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# The Existence and Multiplicity of Heteroclinic and Homoclinic Orbits for a Class of Singular Hamiltonian Systems in $\mathbb{R}^2$

## Joanna Janczewska

**Abstract.** – In this work we consider a class of planar second order Hamiltonian systems:  $\ddot{q} + \nabla V(q) = 0$ , where a potential V has a singularity at a point  $\xi \in \mathbb{R}^2$ :  $V(q) \to -\infty$ , as  $q \to \xi$  and the unique global maximum  $0 \in \mathbb{R}$  that is achieved at two distinct points  $a, b \in \mathbb{R}^2 \setminus \{\xi\}$ . For a class of potentials that satisfy a strong force condition introduced by W. B. Gordon [Trans. Amer. Math. Soc. 204 (1975)], via minimization of action integrals, we establish the existence of at least two solutions which wind around  $\xi$  and join  $\{a,b\}$  to  $\{a,b\}$ . One of them, Q, is a heteroclinic orbit joining a to b. The second is either homoclinic or heteroclinic possessing a rotation number (a winding number) different from Q.

# 1. - Introduction.

In this work we will be concerned with the existence and multiplicity of heteroclinic and homoclinic orbits for a class of autonomous second order Hamiltonian systems in  $\mathbb{R}^2$ ,

$$\ddot{q} + \nabla V(q) = 0,$$

where a potential V satisfies the following conditions:

- $(V_1)$  there exists  $\xi \in \mathbb{R}^2$  such that  $V \in C^1(\mathbb{R}^2 \setminus \{\xi\}, \mathbb{R})$ ,
- $(V_2)$   $\lim_{x\to \xi}V(x)=-\infty$ ,
- $(V_3)$  there is a neighbourhood  $\mathcal N$  of the point  $\xi$  and there is a function  $U \in C^1(\mathcal N \setminus \{\xi\}, \mathbb R)$  such that  $|U(x)| \to \infty$ , as  $x \to \xi$  and  $|\nabla U(x)|^2 \le -V(x)$  for all  $x \in \mathcal N \setminus \{\xi\}$ ,
- $(V_4)$   $V(x) \leq 0$  and there are two distinct points  $a, b \in \mathbb{R}^2 \setminus \{\xi\}$  such that V(x) = 0 if and only if  $x \in \{a, b\}$ ,
  - $(V_5)$  there is a negative constant  $V_0$  such that  $\limsup_{|x| \to \infty} V(x) \leq V_0$ .

In the literature,  $(V_3)$  is known as a strong force condition introduced by Gordon (see [9]). Here and subsequently,  $|\cdot|:\mathbb{R}^n\to[0,\infty)$  is the norm in  $\mathbb{R}^n$  induced by the standard inner product.

A solution  $q: \mathbb{R} \to \mathbb{R}^2$  of (1.1) is said to be *homoclinic* if  $q(-\infty) = a = q(\infty)$  or  $q(-\infty) = b = q(\infty)$ , where

$$q(\pm \infty) = \lim_{t \to \pm \infty} q(t).$$

We call a solution  $q: \mathbb{R} \to \mathbb{R}^2$  of (1.1) heteroclinic if  $q(-\infty) = a$  and  $q(\infty) = b$  or conversely.

Let E be given by

$$E = \left\{ q \in W^{1,2}_{\text{loc}}(\mathbb{R}, \mathbb{R}^2) : \int_{-\infty}^{\infty} |\dot{q}(t)|^2 dt < \infty \right\}.$$

It is known that E is the Hilbert space under the norm:

$$||q||_E^2 = \int_{-\infty}^{\infty} |\dot{q}(t)|^2 dt + |q(0)|^2.$$

We will consider the families of paths that omit  $\xi$  defined as follows:

$$egin{aligned} & \varLambda = \{q \in E \colon q(t) 
eq \xi & ext{ for all } t \in \mathbb{R}\}, \ & \varGamma = \{q \in \varLambda \colon q(-\infty) = a \ \land \ q(\infty) = b\}, \ & \varUpsilon = \{q \in \varLambda \colon q(-\infty) = b \ \land \ q(\infty) = a\}, \ & \Omega_a = \{q \in \varLambda \colon q(-\infty) = a = q(\infty)\}, \ & \Omega_b = \{q \in \varLambda \colon q(-\infty) = b = q(\infty)\}. \end{aligned}$$

Let's introduce the polar coordinate system in  $\mathbb{R}^2$  with the pole  $\xi$  and the polar axis

$$l = \{x \in \mathbb{R}^2 : x = \xi + t \cdot \vec{\xi a}, \ t \ge 0\},\$$

where polar angles are measured counterclockwise from the axis.

In this polar coordinate system one has  $q(t) = (r(t)\cos\varphi(t), r(t)\sin\varphi(t))$  for all  $q \in \Lambda$ . There is no uniqueness of a function  $\varphi(t)$ . If q(t) is continuous then we can assume that r(t) and  $\varphi(t)$  are continuous, too.

DEFINITION 1.1. – For each  $q \in \Lambda$  such that  $q(\pm \infty) \in \mathbb{R}^2 \setminus \{\xi\}$  we can determine the rotation number rot(q) (the winding number) as follows:

$$rot(q) = \left\lceil \frac{\varphi(\infty) - \varphi(-\infty)}{2\pi} \right\rceil,$$

where [s] denotes the integral part of  $s \in \mathbb{R}$ .

This definition is independent of the choice of a function  $\varphi(t)$ .

Set

$$R = \frac{1}{3}\min\{|b-a|, |b-\xi|, |a-\xi|\}.$$

From now on,  $B_r(x)$  stands for an open ball in  $\mathbb{R}^2$  of radius r > 0, centered at a point  $x \in \mathbb{R}^2$ .

REMARK 1.1. — Let  $0 < \varepsilon \le R$ . Assume that  $q \in \Gamma$  and there is  $T \in \mathbb{R}$  such that  $q(T) \in B_{\varepsilon}(b)$ . Then, by  $rot(q|_{(-\infty,T]})$  and  $rot(q|_{[T,\infty)})$  we mean the rotation numbers of appropriate paths in  $\Gamma$  and  $\Omega_b$ , resp., that arise from  $q|_{(-\infty,T]}$  and  $q|_{[T,\infty)}$ , resp., by connecting q(T) to b by a line segment.

It is justified by elementary homotopy arguments that

$$rot(q) = rot(q|_{(-\infty,T]}) + rot(q|_{[T,\infty)}).$$

Moreover, if  $q([T,\infty)) \subset B_{\varepsilon}(b)$  then

$$rot(q) = rot(q|_{(-\infty,T]}).$$

We can also introduce similar notation for q in  $\Upsilon$ ,  $\Omega_a$  or  $\Omega_b$ .

REMARK 1.2. — If  $q_1, q_2 \in \Gamma$  and there are  $t_1, t_2 \in \mathbb{R}$  and  $0 < \varepsilon \le R$  such that  $q_1((-\infty, t_1]) \cup q_2((-\infty, t_1]) \subset B_{\varepsilon}(a)$ ,  $q_1([t_2, \infty)) \cup q_2([t_2, \infty)) \subset B_{\varepsilon}(b)$  and  $q_1(t) = q_2(t)$  for all  $t \in [t_1, t_2]$  then  $rot(q_1) = rot(q_2)$ .

Analogous observations take place for  $q_1, q_2$  belonging to one of the sets: Y,  $\Omega_a$  and  $\Omega_b$ .

To exam rotation numbers of homoclinic and heteroclinic solutions of (1.1) we introduce the sets:

$$\Gamma^{-} = \{ q \in \Gamma : rot(q) < 0 \}, \qquad \Gamma^{+} = \{ q \in \Gamma : rot(q) \ge 0 \},$$

$$\Omega_{a}^{n} = \{ q \in \Omega_{a} : rot(q) \ge n \}, \qquad \Omega_{a}^{-n} = \{ q \in \Omega_{a} : rot(q) \le -n \}$$

and

$$\Omega_b^n = \{ q \in \Omega_b : rot(q) \ge n \}, \qquad \Omega_b^{-n} = \{ q \in \Omega_b : rot(q) \le -n \},$$

where  $n \in \mathbb{N}$ . For  $q \in \Lambda$ , set

(1.2) 
$$I(q) = \int_{-\infty}^{\infty} \left(\frac{1}{2} |\dot{q}(t)|^2 - V(q(t))\right) dt.$$

Let

$$\gamma^{\pm} = \inf\{I(q): q \in \Gamma^{\pm}\},$$
 $\omega_{q}^{\pm n} = \inf\{I(q): q \in \Omega_{q}^{\pm n}\}$ 

and

$$\omega_b^{\pm n} = \inf\{I(q): q \in \Omega_b^{\pm n}\},\,$$

where  $n \in \mathbb{N}$ . From now on, we will assume that

$$\gamma^- \leq \gamma^+$$
.

This involves no loss of generality.

Let us remark that if q is a member of one of the sets:  $\Gamma^{\pm}$ ,  $\Gamma$ ,  $\Omega_a^{\pm n}$ ,  $\Omega_a$ ,  $\Omega_b^{\pm n}$ ,  $\Omega_b$  then  $q+s\psi$  is a member of the same set for  $s\in\mathbb{R}$  small enough and  $\psi\in C_0^\infty(\mathbb{R},\mathbb{R}^2)$ . Moreover, if q is a minimizer of I on one of these families then

$$\frac{d}{ds}I(q+s\psi)_{|s=0}=0=\int\limits_{-\infty}^{\infty}((\dot{q}(t),\dot{\psi}(t))-(\nabla V(q(t)),\psi(t)))dt,$$

and consequently, q is a weak solution of (1.1). Analysis similar to that in the proof of Proposition 3.18 in [13] shows that q is a classical solution of (1.1).

The goal of this paper is to exam the existence of solutions of the Hamiltonian system (1.1) that are not homotopic in  $\mathbb{R}^2 \setminus \{\xi\}$  rel the endpoints. More precisely, we are going to prove the following theorems.

THEOREM 1.3. – Assume that  $V: \mathbb{R}^2 \setminus \{\xi\} \to \mathbb{R}$  satisfies conditions  $(V_1) - (V_5)$  and  $\gamma^- \leq \gamma^+$ . Then there exists  $Q \in \Gamma^-$  such that Q is a classical solution of the Hamiltonian system (1.1) and  $\dot{Q}(t) \to 0$ , as  $t \to \pm \infty$ .

THEOREM 1.4. – Assume that  $V: \mathbb{R}^2 \setminus \{\xi\} \to \mathbb{R}$  satisfies conditions  $(V_1) - (V_5)$  and  $\gamma^- \leq \gamma^+$ . Then one of the following theses holds.

- (i) There is  $Q \in \Gamma^+$  such that Q is a classical solution of (1.1) and  $\dot{Q}(t) \to 0$ , as  $t \to \pm \infty$ .
- (ii) There is  $Q \in \Omega_a$  such that Q is a classical solution of (1.1) with rot(Q) > 0 and  $\dot{Q}(t) \to 0$ , as  $t \to \pm \infty$ .
- (iii) There is  $Q \in \Gamma^-$  such that Q is a classical solution of (1.1),  $\dot{Q}(t) \to 0$ , as  $t \to \pm \infty$  and

$$\gamma^+ = I(Q) + \omega_b^n,$$

where n = -rot(Q). Moreover, the Hamiltonian system (1.1) possesses either a classical solution  $p \in \Omega_b$  such that rot(p) > 0 and  $\dot{p}(t) \to 0$ , as  $t \to \pm \infty$  or a classical solution  $Q_0 \in \Gamma^-$  such that  $rot(Q_0) < rot(Q)$  and  $\dot{Q}_0(t) \to 0$ , as  $t \to \pm \infty$ .

In the case where  $\gamma^- > \gamma^+$  we get the analogous theorems. Summarizing.

Conclusion 1.5. – Under the assumptions  $(V_1)$  –  $(V_5)$ , the Hamiltonian system (1.1) possesses at least two solutions which wind around  $\xi$  and join  $\{a,b\}$ 

to  $\{a,b\}$ . One of them is a heteroclinic orbit joining a to b. The second is either heteroclinic with a rotation number different from the first or homoclinic.

There are some works on periodic, homoclinic and heteroclinic solutions for Hamiltonian systems with singularities. We refer the reader to: [1-6, 9, 10, 14, 15, 18] and the references given there. For a treatment of the existence of other types of solutions we refer to: [7, 8, 16, 17].

We are motivated by [14] of P. H. Rabinowitz. He studied the existence of homoclinic (to 0) solutions for a family of singular Hamiltonian systems which are periodically forced:

$$\ddot{q} + V_q(t, q) = 0,$$

where  $V \in C^1(\mathbb{R} \times (\mathbb{R}^2 \setminus \{\xi\}), \mathbb{R})$   $(\xi \neq 0)$  is T-periodic with respect to t. Moreover, for each  $t \in \mathbb{R}$ ,  $V(t,\cdot)$  satisfies  $(V_2)$ ,  $(V_3)$  and  $(V_5)$  uniformly in t,  $V(t,x) \leq 0$  and V(t,x) = 0 iff x = 0. Under these assumptions, he proved the existence of two homoclinic orbits  $q^{\pm} : \mathbb{R} \to \mathbb{R}^2 \setminus \{\xi\}$  such that the rotation number of  $q^{\pm}$  is positive and negative, respectively. In the same work he also treated a more general situation in which V has strong force singularities at  $\xi_1, \ldots, \xi_k$ . In this case he established the existence of at least k geometrically distinct solutions homoclinic to 0.

Finally, I would like to mention the paper [4] of M. J. Borges. She considered the Hamiltonian system (1.1) with the potential V possessing a global maximum at 0 and strong force singularities at two points:  $\xi_1, \xi_2$ . Using variational methods she found homoclinic solutions winding around each singularity and around both singularities, periodic solutions and heteroclinic solutions joining 0 to periodic solutions.

Our paper is organized as follows. In Section 2 we discuss some properties of the action integral *I*. In Section 3 we prove Theorem 1.3. Section 4 provides a detailed proof of Theorem 1.4.

The problem is studied by variational methods. We look for connecting orbits by minimizing I on suitable classes of maps  $q: \mathbb{R} \to \mathbb{R}^2 \setminus \{\xi\}$ . Although some ideas are from [14], there are many new tricks involved in this work (see Lemmas 4.1-4.6).

# 2. – Some properties of the action integral.

In this section we present some properties of the action functional I given by (1.2). We will use them in our studies.

Define

$$\mathcal{M} = \{x \in \mathbb{R}^2 : V(x) = 0\} = \{a, b\},$$
$$a_{\varepsilon} = \inf\{-V(x) : x \notin B_{\varepsilon}(\mathcal{M})\},$$

where  $0 < \varepsilon \le R$  and  $B_{\varepsilon}(\mathcal{M}) = B_{\varepsilon}(a) \cup B_{\varepsilon}(b)$ . By  $(V_2)$ ,  $(V_4)$  and  $(V_5)$  it follows that  $a_{\varepsilon} > 0$ .

LEMMA 2.1. – Suppose that  $q \in \Lambda$  and  $q(t) \notin B_{\varepsilon}(\mathcal{M})$  for each  $t \in \bigcup_{i=1}^{k} [r_i, s_i]$ , where  $[r_i, s_i] \cap [r_i, s_i] = \emptyset$  for  $i \neq j$ . Then

(2.1) 
$$I(q) \ge \sqrt{2a_{\varepsilon}} \sum_{i=1}^{k} |q(s_i) - q(r_i)|.$$

The proof of Lemma 2.1 is the same as that of Lemma 3.6 in [13] or Lemma 2.1 in [12].

LEMMA 2.2. – If  $q \in \Lambda$  and  $I(q) < \infty$  then  $q \in L^{\infty}(\mathbb{R}, \mathbb{R}^2)$ .

LEMMA 2.3. – If  $q \in \Lambda$  and  $I(q) < \infty$  then  $q(\pm \infty) \in \mathcal{M}$ .

We can easily prove these two lemmas by the use of Lemma 2.1. For more details we refer the reader to [13] (see Remark 3.10 and Proposition 3.11) and [12] (see Corollary 2.2 and Lemma 2.4).

PROPOSITION 2.4. — If  $\{q_m\}_{m\in\mathbb{N}}$  is a sequence that belongs to one of the families:  $\Gamma$ ,  $\Upsilon$ ,  $\Omega_a$  or  $\Omega_b$  and  $\{I(q_m)\}_{m\in\mathbb{N}}$  is a bounded sequence in  $\mathbb{R}$ , then  $\{q_m\}_{m\in\mathbb{N}}$  possesses a subsequence that converges weakly in E and strongly in  $L^\infty_{\mathrm{loc}}(\mathbb{R}, \mathbb{R}^2)$ .

PROOF. – Assume that  $\{q_m\}_{m\in\mathbb{N}}\subset\Gamma$ . It is sufficient to show that  $\{q_m\}_{m\in\mathbb{N}}$  is a bounded sequence in E. By assumption, there is M>0 such that for all  $m\in\mathbb{N}$ ,

$$0 < I(q_m) < M$$
.

From this and (1.2) we get

$$\|\dot{q}_m\|_{L^2}^2 \le 2M.$$

Moreover, from Lemma 2.2 it follows that  $q_m \in L^{\infty}(\mathbb{R}, \mathbb{R}^2)$  for all  $m \in \mathbb{N}$ .

Fix  $0 < \varepsilon \le R$ . Then for each  $m \in \mathbb{N}$  there are  $\tau_m, t_m \in \mathbb{R}$  such that  $q_m(\tau_m) \in \partial B_{\varepsilon}(a), q_m(t) \in B_{\varepsilon}(a)$  for all  $t < \tau_m, q_m(t_m) \in \partial B_{\varepsilon}(b)$  and  $q_m(t) \in B_{\varepsilon}(b)$  for all  $t > t_m$ . Finally, for  $q_m|_{[\tau_m,t_m]}$  there is  $s_m \in [\tau_m,t_m]$  such that

$$|q_m(s_m)| = \max_{t \in [\tau_m, t_m]} |q_m(t)|.$$

Applying Lemma 2.1 we conclude that the sequence  $\{q_m(s_m)\}_{m\in\mathbb{N}}$  is bounded. Hence  $\{q_m\}_{m\in\mathbb{N}}$  is bounded in  $L^{\infty}(\mathbb{R},\mathbb{R}^2)$ .

In consequence,  $\{q_m\}_{m\in\mathbb{N}}$  is bounded in E. By the reflexivity of E there is  $Q\in E$  such that going to a subsequence  $q_m\rightharpoonup Q$  in E, which implies that  $q_m\to Q$  in  $L^\infty_{loc}(\mathbb{R},\mathbb{R}^2)$ .

In the rest of cases, the proof is similar.

LEMMA 2.5. – If  $q \in \Lambda$  and  $q(t) \in \mathcal{N}$  for all  $t \in [\sigma, \mu]$  then

$$|U(q(\mu))| \leq |U(q(\sigma))| + \left(\int\limits_{\sigma}^{\mu} -V(q(t))dt\right)^{\frac{1}{2}} \cdot \left(\int\limits_{\sigma}^{\mu} |\dot{q}(t)|^2 dt\right)^{\frac{1}{2}}.$$

The proof of this lemma can be found in [14] (see (2.21), p. 271). It is based on the strong force condition  $(V_3)$ .

Applying the above inequality and (1.2), for  $q \in \Lambda$  such that  $q(t) \in \mathcal{N}$  for all  $t \in [\sigma, \mu]$  we get

$$|U(q(\mu))| \le |U(q(\sigma))| + \sqrt{2}I(q).$$

PROPOSITION 2.6. – Let  $\{q_m\}_{m\in\mathbb{N}}\subset \Lambda$  be a sequence such that  $\{I(q_m)\}_{m\in\mathbb{N}}$  is bounded. Then there is r>0 such that  $q_m(t)\cap B_r(\xi)=\emptyset$  for all  $t\in\mathbb{R}$  and  $m\in\mathbb{N}$ .

PROOF. – By Lemma 2.3,  $q_m(\pm \infty) \in \mathcal{M}$  for each  $m \in \mathbb{N}$ .

On the contrary, suppose that there exists a sequence  $\{q_m(\mu_m)\}_{m\in\mathbb{N}}$  such that  $q_m(\mu_m)\to \xi$ , as  $m\to\infty$ . Fix  $0<\delta\leq R$  such that  $\overline{B_\delta(\xi)}\subset\mathcal{N}$ . There is  $m_0\in\mathbb{N}$  such that for  $m\geq m_0$ ,  $|q_m(\mu_m)-\xi|<\delta$ . For each  $m\geq m_0$  there exists  $\sigma_m<\mu_m$  such that  $q_m(\sigma_m)\in\partial B_\delta(\xi)$  and  $q_m(t)\in B_\delta(\xi)$  for all  $t\in(\sigma_m,\mu_m)$ . Then

$$|U(q_m(\mu_m))| \le |U(q_m(\sigma_m))| + \sqrt{2}I(q_m).$$

As  $\{U(q_m(\sigma_m))\}_{m\in\mathbb{N}}$  and  $\{I(q_m)\}_{m\in\mathbb{N}}$  are bounded, we get  $\{U(q_m(\mu_m))\}_{m\in\mathbb{N}}$  is bounded, too. On the other hand, by  $(V_3)$ , we receive  $|U(q_m(\mu_m))| \to \infty$ , as  $m \to \infty$ , a contradiction.

FACT 2.7. – If  $q: \mathbb{R} \to \mathbb{R}^n$  is a continuous function such that  $\dot{q} \in L^2_{loc}(\mathbb{R}, \mathbb{R}^n)$  then for each  $t \in \mathbb{R}$ ,

$$|q(t)| \leq \sqrt{2} \Biggl( \int\limits_{t-rac{1}{2}}^{t+rac{1}{2}} (|q(s)|^2 + |\dot{q}(s)|^2) ds \Biggr)^{rac{1}{2}}.$$

This inequality was proved for example in [11] (see Fact 2.8).

Proposition 2.8. – If  $Q \in \Lambda$  is a homoclinic or heteroclinic orbit of the Hamiltonian system (1.1) then

$$\dot{Q}(t) \to 0$$
, as  $t \to \pm \infty$ .

PROOF. – From Fact 2.7 we get

$$|\dot{Q}(t)|^2 \leq 2 \int\limits_{t-\frac{1}{2}}^{t+\frac{1}{2}} |\dot{Q}(s)|^2 ds + 2 \int\limits_{t-\frac{1}{2}}^{t+\frac{1}{2}} |\ddot{Q}(s)|^2 ds$$

for each  $t \in \mathbb{R}$ . As Q(t) satisfies the Hamiltonian system (1.1) we have

$$|\dot{Q}(t)|^2 \leq 2\int\limits_{t-\frac{1}{2}}^{t+\frac{1}{2}} |\dot{Q}(s)|^2 ds + 2\int\limits_{t-\frac{1}{2}}^{t+\frac{1}{2}} |\nabla V(Q(s))|^2 ds.$$

Let  $\eta > 0$ . By  $(V_4)$ , there is  $L_1 > 0$  such that if  $|s| > L_1$  then  $|\nabla V(Q(s))|^2 < \frac{\eta}{4}$ . Since  $Q \in A \subset E$ , there is  $L_2 > 0$  such that if  $|t| > L_2$  then

$$\int_{t-\frac{1}{2}}^{t+\frac{1}{2}} |\dot{Q}(s)|^2 ds < \frac{\eta}{4}.$$

Set  $L=\max\{L_1,L_2\}$ . If  $|t|>L+\frac{1}{2}$  then  $|\dot{Q}(t)|^2<\eta$ . Hence  $\dot{Q}(t)\to 0$ , as  $t\to\pm\infty$ .

### 3. - Proof of Theorem 1.3.

Let  $\{q_m\}_{m\in\mathbb{N}}\subset \Gamma^-$  be a sequence such that

$$\lim_{m\to\infty}I(q_m)=\gamma^-.$$

From Proposition 2.4 it follows that there is  $Q \in E$  such that going to a subsequence if necessary  $q_m \rightharpoonup Q$  in E and  $q_m \to Q$  in  $L^\infty_{loc}(\mathbb{R},\mathbb{R}^2)$ . By Proposition 2.6 we conclude that  $Q \in \Lambda$ .

Remark 3.1. – For all  $T_1, T_2 \in \mathbb{R}$  such that  $T_1 < T_2$  a functional given by

$$E
i q \longrightarrow \int\limits_{T_1}^{T_2} \left(rac{1}{2}|\dot{q}(t)|^2 - V(q(t))
ight) dt$$

is weakly lower semi-continuous.

Hence for each  $l \in \mathbb{N}$ ,

$$\begin{split} \int_{-l}^{l} & \left( \frac{1}{2} |\dot{Q}(t)|^2 - V(Q(t)) \right) dt \leq \liminf_{m \to \infty} \int_{-l}^{l} \left( \frac{1}{2} |\dot{q}_m(t)|^2 - V(q_m(t)) \right) dt \\ & \leq \lim_{m \to \infty} I(q_m) = \gamma^-. \end{split}$$

Letting  $l \to \infty$  we receive

$$I(Q) < \gamma^{-}$$
.

By Lemma 2.3,  $Q(\pm \infty) \in \mathcal{M}$ . We will show that  $Q(-\infty) = a$  and  $Q(\infty) = b$ . Fix

 $0 < \varepsilon \le R$ . Since  $q_m(-\infty) = a$ , there is  $\tau_m \in \mathbb{R}$  such that  $q_m(\tau_m) \in \partial B_{\varepsilon}(a)$  and  $q_m(t) \in B_{\varepsilon}(a)$  for all  $t < \tau_m$ .

REMARK 3.2. – If  $q \in \Lambda$  then for each  $\theta \in \mathbb{R}$ ,  $\theta q = q(\cdot - \theta) \in \Lambda$  and  $I(q) = I(\theta q)$ . Moreover, if  $\bar{q}(t) = q(-t)$  then  $I(q) = I(\bar{q})$ .

Therefore, without loss of generality, we can assume that  $\tau_m = 0$  for each  $m \in \mathbb{N}$ . In consequence,

$$|q_m(t) - a| \le \varepsilon$$

for all  $m \in \mathbb{N}$  and  $t \leq 0$ , and so

$$|Q(t) - a| \le \varepsilon$$

for all  $t \leq 0$ . As  $Q(t) \in \overline{B_{\varepsilon}(a)}$  for all  $t \leq 0$  and  $Q(-\infty) \in \mathcal{M}$ , we get  $Q(-\infty) = a$ . Suppose, contrary to our claim, that  $Q(\infty) = a$ . Let  $\delta > 0$  be sufficiently small such that  $4\delta < \varepsilon$  and

$$2\delta^2 + \max\{-V(x): |x-a| \le 2\delta\} < \frac{\varepsilon}{4}\sqrt{2a_{\underline{\varepsilon}}}.$$

There is  $t_{\delta} > 0$  such that  $Q(t_{\delta}) \in \partial B_{\delta}(a)$  and  $Q(t) \in B_{\delta}(a)$  for all  $t > t_{\delta}$ . Since  $q_m(t_{\delta}) \to Q(t_{\delta})$ , there exists  $m_0 \in \mathbb{N}$  such that for all  $m \geq m_0$ ,

$$|q_m(t_\delta) - Q(t_\delta)| < \delta.$$

From this,

$$|q_m(t_\delta) - a| < 2\delta$$

for all  $m \geq m_0$ . Take  $s^m_{\delta} \in [0, t_{\delta}]$  such that  $q_m(t) \notin B_{\frac{\varepsilon}{2}}(a)$  for all  $t \in [0, s^m_{\delta}]$  and  $q_m(s^m_{\delta}) \in \partial B_{\frac{\varepsilon}{2}}(a)$ .

Then

$$egin{split} I(q_m) &\geq \int\limits_0^{s_\delta^m} \left(rac{1}{2}|\dot{q}_m(t)|^2 - V(q_m(t))
ight)\!dt + \int\limits_{t_\delta}^\infty \left(rac{1}{2}|\dot{q}_m(t)|^2 - V(q_m(t))
ight)\!dt \ &\geq rac{arepsilon}{2}\sqrt{2a_{rac{arepsilon}{2}}} + \int\limits_{t_\delta}^\infty \left(rac{1}{2}|\dot{q}_m(t)|^2 - V(q_m(t))
ight)\!dt, \end{split}$$

by Lemma 2.1. Define

$$Q_m(t) = \left\{ egin{aligned} a & ext{if} & t \leq t_\delta - 1, \ (t - t_\delta + 1)q_m(t_\delta) + (t_\delta - t)a & ext{if} & t \in [t_\delta - 1, t_\delta], \ q_m(t) & ext{if} & t > t_\delta, \end{aligned} 
ight.$$

where  $m \geq m_0$ . By the above, we have  $Q_m \in \Gamma$  and

$$egin{aligned} I(Q_m) &= \int\limits_{t_\delta-1}^{t_\delta} \left(rac{1}{2}|q_m(t_\delta)-a|^2 - V(Q_m(t))
ight) dt \ &+ \int\limits_{t_\delta}^{\infty} \left(rac{1}{2}|\dot{q}_m(t)|^2 - V(q_m(t))
ight) dt \ &\leq &2\delta^2 + \max\{-V(x)\colon |x-a| \leq 2\delta\} \ &+ I(q_m) - rac{arepsilon}{2}\sqrt{2a_{rac{arepsilon}{2}}} \ &< &I(q_m) - rac{arepsilon}{4}\sqrt{2a_{rac{arepsilon}{2}}} \end{aligned}$$

for all  $m \geq m_0$ . In consequence,

$$\gamma^- \leq \liminf_{m \to \infty} I(Q_m) \leq \liminf_{m \to \infty} I(q_m) - \frac{\varepsilon}{4} \sqrt{2a_{\frac{\varepsilon}{2}}} = \gamma^- - \frac{\varepsilon}{4} \sqrt{2a_{\frac{\varepsilon}{2}}}$$

a contradiction. Thus  $Q(\infty) = b$ .

By the above,  $Q \in \Gamma$ . Suppose, contrary to our claim, that  $Q \in \Gamma^+$ . If  $\gamma^- < \gamma^+$  then  $I(Q) \geq \gamma^+ > \gamma^-$ , a contradiction. Assume now that  $\gamma^- = \gamma^+$ . Let  $\beta$  be a positive constant such that  $\beta < \frac{1}{2} \sqrt{2a_{\varepsilon}} (|b - \xi| - 2\varepsilon)$ . Choose T > 0 such that  $Q([T, \infty)) \subset B_{\varepsilon}(b)$  and

$$\int_{-\infty}^{T} \left(\frac{1}{2}|\dot{Q}(t)|^{2} - V(Q(t))dt\right)dt > \gamma^{-} - \beta.$$

Since  $q_m \to Q$  uniformly on [0,T], there is  $m_0 \in \mathbb{N}$  such that for  $m \geq m_0$ ,  $rot(q_m|_{(-\infty,T]}) = rot(Q) \geq 0$ , and so  $rot(q_m|_{[T,\infty)}) < -rot(Q) \leq 0$ . Moreover, by Lemma 2.1,

$$\int\limits_{T}^{\infty} \Biggl( \frac{1}{2} {\left| \dot{q}_m(t) \right|}^2 - V(q_m(t)) \Biggr) dt \geq \sqrt{2a_{\varepsilon}} (|b-\xi| - 2\varepsilon)$$

for all  $m \geq m_0$ . From Remark 3.1 we get

$$\liminf_{m\to\infty}\int\limits_{-\infty}^T \left(\frac{1}{2}|\dot{q}_m(t)|^2 - V(q_m(t))\right) dt \geq \int\limits_{-\infty}^T \left(\frac{1}{2}|\dot{Q}(t)|^2 - V(Q(t))\right) dt.$$

Hence there is  $m_1 \in \mathbb{N}$  such that for all  $m \geq m_1$ ,

$$\begin{split} \int\limits_{-\infty}^{T} & \left(\frac{1}{2} |\dot{q}_m(t)|^2 - V(q_m(t))\right) dt > \int\limits_{-\infty}^{T} & \left(\frac{1}{2} |\dot{Q}(t)|^2 - V(Q(t))\right) dt \\ & - \frac{1}{4} \sqrt{2a_{\varepsilon}} (|b - \xi| - 2\varepsilon). \end{split}$$

Consequently, for  $m \in \mathbb{N}$  large enough,

$$\begin{split} I(q_m) &= \int\limits_{-\infty}^T \left(\frac{1}{2}|\dot{q}_m(t)|^2 - V(q_m(t))\right) dt + \int\limits_T^\infty \left(\frac{1}{2}|\dot{q}_m(t)|^2 - V(q_m(t))\right) dt \\ &> \int\limits_{-\infty}^T \left(\frac{1}{2}|\dot{Q}(t)|^2 - V(Q(t)) dt\right) dt + \frac{3}{4}\sqrt{2a_{\varepsilon}}(|b - \xi| - 2\varepsilon) \\ &> \gamma^- - \beta + \frac{3}{4}\sqrt{2a_{\varepsilon}}(|b - \xi| - 2\varepsilon) \\ &> \gamma^- + \frac{1}{4}\sqrt{2a_{\varepsilon}}(|b - \xi| - 2\varepsilon), \end{split}$$

which contradicts the assumption  $\lim_{m\to\infty} I(q_m) = \gamma^-$ . Therefore  $Q\in \Gamma^-$ , and in consequence,  $I(Q) = \gamma^-$ . Thus Q is a classical solution of (1.1).

From Proposition 2.8 we get  $\dot{Q}(t) \to 0$ , as  $t \to \pm \infty$ .

### 4. - Proof of Theorem 1.4.

Let  $\{q_m\}_{m\in\mathbb{N}}\subset \Gamma^+$  be a sequence such that

$$\lim_{m\to\infty}I(q_m)=\gamma^+.$$

From Proposition 2.4 it follows that there is a subsequence of  $\{q_m\}_{m\in\mathbb{N}}$  which converges weakly in E and strongly in  $L^\infty_{\mathrm{loc}}(\mathbb{R},\mathbb{R}^2)$ . For abbreviation, we write

$$q_m 
ightharpoonup Q$$
 in  $E$  and  $q_m 
ightharpoonup Q$  in  $L^\infty_{
m loc}(\mathbb{R},\mathbb{R}^2)$ .

Moreover, by Proposition 2.6,  $Q \in \Lambda$ , by Remark 3.1,  $I(Q) \le \gamma^+$ , and by Lemma 2.3,  $Q(\pm \infty) \in \mathcal{M}$ .

Fix  $0 < \varepsilon \le R$ . Remark 3.2 implies that we can assume that  $q_m(0) \in \partial B_{\varepsilon}(a)$  and  $q_m(t) \in B_{\varepsilon}(a)$  for all t < 0 and  $m \in \mathbb{N}$ . Then  $Q((-\infty, 0]) \subset \overline{B_{\varepsilon}(a)}$ , and in consequence,  $Q(-\infty) = a$ . Now the proof falls naturally into three parts, because Q may belong to  $\Gamma^+$ ,  $\Gamma^-$  or  $\Omega_a$ .

We have divided the proof into a sequence of lemmas. The proofs of Lemmas 4.3-4.6 are similar in spirit. However, for convenience of the reader, we have decided to prove them all.

LEMMA 4.1. – For each  $\eta > 0$  there is  $0 < r \le R$  such that for all  $x, y \in B_r(a)$  (resp.  $x, y \in B_r(b)$ ) and  $T \in \mathbb{R}$ ,

$$\int_{T}^{T+1} \left( \frac{1}{2} |y - x|^2 - V(l_{x,y}(t)) \right) dt < \eta,$$

where  $l_{x,y}(t) = (T + 1 - t)x + (t - T)y$  for each  $t \in [T, T + 1]$ .

The proof of Lemma 4.1 is straightforward. Therefore we omit it.

Lemma 4.2. – If  $Q \in \Gamma^+$  then Q is a classical solution of (1.1).

PROOF. – Since  $Q \in \Gamma^+$ , we get  $I(Q) \ge \gamma^+$ . Consequently,  $I(Q) = \gamma^+$ , and so Q is a minimizer of I on  $\Gamma^+$ . Thus Q is a classical solution of (1.1).

Lemma 4.3. – If  $Q \in \Omega_a$  then Q is a classical solution of (1.1) and rot(Q) > 0.

PROOF. – Set k = rot(Q). It is sufficient to show that

$$I(Q) = \inf\{I(q): q \in \Omega_a \land rot(q) = k\}.$$

Suppose, by contradiction, that there is  $\tilde{q} \in \Omega_a$  such that  $rot(\tilde{q}) = k$  and  $I(\tilde{q}) < I(Q)$ . Put  $d = I(Q) - I(\tilde{q})$ . Fix  $0 < \eta < \frac{d}{2}$ . By Lemma 4.1, there is  $0 < \delta \le R$  such that for all  $x, y \in B_{\delta}(a)$  and  $T \in \mathbb{R}$ ,

$$\int_{T}^{T+1} \! \left( \frac{1}{2} |y-x|^2 - V(l_{x,y}(t)) \right) \! dt \! < \! \frac{\eta}{2}.$$

Choose T > 0 such that  $\tilde{q}([T, \infty)) \subset B_{\delta}(a)$ ,  $Q([T, \infty)) \subset B_{\delta}(a)$  and

$$\int\limits_{-\infty}^T \biggl(\frac{1}{2}|\dot{Q}(t)|^2 - V(Q(t))\biggr)dt > I(Q) - \frac{\eta}{4}.$$

Since  $q_m \to Q$  uniformly on [0,T+1], there is  $m_0 \in \mathbb{N}$  such that  $q_m([T,T+1]) \subset B_\delta(a)$  and  $rot(q_m|_{(-\infty,T]}) = rot(Q)$  for all  $m \geq m_0$ . Let

$$\tilde{q}_m(t) = \begin{cases} \tilde{q}(t) & \text{if } t \leq T, \\ (T+1-t)\tilde{q}(T) + (t-T)q_m(T+1) & \text{if } t \in [T,T+1], \\ q_m(t) & \text{if } t > T+1. \end{cases}$$

where  $m \geq m_0$ . Then  $\tilde{q}_m(-\infty) = a$ ,  $\tilde{q}_m(\infty) = b$  and

$$\begin{split} rot(\tilde{q}_m) &= rot(\tilde{q}_{|(-\infty,T]}) + rot(q_m|_{[T+1,\infty)}) \\ &= rot(Q_{|(-\infty,T]}) + rot(q_m|_{[T+1,\infty)}) \\ &= rot(q_m|_{(-\infty,T]}) + rot(q_m|_{[T+1,\infty)}) = rot(q_m), \end{split}$$

and hence  $\tilde{q}_m \in \Gamma^+$ . From Remark 3.1 we deduce that there is  $m_1 \in \mathbb{N}$  such that for all  $m \geq m_1$ ,

$$\int\limits_{-\infty}^T \biggl(\frac{1}{2}|\dot{q}_m(t)|^2 - V(q_m(t))\biggr)dt > \int\limits_{-\infty}^T \biggl(\frac{1}{2}|\dot{Q}(t)|^2 - V(Q(t))\biggr)dt - \frac{\eta}{4}.$$

Using the above inequalities we get

$$\begin{split} I(q_m) - I(\tilde{q}_m) &\geq \int\limits_{-\infty}^{T} \left(\frac{1}{2}|\dot{q}_m(t)|^2 - V(q_m(t))\right) dt \\ &- \int\limits_{T}^{T+1} \left(\frac{1}{2}|\dot{\tilde{q}}_m(t)|^2 - V(\tilde{q}_m(t))\right) dt \\ &- \int\limits_{-\infty}^{T} \left(\frac{1}{2}|\dot{\tilde{q}}(t)|^2 - V(\tilde{q}(t))\right) dt \\ &> I(Q) - I(\tilde{q}) - \eta > \frac{d}{2} \end{split}$$

for  $m \in \mathbb{N}$  large enough, and so

$$\gamma^+ = \lim_{m o \infty} I(q_m) \geq \liminf_{m o \infty} I( ilde{q}_m) + rac{d}{2} \geq \gamma^+ + rac{d}{2},$$

a contradiction. Consequently, Q is a classical solution of (1.1).

To complete the proof, we have to show that k > 0. Suppose, on the contrary, that  $k \le 0$ . For  $\eta > 0$  we choose  $\delta$ , T,  $m_0$  and  $m_1$  as above.

For  $m \geq m_0$ , let

$$u_m(t) = \begin{cases} a \text{ if } t \leq T, \\ (T+1-t)a + (t-T)q_m(T+1) \text{ if } t \in [T, T+1], \\ q_m(t) \text{ if } t \geq T+1. \end{cases}$$

Since  $rot(q_m) \ge 0$  and  $rot(q_{m|(-\infty,T+1]}) = rot(Q_{|(-\infty,T+1]}) = k$ , we get

$$rot(u_m) = rot(q_{m|[T+1,\infty)}) \ge 0.$$

Thus  $u_m \in \Gamma^+$ . Furthermore, for  $m \in \mathbb{N}$  sufficiently large,

$$I(q_m) - I(u_m) \ge \int_{-\infty}^{T} \left(\frac{1}{2} |\dot{q}_m(t)|^2 - V(q_m(t))\right) dt$$
$$- \int_{T}^{T+1} \left(\frac{1}{2} |\dot{u}_m(t)|^2 - V(u_m(t))\right) dt$$
$$> I(Q) - \eta.$$

Passing to a limit we get

$$\gamma^+ = \lim_{m o \infty} I(q_m) \geq \liminf_{m o \infty} I(u_m) + I(Q) - \eta \geq \gamma^+ + I(Q) - \eta.$$

Letting  $\eta \to 0^+$ ,

$$\gamma^+ \ge \gamma^+ + I(Q) > \gamma^+,$$

a contradiction. Therefore k > 0.

Lemma 4.4. – If  $Q \in \Gamma^-$  then  $\gamma^+ = I(Q) + \omega_b^n$ , where n = -rot(Q).

PROOF. — Let  $\eta > 0$ . From Lemma 4.1 it follows that there is  $0 < \delta \le R$  such that for all  $x, y \in B_{\delta}(b)$  and  $T \in \mathbb{R}$ ,

$$\int_{T}^{T+1} \left( \frac{1}{2} |y-x|^2 - V(l_{x,y}(t)) \right) dt < \frac{\eta}{2}.$$

By assumption, there is T>0 such that  $Q([T,\infty))\subset B_\delta(b)$ . By the definition of infimum, there exists  $p\in\Omega_b^n$  such that

$$I(p) < \omega_b^n + \frac{\eta}{2}.$$

Additionally, by Remark 3.2, we can assume that  $p((-\infty, T+1]) \subset B_{\delta}(b)$ . Define

$$\hat{Q}(t) = \left\{ egin{aligned} Q(t) & \text{if} & t \leq T, \\ (T+1-t)Q(T) + (t-T)p(T+1) & \text{if} & t \in [T,T+1], \\ p(t) & \text{if} & t \geq T+1. \end{aligned} \right.$$

We have  $\hat{Q}(-\infty) = a$ ,  $\hat{Q}(\infty) = b$  and  $I(\hat{Q}) < I(Q) + \omega_b^n + \eta$ . Moreover,

$$rot(\hat{Q}) = rot(Q) + rot(p) > 0.$$

Hence  $\hat{Q} \in \Gamma^+$  and  $I(\hat{Q}) \geq \gamma^+$ . In consequence,

$$\gamma^+ < I(Q) + \omega_b^n + \eta,$$

and letting  $\eta \to 0^+$ , we get

$$(4.1) \gamma^+ \le I(Q) + \omega_h^n.$$

In order to complete the proof, we have to show that  $\gamma^+ \geq I(Q) + \omega_h^n$ .

To this aim, fix  $\eta > 0$ . By Lemma 4.1, there is  $0 < \delta \le R$  such that for each  $x \in B_{\delta}(b)$  and  $T \in \mathbb{R}$ ,

$$\int_{T-1}^{T} \left( \frac{1}{2} |x-b|^2 - V(l_{b,x}(t)) \right) dt < \frac{\eta}{2},$$

where  $l_{b,x}(t) = (T-t)b + (t-T+1)x$  for  $t \in [T-1,T]$ . By assumption, there is T > 0 such that  $Q([T,\infty)) \subset B_{\delta}(b)$  and

$$\int_{-\infty}^{T} \left(\frac{1}{2}|\dot{Q}(t)|^2 - V(Q(t))\right) dt > I(Q) - \frac{\eta}{4}.$$

Let  $\{p_m\}_{m\in\mathbb{N}}\subset\Omega_b$  be given by

$$p_m(t) = \left\{ egin{aligned} b & ext{if} \quad t \leq T-1, \\ (T-t)b + (t-T+1)q_m(T) & ext{if} \quad t \in [T-1,T], \\ q_m(t) & ext{if} \quad t \geq T. \end{aligned} 
ight.$$

Then for  $m \in \mathbb{N}$  large enough,

$$I(p_m) < \int_{T}^{\infty} \left(\frac{1}{2} |\dot{q}_m(t)|^2 - V(q_m(t))\right) dt + \frac{\eta}{2}.$$

By the strong convergence of  $\{q_m\}_{m\in\mathbb{N}}$  in  $L^{\infty}_{loc}(\mathbb{R},\mathbb{R}^2)$ , there is  $m_0\in\mathbb{N}$  such that for all  $m\geq m_0$ ,  $q_m(T)\in B_{\delta}(b)$  and  $rot(q_m|_{\ell_{-\infty}(T)})=rot(Q)$ .

Hence

$$rot(Q) + rot(p_m) = rot(q_m) > 0.$$

From this it follows that for all  $m \geq m_0$  we have

$$rot(p_m) \geq n$$
,

and so  $p_m \in \Omega_b^n$ . Remark 3.1 implies the existence of  $m_1 \in \mathbb{N}$  such that

$$\int_{-\infty}^{T} \left( \frac{1}{2} |\dot{q}_{m}(t)|^{2} - V(q_{m}(t)) \right) dt > \int_{-\infty}^{T} \left( \frac{1}{2} |\dot{Q}(t)|^{2} - V(Q(t)) \right) dt - \frac{\eta}{4}$$

for all  $m \geq m_1$ . By the above, we conclude that for  $m \in \mathbb{N}$  sufficiently large,

$$I(q_m) > I(Q) + I(p_m) - \eta \ge I(Q) + \omega_b^n - \eta.$$

Hence

$$\gamma^+ \geq I(Q) + \omega_b^n - \eta$$
.

Letting  $\eta \to 0^+$ , we receive

$$(4.2) \gamma^+ \ge I(Q) + \omega_h^n.$$

Combining (4.1) with (4.2), we get our claim.

Lemma 4.5. – If  $Q \in \Gamma^-$  then Q is a classical solution of (1.1).

PROOF. – Put n = -rot(Q). It suffices to prove that

$$I(Q) = \inf\{I(q): q \in \Gamma^- \land rot(q) = -n\}.$$

On the contrary, suppose that there exists  $\hat{q} \in \Gamma^-$  such that  $rot(\hat{q}) = -n$  and  $I(\hat{q}) < I(Q)$ . Define  $d = I(Q) - I(\hat{q})$ . Fix  $0 < \eta < \frac{d}{2}$ . From Lemma 4.1 it follows that there is  $0 < \delta \le R$  such that for all  $x, y \in B_{\delta}(b)$  and  $T \in \mathbb{R}$ ,

$$\int_{T}^{T+1} \left( \frac{1}{2} |y - x|^2 - V(l_{x,y}(t)) \right) dt < \frac{\eta}{2}.$$

We can choose T>0 such that  $\hat{q}([T,\infty))\subset B_{\delta}(b),\,Q([T,\infty))\subset B_{\delta}(b)$  and

$$\int_{-\infty}^{T} \left(\frac{1}{2}|\dot{Q}(t)|^2 - V(Q(t))\right) dt > I(Q) - \frac{\eta}{4}.$$

Since  $q_m \to Q$  uniformly on [0, T+1], there is  $m_0 \in \mathbb{N}$  such that for all  $m \ge m_0$ ,  $q_m([T, T+1]) \subset B_{\delta}(b)$  and  $rot(q_m|_{(-\infty, T]}) = rot(Q)$ . For each  $m \ge m_0$ , let  $\hat{q}_m : \mathbb{R} \to \mathbb{R}^2$  be defined by

$$\hat{q}_m(t) = egin{cases} \hat{q}(t) ext{ if } & t \leq T, \ (T+1-t)\hat{q}(T) + (t-T)q_m(T+1) ext{ if } & t \in [T,T+1], \ q_m(t) ext{ if } & t \geq T+1. \end{cases}$$

By definition, it follows that  $\hat{q}_m \in \Gamma$ . What is more,

$$\begin{split} rot(\hat{q}_{m}) &= rot(\hat{q}|_{(-\infty,T]}) + rot(q_{m}|_{[T+1,\infty)}) \\ &= rot(Q|_{(-\infty,T]}) + rot(q_{m}|_{[T+1,\infty)}) \\ &= rot(q_{m}|_{(-\infty,T]}) + rot(q_{m}|_{[T+1,\infty)}) = rot(q_{m}), \end{split}$$

and so  $\hat{q}_m \in \Gamma^+$ . Applying Remark 3.1 we conclude that there is  $m_1 \in \mathbb{N}$  such

that for all  $m \geq m_1$ ,

$$\int\limits_{-\infty}^{T} \biggl( \frac{1}{2} |\dot{q}_m(t)|^2 - V(q_m(t)) \biggr) dt > \int\limits_{-\infty}^{T} \biggl( \frac{1}{2} |\dot{Q}(t)|^2 - V(Q(t)) \biggr) dt - \frac{\eta}{4}.$$

Combining the above inequalities we receive

$$I(q_m) - I(\hat{q}_m) > I(Q) - I(\hat{q}) - \eta$$

for  $m \in \mathbb{N}$  sufficiently large, and hence

$$I(q_m) - I(\hat{q}_m) > \frac{d}{2}.$$

In consequence,

$$\gamma^+ = \lim_{m \to \infty} I(q_m) \geq \liminf_{m \to \infty} I(\hat{q}_m) + \frac{d}{2} \geq \gamma^+ + \frac{d}{2},$$

a contradiction. Therefore Q is a classical solution of (1.1).

LEMMA 4.6. – If  $Q \in \Gamma^-$  then (1.1) has either a homoclinic solution  $p \in \Omega_b$  such that rot(p) > 0 or a heteroclinic solution  $Q_0 \in \Gamma^-$  such that  $rot(Q_0) < rot(Q)$ .

Proof. – By Lemma 4.4,

$$\gamma^+ = I(Q) + \omega_b^n,$$

where n = -rot(Q). Let  $\{p_m\}_{m \in \mathbb{N}} \subset \Omega_b^n$  be a sequence such that

$$\lim_{m\to\infty}I(p_m)=\omega_b^n.$$

By Proposition 2.4, going to a subsequence if necessary, there is  $p \in E$  such that

$$p_m \rightharpoonup p \text{ in } E \wedge p_m \rightarrow p \text{ in } L^{\infty}_{loc}(\mathbb{R}, \mathbb{R}^2).$$

From Proposition 2.6 it follows that  $p \in \Lambda$ . Applying Remark 3.1 we obtain

$$I(p) \leq \omega_b^n$$
.

Lemma 2.3 implies  $p(\pm \infty) \in \mathcal{M}$ .

By Remark 3.2, we can assume that for all  $m \in \mathbb{N}$ ,  $p_m(0) \in \partial B_{\varepsilon}(b)$  and  $p_m((-\infty,0)) \subset B_{\varepsilon}(b)$ . Then  $p((-\infty,0]) \subset \overline{B_{\varepsilon}(b)}$  and  $p(-\infty) = b$ .

We have to consider now two cases:  $p(\infty) = b$  or  $p(\infty) = a$ .

Case 1.  $-p(\infty) = b$ .

Put k = rot(p). We will prove that

$$I(p) = \inf\{I(q): q \in \Omega_b \land rot(q) = k\}.$$

Suppose, contrary to our claim, that there is  $\tilde{p} \in \Omega_b$  such that  $rot(\tilde{p}) = k$  and  $I(\tilde{p}) < I(p)$ . Set  $d = I(p) - I(\tilde{p})$  and take  $0 < \eta < \frac{d}{2}$ . By Lemma 4.1, there exists  $0 < \delta \le R$  such that

$$\int_{T}^{T+1} \left( \frac{1}{2} |y-x|^2 - V(l_{x,y}(t)) \right) dt < \frac{\eta}{2}$$

for all  $x, y \in B_{\delta}(b)$  and  $T \in \mathbb{R}$ . Choose T > 0 such that  $\tilde{p}([T, \infty)) \subset B_{\delta}(b)$ ,  $p([T, \infty)) \subset B_{\delta}(b)$  and

$$\int_{-\infty}^{T} \left(\frac{1}{2}|\dot{p}(t)|^2 - V(p(t))\right) dt > I(p) - \frac{\eta}{4}.$$

By the almost uniformly convergence of  $\{p_m\}_{m\in\mathbb{N}}$ , there is  $m_0\in\mathbb{N}$  such that  $p_m([T,T+1])\subset B_\delta(b)$  and  $rot(p_m|_{(-\infty,T]})=rot(p)$  for all  $m\geq m_0$ .

For each  $m \geq m_0$ , let  $\tilde{p}_m$  be given by

$$\tilde{p}_m(t) = \begin{cases} \tilde{p}(t) \text{ if } t \leq T, \\ (T+1-t)\tilde{p}(T) + (t-T)p_m(T+1) \text{ if } t \in [T,T+1], \\ p_m(t) \text{ if } t \geq T+1. \end{cases}$$

We have  $\tilde{p}_m(-\infty) = b = \tilde{p}_m(\infty)$  and  $rot(\tilde{p}_m) = rot(p_m)$ . From Remark 3.1 it follows that there is  $m_1 \in \mathbb{N}$  such that for all  $m \ge m_1$ ,

$$\int_{-\infty}^{T} \left( \frac{1}{2} |\dot{p}_m(t)|^2 - V(p_m(t)) \right) dt > \int_{-\infty}^{T} \left( \frac{1}{2} |\dot{p}(t)|^2 - V(p(t)) \right) dt - \frac{\eta}{4}.$$

From what has already been proved, we obtain

$$I(p_m) > I(\tilde{p}_m) + \frac{d}{2}$$

for  $m \in \mathbb{N}$  large enough. Hence

$$\omega_b^n = \lim_{m o \infty} I(p_m) \geq \liminf_{m o \infty} I( ilde{p}_m) + rac{d}{2} \geq \omega_b^n + rac{d}{2},$$

a contradiction. In consequence, p is a classical solution of (1.1).

We observe that k > 0. By contradiction, assume that  $k \le 0$ . Fix  $\eta > 0$  and choose  $\delta$ , T,  $m_0$  and  $m_1$  as above.

Define

$$v_m(t) = \begin{cases} b \text{ if } t \leq T, \\ (T+1-t)b + (t-T)p_m(t) \text{ if } t \in [T,T+1], \\ p_m(t) \text{ if } t \geq T+1 \end{cases}$$

for  $m \geq m_0$ . Since  $rot(p_m) \geq n$  and  $rot(p_{m|(-\infty,T+1)}) = k$ , we get

$$rot(v_m) = rot(p_{m|[T+1,\infty)}) \ge n - k \ge n.$$

What is more, for  $m \in \mathbb{N}$  large enough,

$$I(p_m) - I(v_m) > I(p) - \eta,$$

and so

$$\omega_b^n = \lim_{m o \infty} I(p_m) \geq \liminf_{m o \infty} I(v_m) + I(p) - \eta \geq \omega_b^n + I(p) - \eta.$$

Letting  $\eta \to 0^+$ , we receive

$$\omega_b^n \ge \omega_b^n + I(p) > \omega_b^n$$

a contradiction.

Case 2.  $-p(\infty) = a$ .

Set k = rot(p). We will prove that

$$I(p) = \inf\{I(q): q \in \Upsilon \land rot(q) = k\}.$$

On the contrary, assume that there exists  $\hat{p} \in \Upsilon$  such that  $rot(\hat{p}) = k$  and  $I(\hat{p}) < I(p)$ . Put  $d = I(p) - I(\hat{p})$ . Fix  $0 < \eta < \frac{d}{2}$ . By Lemma 4.1, there is  $0 < \delta \le R$  such that

$$\int_{T}^{T+1} \left( \frac{1}{2} |y - x|^2 - V(l_{x,y}(t)) \right) dt < \frac{\eta}{2}$$

for all  $x, y \in B_{\delta}(a)$  and  $T \in \mathbb{R}$ . Choose T > 0 such that  $\tilde{p}([T, \infty)) \subset B_{\delta}(a)$ ,  $p([T, \infty)) \subset B_{\delta}(a)$  and

$$\int_{-\infty}^{T} \left(\frac{1}{2}|\dot{p}(t)|^2 - V(p(t))\right) dt > I(p) - \frac{\eta}{4}.$$

There is  $m_0 \in \mathbb{N}$  such that  $p_m([T, T+1]) \subset B_{\delta}(a)$  and  $rot(p_m|_{(-\infty,T]}) = rot(p)$  for all  $m \geq m_0$ .

For each  $m \geq m_0$ , we define  $\hat{p}_m$  as follows:

$$\hat{p}_m(t) = \begin{cases} \hat{p}(t) \text{ if } t \leq T, \\ (T+1-t)\hat{p}(T) + (t-T)p_m(T+1) \text{ if } t \in [T,T+1], \\ p_m(t) \text{ if } t \geq T+1. \end{cases}$$

By definition,  $\hat{p}_m(-\infty) = b = \hat{p}_m(\infty)$  and  $rot(\hat{p}_m) = rot(p_m)$ . From Remark 3.1

we see that there is  $m_1 \in \mathbb{N}$  such that for all  $m \geq m_1$ ,

$$\int_{-\infty}^{T} \left( \frac{1}{2} |\dot{p}_m(t)|^2 - V(p_m(t)) \right) dt > \int_{-\infty}^{T} \left( \frac{1}{2} |\dot{p}(t)|^2 - V(p(t)) \right) dt - \frac{\eta}{4}.$$

Applying the above inequalities we immediately check that

$$I(p_m) > I(\hat{p}_m) + \frac{d}{2}.$$

Going to a limit we get

$$\omega_b^n = \lim_{m \to \infty} I(p_m) \ge \liminf_{m \to \infty} I(\hat{p}_m) + \frac{d}{2} \ge \omega_b^n + \frac{d}{2},$$

a contradiction. Hence p minimizes I on  $\{q \in \Upsilon: rot(q) = k\}$ .

We now observe that k > n. To this end, we first exclude the case k < 0. Set  $\bar{p}(t) = p(-t)$ . Of course,  $\bar{p} \in \Gamma^+$ . We obtain

$$I(\bar{p}) \ge \gamma^+ = I(Q) + \omega_h^n > \omega_h^n \ge I(p) = I(\bar{p}),$$

a contradiction.

We now exclude the case  $0 \le k \le n$ . For this purpose, take  $\eta > 0$  and choose  $\delta$ , T and  $m_0$  as above.

Let  $P_m$  for  $m \geq m_0$  be given by

$$P_m(t) = \left\{ egin{aligned} a & ext{if} & t \leq T, \\ (T+1-t)a + (t-T)p_m(T+1) & ext{if} & t \in [T,T+1], \\ p_m(t) & ext{if} & t \geq T+1. \end{aligned} 
ight.$$

Then  $P_m(-\infty)=a$ ,  $P_m(\infty)=b$  and  $rot(P_m)=rot(p_m|_{[T+1,\infty)})\geq n-k\geq 0$ , and so  $P_m\in \Gamma^+$ . Moreover,

$$I(P_m) \le \int_{T}^{T+1} \left(\frac{1}{2}|\dot{P}_m(t)|^2 + V(P_m(t))\right) dt + I(p_m) < \frac{\eta}{2} + I(p_m).$$

Hence  $\gamma^+ \leq \frac{\eta}{2} + \omega_b^n$ , and consequently,  $\gamma^+ \leq \omega_b^n$ , a contradiction. By the above, we have k > n.

Set 
$$Q_0(t) = p(-t)$$
 for  $t \in \mathbb{R}$ . Then  $Q_0 \in \Gamma^-$  and

$$rot(Q_0) = -rot(p) - 1 = -k - 1 < -n - 1 < -n = rot(Q).$$

Thus  $Q_0 \neq Q$ . Finally, by Remark 3.2, we get

$$\begin{split} I(Q_0) = & I(p) = \inf\{I(q) \colon q \in \Upsilon \ \land \ rot(q) = k\} \\ &= \inf\{I(q) \colon q \in \Gamma^- \ \land \ rot(q) = -k - 1\}. \end{split}$$

Therefore  $Q_0$  is a classical solution of (1.1).

Applying Proposition 2.8 we complete the proof of Theorem 1.4.

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