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Transformations in a three - space.

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Summary. - *The set of 3×3 non-singular matrices over the scalar field of real numbers is a group with respect to matrix multiplication. A number of its subgroups have interesting geometric significance.*

1. - Purposes of the problem: The purposes of this paper are to analyze certain eigenvectors and their corresponding eigenvalues of 3×3 matrices, which transform in a rectangular coordinatized E_3 the vector $v = (a_1, a_2, a_3)$ leaving its length invariant, and to survey the group properties of these matrices.

2. - Transformations: Consider in E_3 the vector v .

Let π be the set of transformations which permute the components of v allowing for change in sign. Then π leaves the origin 0 as a fixed point.

If we define an *augmented permutation matrix* as a monomial matrix [1] having non-zero entries 1 and -1 , then π will be the set of corresponding augmented permutation transformations. The $2^3 \cdot 3! = 48$ transformations of π are:

Identity	I	I
Inversion w.r.t. 0	$-I$	$(-1)^3 = I$
Reflections w.r.t. lines through 0	$A_i \quad i = 1, \dots, 9$	$A_i^2 = I$
Reflections w.r.t. planes through 0	$B_i \quad i = 1, \dots, 9$	$B_i^2 = I$
90° rotations about axes	$C_i \quad i = 1, \dots, 6$	$C_i^4 = I$
Reflection-rotations w.r.t. planes $X_j = 0$ and X_j axes	$D_i = B_j C_i = 1, \dots, 6$ $j \equiv i \pmod{3}$	$D_i^4 = I$
$(a_j)T_i = [\pm a_{\Phi(j)}], \Phi$ permutes subscripts $j = 1, 2, 3$	$T_i \quad i = 1, \dots, 8$ $i = 9, \dots, 16$	$T_i^3 = I$ $T_i^6 = I$

(*) Pervenuta alla Segreteria dell'U. M. I. il 7 dicembre 1963.

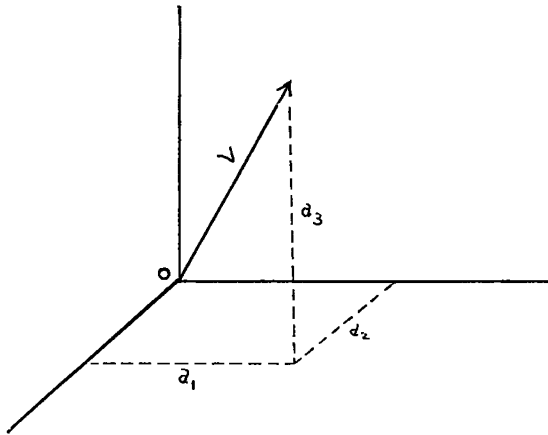
3. - *Eigenrays*: A given point (x_i) lies on an eigenray of some augmented permutation matrix A iff $\exists$ a complex scalar $\lambda \ni (x_i)' = (\lambda x_i) i = 1, 2, 3$ and $(x_i)A = (x_i)'$. This is tantamount to solving the secular equation $|A - \lambda I| = 0$ for λ .

Suppose:

$$C = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{pmatrix} \text{ represent the } 90^\circ \text{ counterclockwise rota-}$$

tion about the x_1 axis. The eigenvalues of C are found to be 1 and $\pm i$. The corresponding eigenvectors are $(c_1, 0, 0)$ and $(0, c_2, \mp c_2 i)$ where c_1 and c_2 are real scalars. It can then be concluded that the only real eigenray for C is the x_1 axis. Similarly, if

$$T = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & -1 & 0 \end{pmatrix} \text{ represents the mapping } (x_1, x_2, x_3) \rightarrow (x_2,$$



$-x_3, x_1)$, then the eigenrays corresponding to the eigenvalues -1 , $\lambda_1 = (1/2) + (\sqrt{3}/2)i$, and $\bar{\lambda}_1$ are $(c_1, -c_1, -c_1)$, $(c_1, \lambda_1 c_1, \bar{\lambda}_1 c_1)$ and $(c_1, \bar{\lambda}_1 c_1, \lambda_1 c_1)$ respectively: the first of these is the only real eigenray for T .

The secular equation resulting from an augmented permutation matrix yields three eigenvalues. The corresponding real eigen-

vectors generate a subspace of E_3 . In general, a line of reflection has eigenvalue 1 and all orthogonal lines have eigenvalue -1 ; rays lying in a plane of reflection have eigenvalue 1 and orthogonal rays eigenvalue -1 ; the axis of a rotation has an eigenvalue 1, all other eigenrays being imaginary; a reflection-rotation mapping has its line of rotation as an eigenray with eigenvalue -1 ; a transformation of the form $(a_i) \rightarrow (\pm a_{\Phi(i)})$ where one or three of the signs are $+$ has eigenvalue 1 and where none or two of the signs are $+$ has eigenvalue -1 .

4. - *Group Structure*: The set M of $48 = 2^4 \cdot 3$ augmented permutation matrices is a group generated by C and T above with defining relations.

$C^4 = T^6 = I$	$C^3 T^4 = T^2 C$	$CT^2 = T^4 C^2$
$CT^5 = TC^3$	$T^3 = -I$	$C^3 T = T^3 C$

Let $\|m_{ij}\| \in M$. Denote the k^{th} Sylow p -subgroup of M by $S_k(p)$. Then $M \supset S_k(2)$ and $S_1(3)$, $k = 1, 2, 3$ and $1 = 1, \dots, 4$. Each of the 16 $m_{ij} \in S_k(2)$ for fixed k_0 has an entry $m_{ii} \neq 0$. $\bigcap_{k=1}^3 S_k(2)$ is a self-conjugate subgroup of order $8 \ni \forall i, m_{ii} \neq 0$. $\forall 1, S_1(3) \subset Z_1(3)$ where $Z(n)$ is a cyclic group of order n . $\bigcup_{i=1}^4 S_1(3) = [T_i : i = 1, \dots, 8]$. $\bigcup_{i=1}^4 Z_1(6) = [T_i : i = 9, \dots, 16]$. $\cong 6 Z_1(4)s$.

Any two matrices of order 3 and 4 in M generate a subgroup of order 24. An interesting exploration would be the extension of this topic to E_n where the number of augmented permutation matrices is $2^n \cdot n!$

REFERENCES

- [1] BIRKHOFF and MACLANE *A Survey of Modern Algebra*, New York, 1957.
- [2] V. ROJANSKY, *Introductory Quantum Mechanics* New York, 1946.