lambda_{(b)}^j = \delta_{ab},$$

where the Kronecker delta  $\delta_{ab} = \begin{cases} 1, & \text{if } a = b \\ 0, & \text{if } a \neq b \end{cases}$ . We have the Ricci coefficients of rotation, given by [2, 3]

$$(1.8) \quad Y_{abc}(x, \dot{x}) \stackrel{\text{def}}{=} \lambda_{(a)|j}^i \lambda_{(b);j}^l \lambda_{(c)}^j,$$

where the symbol  $|$  denotes the covariant derivative with respect to  $x^k$  in the sense of Cartan and

$$(1.9) \quad \mu_{(m)}^i(x, \dot{x}) \stackrel{\text{def}}{=} \sum_h Y_{mhk} \lambda_{(h)}^i.$$

The geometric entities  $\mu_{(m)}^i(x, \dot{x})$  are called the first curvature vector of a curve of a congruence in Finsler space [3].

## 2. PROJECTIVE TRANSFORMATION.

The differential equation of a geodesic

$$(2.1) \quad \frac{d^2 x^i}{ds^2} + \Gamma_{jk}^{*i}(x, dx/ds) \frac{dx^j}{ds} \frac{dx^k}{ds} = 0$$

assumes the following form by the transformation of its parameter  $s$  to  $t$  [4]:

$$(2.2) \quad \dot{x}^i \left\{ \frac{d^2 x^i}{dt^2} + \Gamma_{jk}^{*i}(x, \dot{x}) \dot{x}^j \dot{x}^k \right\} - \dot{x}^i \left\{ \frac{d^2 x^i}{dt^2} + \Gamma_{jk}^{*i}(x, \dot{x}) \dot{x}^j \dot{x}^k \right\} = 0,$$

where

$$(2.3) \quad \Gamma_{jk}^{*i}(x, \dot{x}) = \Gamma_{kj}^{*i}(x, \dot{x}).$$

The equation (2.2) remains unchanged if we replace the Cartan connection coefficient  $\Gamma_{jk}^{*i}(x, \dot{x})$  by a new symmetric coefficient  $\bar{\Gamma}_{jk}^{*i}(x, \dot{x})$ , given by

$$(2.4) \quad \bar{\Gamma}_{jk}^{*i}(x, \dot{x}) \stackrel{\text{def}}{=} \Gamma_{jk}^{*i}(x, \dot{x}) + 2 \delta_{(j}^i p_{k)} + p_{jk} \dot{x}^i,$$

where  $p_k(x, \dot{x})$  is a covariant vector, positively homogeneous of degree zero in its directional arguments and

$$(2.5) \quad p_{jk}(x, \dot{x}) \stackrel{\text{def}}{=} \partial_j p_k(x, \dot{x}).$$

*Definition 2.1.* Let  $F_n$  and  $\bar{F}_n$  be two spaces with fundamental tensors  $g_{ij}(x, \dot{x})$  and  $\bar{g}_{ij}(x, \dot{x})$  at the corresponding points. Then the spaces are said to be in geodesic correspondence if their geodesics are the same and we shall call (2.4) a "projective change" of the Cartan function  $\Gamma_{jk}^{*i}(x, \dot{x})$ .

Contracting (2.4) with respect to the indices  $i$  and  $j$ , we get

$$(2.6) \quad \bar{\Gamma}_{hk}^{*h}(x, \dot{x}) = \Gamma_{hk}^{*h}(x, \dot{x}) + (n+1)p_k.$$

Differentiating (2.6) with respect to  $x^l$ , we obtain

$$(2.7) \quad \dot{\partial}_l \bar{\Gamma}_{hk}^{*h}(x, \dot{x}) = \dot{\partial}_l \Gamma_{hk}^{*h}(x, \dot{x}) + (n+1)p_{lk}.$$

*Theorem 2.1.* If  $\mu_{(a)}$  and  $\mu_{(a)i}$  are the contravariant and covariant components of the first curvature vector of a curve of congruence then the following geometric entities are invariant under the projective change:

$$(2.8) \quad T_{(a)}^i \stackrel{\text{def}}{=} \mu_{(a)}^i - \frac{1}{n+1} \{ 2g^{ki} \Gamma_{hi}^{*h} + g^{kj} \partial_j \Gamma_{hk}^{*h} \dot{x}^i \}$$

and

$$(2.9) \quad T_{(a)i} \stackrel{\text{def}}{=} \mu_{(a)i} - \frac{1}{n+1} \{ 2\Gamma_{hi}^{*h} + g^{kj} g_{li} \dot{x}^j \partial_j \Gamma_{hk}^{*h} \}.$$

*Proof.* If  $\lambda_{(a)|\bar{k}}$  denotes the covariant derivative of  $\lambda_{(a)}$  in the sense of Cartan under the projective change, then we have

$$(2.10) \quad \lambda_{(a)|\bar{k}}^i = \partial_{\bar{k}} \lambda_{(a)}^i + \lambda_{(a)}^j \Gamma_{jk}^{*i}(x, \dot{x}).$$

Hence we get in consequence of (2.4)

$$(2.11) \quad \lambda_{(a)|\bar{k}}^i - \lambda_{(a)|k}^i = \lambda_{(a)}^j \{ 2\delta_{(j}^i p_{k)} + p_{jk} \dot{x}^i \}.$$

With the help of equations (2.6) and (2.7) the above equation assumes the form

$$(2.12) \quad \lambda_{(a)|\bar{k}}^i - \lambda_{(a)|k}^i = \frac{1}{n+1} [\lambda_{(a)}^j \{ \delta_{(j}^i (\bar{\Gamma}_{hk}^{*h} - \Gamma_{hk}^{*h}) + \delta_{k}^i (\bar{\Gamma}_{hj}^{*h} - \Gamma_{hj}^{*h}) + \dot{x}^i \partial_j (\bar{\Gamma}_{hk}^{*h} - \Gamma_{hk}^{*h}) \} ].$$

Multiplying (2.12) by  $\lambda_{(a)}^k$  and using the orthogonality condition (1.7), we obtain

$$(2.13) \quad \begin{aligned} \mu_{(a)}^i &= \frac{1}{n+1} \{ g^{ki} \bar{\Gamma}_{hk}^{*h} + g^{ij} \bar{\Gamma}_{hj}^{*h} + g^{kj} \dot{x}^i \partial_j \bar{\Gamma}_{hk}^{*h} \} = \\ &= \mu_{(a)}^i - \frac{1}{n+1} \{ g^{ki} \Gamma_{hk}^{*h} + g^{ij} \Gamma_{hj}^{*h} + g^{kj} \dot{x}^i \partial_j \Gamma_{hk}^{*h} \}, \end{aligned}$$

where

$$(2.14) \quad \bar{\mu}_{(a)}^i \stackrel{\text{def}}{=} \lambda_{(a)|\bar{k}}^i \lambda_{(a)}^k.$$

Again multiplying (2.12) by the product  $\lambda_{(a)}^k g_{il}$  and using (1.7), we get

$$(2.15) \quad \begin{aligned} \bar{\mu}_{(a)l} &= \frac{1}{n+1} \{ 2 \bar{\Gamma}_{hl}^{*h} + g^{kj} g_{il} x^i \partial_j \bar{\Gamma}_{hk}^{*h} \} = \\ &= \mu_{(a)l} - \frac{1}{n+1} \{ 2 \Gamma_{hl}^{*h} + g^{kj} g_{il} x^i \partial_j \Gamma_{hk}^{*h} \}, \end{aligned}$$

where

$$(2.16) \quad \bar{\mu}_{(a)l} \stackrel{\text{def}}{=} \lambda_{(a)|\bar{k}}^i \lambda_{(a)}^k g_{il}.$$

**THEOREM 2.2.** *The necessary and sufficient condition, that a curve of congruence whose unit tangent is  $\lambda_{(l)}$  satisfies the relation  $\mu_{(l)} = 0$ , is that*

$$(2.17) \quad \Gamma_{ij}^{*j}(x, \dot{x}) - \lambda_{(l)}^j \partial_j \lambda_{(l)i} = 0$$

holds.

*Proof.* In consequence of (1.8) and (1.9), we get, using the relation  $\mu_{(l)} = 0$

$$(2.18) \quad \{ \partial_j \lambda_{(l)i} - \lambda_{(l)m} \Gamma_{ij}^{*m} \} \lambda_{(h)}^i \lambda_{(h)}^j \lambda_{(h)} = 0,$$

which yields, in view of (1.7) that

$$(2.19) \quad \{ \partial_j \lambda_{(l)i} - \Gamma_{ij}^{*j} \} \lambda_{(h)}^i \lambda_{(h)} = 0.$$

Conversely, if the condition (2.17) is satisfied, it is obvious that

$$(2.20) \quad \mu_{(l)}^i = 0.$$

### 3. PROJECTIVE CHANGE OF THE INDUCED CONNECTION IN THE SUBSPACE OF A FINSLER SPACE.

An  $m$ -dimensional subspace  $F_m$  of a Finsler space  $F_n$  is represented parametrically by the equations

$$(3.1) \quad x^i = x^i(u^\alpha) \quad (3),$$

We suppose that the variables  $u^\alpha$  form a co-ordinate system of  $F_m$ . We further assume that the functions (3.1) are of class  $c^4$  ([1], page 155) and we put

$$(3.2) \quad B_a^i \stackrel{\text{def}}{=} \partial x^i / \partial u^\alpha.$$

The induced connection parameters are expressed as in [1], page 159

$$(3.3) \quad \Gamma_{\beta\gamma}^{*\alpha} = B_\beta^a (B_{\beta\gamma}^i + \Gamma_{hk}^{*i} B_{\beta\gamma}^{hk}),$$

(3) Latin indices run from 1 to  $n$ , Greek indices from 1 to  $n$ .

where

$$(3.4) \quad B_{\beta\gamma}^i \stackrel{\text{def}}{=} \frac{\partial^2 x^i}{\partial u^\beta \partial u^\gamma},$$

and

$$(3.5) \quad B_{\alpha\beta}^{hk} = B_\alpha^h B_\beta^k.$$

**THEOREM 3.1.** *When the connection  $\Gamma_{jk}^{*i}(x, \dot{x})$  of a Finsler space undergoes a projective change, the same is true of the induced connection of any subspace and*

$$(3.6) \quad \delta_\beta^\alpha \Phi_\gamma = B_\beta^\alpha p_k B_{\beta\gamma}^{hk},$$

where the vectors  $\Phi_\gamma(u, \dot{u})$  determine the projective transformation in the subspace.

*Proof.* Substituting the value of  $\Gamma_{jk}^{*i}(x, \dot{x})$  from (2.4), the equation (3.3) reduces to the form

$$(3.7) \quad \Gamma_{\beta\gamma}^{*a} + B_i^\alpha (2 \delta_{(k}^i p_{k)} + p_{hk} \dot{x}^i) B_{\beta\gamma}^{hk} = B_i^\alpha (B_{\beta\gamma}^i + \bar{\Gamma}_{hk}^{*i} B_{\beta\gamma}^{hk}).$$

If we put

$$(3.8) \quad \bar{\Gamma}_{\beta\gamma}^{*a}(u, \dot{u}) \stackrel{\text{def}}{=} \Gamma_{\beta\gamma}^{*a} + 2 \delta_{(\beta}^\alpha \Phi_{\gamma)} + \Phi_{\beta\gamma}(u, \dot{u}) \dot{u}^\alpha,$$

where  $\Phi_\gamma(u, \dot{u})$  are the covariant vectors positively homogeneous of zero degree in their directional argument, then the equation (3.7) becomes

$$(3.9) \quad \bar{\Gamma}_{\beta\gamma}^{*a} = B_i^\alpha (B_{\beta\gamma}^i + \bar{\Gamma}_{hk}^{*i} B_{\beta\gamma}^{hk}),$$

provided we have

$$(3.10)a \quad \delta_\beta^\alpha \Phi_\gamma = B_i^\alpha p_k \delta_h^i B_{\beta\gamma}^{hk}$$

and

$$(3.10)b \quad \Phi_{\beta\gamma} \dot{u}^\alpha = B_i^\alpha B_{\beta\gamma}^{hk} p_{hk} \dot{x}^i.$$

From (3.10)a it is clear that  $(m-n)$  independent vectors  $\Phi_\alpha(u, \dot{u})$  exist such that there is no change in the induced connection.

I am grateful to Professor R. S. Mishra for his kind help in the preparation of this paper.

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